

## MATH 20C Lecture 2 - Monday, September 27, 2010

### Observations

1. Two vectors pointing in the same direction are scalar multiples of each other.
2. The sum of three head-to-tail vectors in a triangle is 0.

### Lines in space

Polled the students about what kind of object is described by the equation  $x + 2y = 5$  in the plane. Most got it right (a line). How about the equation  $x + 2y + 3z = 7$  in space? It's a plane (about half of the students answered correctly, the other half thought it was a line).

So need some other way to think about lines in space. Think of it as the trajectory of a moving point. Express lines by a parametric equations.

**In coordinates.** For instance, the line through  $Q_0 = (1, 2, 2)$  and  $Q_1 = (1, 3, 1)$ : moving point  $Q(t) = (x, y, z)$  starts at  $Q_0$  at  $t = 0$ , moves at constant speed along line, reaches  $Q_1$  at  $t = 1$ . Its "velocity" is  $\vec{v} = \overrightarrow{Q_0Q_1}$ , so  $\overrightarrow{Q_0Q(t)} = t\overrightarrow{Q_0Q_1}$ . In our example we get  $\langle x + 1, y - 2, z - 2 \rangle = t\langle 2, 1, -3 \rangle$ , i.e.

$$\begin{cases} x(t) &= -1 + 2t \\ y(t) &= 2 + t \\ z(t) &= 2 - 3t \end{cases}$$

**In vector form.** The line through a point  $P$  in the direction given by some vector  $\vec{v}$  is given by

$$\vec{r}(t) = \overrightarrow{OP} + t\vec{v}$$

where  $\vec{r}(t)$  is the position vector of the point  $Q(t)$  on the line. Did example with  $P = (0, 1, 1)$  and  $v = \langle 0, 5, -1 \rangle$ . (Not sure I remember the exact numbers, I had made it up on the spot in class.)

### Dot product

**Definition**  $\vec{A} \cdot \vec{B} = a_1b_1 + a_2b_2 + a_3b_3 + \dots$  (a scalar, not a vector)

**Geometrically**  $\vec{A} \cdot \vec{B} = |\vec{A}||\vec{B}|\cos\theta$ , where  $\theta$  is the angle between the two vectors.

Explained the result as follows. First,  $\vec{A} \cdot \vec{A} = |\vec{A}|^2 \cos 0 = |\vec{A}|^2$  is consistent with the definition. Next, consider a triangle with sides  $\vec{A}, \vec{B}$  and  $\vec{C} = \vec{A} - \vec{B}$ . Then the law of cosines gives  $|\vec{C}|^2 = |\vec{A}|^2 + |\vec{B}|^2 - 2|\vec{A}||\vec{B}|\cos\theta$ . On the other hand, we get

$$|\vec{C}|^2 = \vec{C} \cdot \vec{C} = (\vec{A} - \vec{B}) \cdot (\vec{A} - \vec{B}) = |\vec{A}|^2 + |\vec{B}|^2 - 2\vec{A} \cdot \vec{B}.$$

Hence the geometric interpretation is a vector formulation of the law of cosines.

## MATH 20C Lecture 3 - Wednesday, September 29, 2010

Recall that  $\vec{A} \cdot \vec{B} = a_1b_1 + a_2b_2 + a_3b_3 + \dots = |\vec{A}||\vec{B}|\cos\theta$ .

## Today: applications of the dot product

1. **Computing lengths and angles (especially angles):**  $\cos \theta = \frac{\vec{A} \cdot \vec{B}}{|\vec{A}| |\vec{B}|}$ .

For instance, in the triangle in space with vertices at  $P = (1, 0, 0)$ ,  $Q = (0, 1, 0)$ ,  $R = (0, 0, 2)$ , the angle  $\theta$  at  $P$ :

$$\cos \theta = \frac{\overrightarrow{PQ} \cdot \overrightarrow{PR}}{|\overrightarrow{PQ}| |\overrightarrow{PR}|} = \frac{\langle -1, 1, 0 \rangle \cdot \langle -1, 0, 2 \rangle}{\sqrt{(-1)^2 + 1^2 + 0^2} \sqrt{(-1)^2 + 0^2 + 2^2}} = \frac{1}{\sqrt{10}}, \quad \theta \approx 71.5^\circ.$$

2. **Relative direction of two vectors**

$$\text{sign}(\vec{A} \cdot \vec{B}) = \begin{cases} > 0 & , \text{ if } \theta < 90^\circ (\text{acute angle, the two vectors point more or less in} \\ & \text{the same direction)} \\ = 0 & , \text{ if } \theta = 90^\circ \Leftrightarrow \vec{A} \perp \vec{B} \\ < 0 & , \text{ if } \theta > 90^\circ (\text{obtuse angle, vectors point away from each other}) \end{cases}$$

3. **Detecting orthogonality:** it's worth emphasizing that  $\vec{A} \perp \vec{B} = 0 \Leftrightarrow \vec{A} \cdot \vec{B} = 0$ .
4. **Finding the component of a vector in a given direction** If  $\vec{u}$  is a unit vector, the component of a vector  $\vec{A}$  in the direction of  $\vec{u}$  has length  $|\vec{A}| \cos \theta = |\vec{A}| |\vec{u}| \cos \theta = \vec{A} \cdot \vec{u}$  ( $\theta$  = the angle between the two vectors). The component itself is a vector called the *projection* of  $\vec{A}$  in the direction of  $\vec{u}$ , namely the vector

$$\vec{A}_{\parallel} = \mathbf{proj}_{\vec{u}}(\vec{A}) = (\vec{A} \cdot \vec{u})\vec{u}.$$

The component of  $\vec{A}$  in the direction perpendicular to  $\vec{u}$  is  $\vec{A}_{\perp} = \vec{A} - \vec{A}_{\parallel}$ , so

$$\vec{A} = \vec{A}_{\parallel} + \vec{A}_{\perp}.$$

*Example:* Find the component of  $\vec{A} = \langle 1, 2, 3 \rangle$  in the direction of the vector  $\vec{v} = \langle 1, 1, 0 \rangle$ .

**Step 1** Find the unit vector in the direction of  $\vec{v}$ :

$$\vec{u} = \frac{\vec{v}}{|\vec{v}|} = \frac{\langle 1, 1, 0 \rangle}{\sqrt{2}} = \left\langle \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0 \right\rangle.$$

**Step 2** Find the length of the component:

$$|\vec{A}_{\parallel}| = \vec{A} \cdot \vec{u} = \frac{1}{\sqrt{2}} + \frac{2}{\sqrt{2}} = \frac{3}{\sqrt{2}}$$

**Step 3** Multiply the results from step 1 and step 2:

$$\mathbf{proj}_{\vec{v}}(\vec{A}) = \frac{3}{\sqrt{2}} \left\langle \frac{1}{\sqrt{2}}, \frac{1}{\sqrt{2}}, 0 \right\rangle = \left\langle \frac{3}{2}, \frac{3}{2}, 0 \right\rangle.$$

*Application:* object moving on a frictionless inclined ramp. The physically important quantities are the components of the weight  $\vec{F}$  of object (pointing downward) in the direction of the ramp (causes the object to move) and the direction perpendicular to the ramp (creates counter-reaction and keeps the object on the ramp).

## 5. Planes

The plane  $x + 2y + 3z = 0$  consists of the points  $P = (x, y, z)$  with the property that  $\vec{A} \cdot \vec{OP} = x + 2y + 3z = 0$ , where  $\vec{A} = \langle 1, 2, 3 \rangle$ . This is the same as saying that  $\vec{A} \perp \vec{OP}$ .

### Area

We can decompose the area of a polygon in the plane into a sum of areas of triangles. The area of the triangle with sides  $\vec{A}$  and  $\vec{B}$  is  $\frac{1}{2} \text{base} \times \text{height} = \frac{1}{2} |\vec{A}| |\vec{B}| \sin \theta = (\frac{1}{2} \text{area of the parallelogram})$ .

So we need to compute  $\sin \theta$ . We know how to compute  $\cos \theta$ . Could do  $\sin^2 \theta + \cos^2 \theta = 1$ , but get ugly formula. Instead reduce to complementary angle  $\theta' = \frac{\pi}{2} - \theta$  by considering  $\vec{A}' = \vec{A}$  rotated by  $90^\circ = \frac{\pi}{2}$  counterclockwise (drew a picture).

Then, the area of the parallelogram with sides  $\vec{A}, \vec{B}$  is  $|\vec{A}| |\vec{B}| \sin \theta = |\vec{A}'| |\vec{B}| \cos \theta' = \vec{A}' \cdot \vec{B}$

## MATH 20C Lecture 4 - Friday, October 1, 2010

Continued from last time: If  $\vec{A} = \langle a_1, a_2 \rangle$  and  $\vec{A}' = \vec{A}$  rotated by  $90^\circ = \frac{\pi}{2}$  counterclockwise, what are the coordinates of  $\vec{A}'$ ? (showed slide, multiple choice).

Answer:  $\langle -a_2, a_1 \rangle$  (most students got it right).

So area of the parallelogram with sides  $\vec{A}, \vec{B}$  is  $\vec{A}' \cdot \vec{B} = \langle -a_2, a_1 \rangle \cdot \langle b_1, b_2 \rangle = a_1 b_2 - a_2 b_1$ .

### Determinants in the plane

**Definition:** The determinant of vectors  $\vec{A}, \vec{B}$  is  $\det \begin{pmatrix} \vec{A} \\ \vec{B} \end{pmatrix} = \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} = a_1 b_2 - a_2 b_1$ .

*Geometrically:*  $\det \begin{pmatrix} \vec{A} \\ \vec{B} \end{pmatrix} = \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} = \pm \text{area of the parallelogram}$ . (Area is positive, determinant might be negative, so take absolute value.)

### Determinants in space

**Definition:** The determinant of vectors  $\vec{A}, \vec{B}, \vec{C}$  is

$$\det \begin{pmatrix} \vec{A} \\ \vec{B} \\ \vec{C} \end{pmatrix} = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix} = a_1 \begin{vmatrix} b_2 & b_3 \\ c_2 & c_3 \end{vmatrix} - a_2 \begin{vmatrix} b_1 & b_3 \\ c_1 & c_3 \end{vmatrix} + a_3 \begin{vmatrix} b_1 & b_2 \\ c_1 & c_2 \end{vmatrix}.$$

*Geometrically:*  $\det \begin{pmatrix} \vec{A} \\ \vec{B} \\ \vec{C} \end{pmatrix} = \pm \text{the area of the parallelepiped with sides } \vec{A}, \vec{B}, \vec{C}$ .

### Cross-product

Is defined only for 2 vectors in space. Gives a vector (not a scalar, like dot product).

**Definition:**  $\vec{A} \times \vec{B} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} \hat{i} - \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} \hat{j} + \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix} \hat{k}$

(the  $3 \times 3$  determinant is a *symbolic notation*, the actual formula is the expansion).

*Geometrically:*  $\vec{A} \times \vec{B}$  is a vector with

- length:  $|\vec{A} \times \vec{B}| = \text{area of the parallelogram with sides } \vec{A}, \vec{B}$ ;
- direction: perpendicular on the plane containing  $\vec{A}, \vec{B}$  and pointing in the direction given by the right hand rule.

**Right hand rule:**

1. extend right hand in direction of  $\vec{A}$
2. curl fingers towards direction of  $\vec{B}$
3. thumb points in same direction as  $\vec{A} \times \vec{B}$

*Question* Compute  $\hat{i} \times \hat{j} = ?$  (multiple choice) Answer:  $\hat{k}$  (most got it right). Checked both by picture and formula.

Another example:  $\vec{A} = \langle 5, 2, -7 \rangle$ ,  $\vec{B} = \langle 3, 0, 1 \rangle$ . Then

$$\vec{A} \times \vec{B} = \begin{vmatrix} 2 & -7 \\ 0 & 1 \end{vmatrix} \hat{i} - \begin{vmatrix} 5 & -7 \\ 3 & 1 \end{vmatrix} \hat{j} + \begin{vmatrix} 5 & 2 \\ 3 & 0 \end{vmatrix} \hat{k} = 2\hat{i} - 26\hat{j} - 6\hat{k} = \langle 2, -26, -6 \rangle.$$

(numbers might be slightly different from the ones in class).

**Properties** of the cross product:

1.  $\vec{B} \times \vec{A} = -\vec{A} \times \vec{B}$
2.  $(2\vec{A}) \times (3\vec{B}) = 6(\vec{A} \times \vec{B})$
3.  $\vec{A} \times (\vec{B} + \vec{C}) = \vec{A} \times \vec{B} + \vec{A} \times \vec{C}$
4.  $\vec{A} \times \vec{A} = 0$