UNIPOTENT FLOWS AND ISOTROPIC QUADRATIC FORMS IN POSITIVE CHARACTERISTIC

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ABSTRACT. The analogous statement to Oppenheim conjecture over a local field of positive characteristic is proved. The dynamical argument is most involved in the case of characteristic 3.

1. Introduction

Let Q be a real non-degenerate indefinite quadratic form in n variables. Further assume Q is not proportional to a form with rational coefficients. It was conjectured by Oppenheim in [O31] that if $n \geq 5$ then for any $\varepsilon > 0$ there is $x \in \mathbb{Z}^n - \{0\}$ such that $|Q(x)| < \varepsilon$. Later on in 1946 Davenport stated the conjecture for $n \geq 3$, see [DH46]. However the conjecture even in the case $n \geq 3$ is usually referred to as Oppenheim conjecture. Note that if the conjecture is proved for n_0 then it holds for $n > n_0$. Hence it is enough to show this for n = 3. Note also that the conclusion of the theorem is false for n = 2. Using methods of analytic number theory the aforementioned conjecture was verified for $n \geq 21$ and also for diagonal forms in five variables, see [DH46, DR59].

The Oppenheim conjecture in its full generality was finally settled affirmatively by G. A. Margulis in [Mar86]. Margulis actually proved a reformulation of this conjecture, in terms of closure of orbits of certain subgroup of $SL_3(\mathbb{R})$ on the space of unimodular lattices. This reformulation (as is well-known) is due to M. S. Raghunathan and indeed is a special case of Raghunathan's conjecture on the closure of orbits of unipotent groups. S. G. Dani and G. A. Margulis utilized and generalized ideas in Margulis's proof of Oppenheim conjecture to get partial result in the direction of Raghunathan's conjecture, see [DM89, DM90]. Raghunathan's orbit closure conjecture was proved by M. Ratner in a series of path breaking papers. M. Ratner proved Raghunathan's measure rigidity conjecture conjecture (which apparently was first formulated by S. G. Dani) and derived the orbit closure from that, see [R90a, R90a, R91, R92].

Both measure rigidity conjecture and the Oppenheim conjecture can be formulated over other local fields as well. Indeed A. Borel and G. Prasad in [BP92], following the same strategy as in Margulis's proof of Oppenheim conjecture, proved the analogous statement in the S-arithmetic setting. The measure rigidity and orbit closure in the case of product of real and p-adic algebraic groups were also proved by G. A. Margulis and G. Tomanov [MT94] and independently by M. Ratner [R95].

In this paper we prove the analogous statement to Oppenheim conjecture in positive characteristic case. More precisely let K be a global function field of characteristic

 $\mathfrak{p} \neq 2$. Let ν be a place of K and let \mathscr{O}_{ν} be the ring of ν -integers in K. Let $K_{\nu} = \mathbb{F}_{\mathfrak{q}}((\theta^{-1}))$, where \mathfrak{q} is a power of \mathfrak{p} . Let $\mathfrak{o} = \mathbb{F}_{\mathfrak{q}}[[\theta^{-1}]]$ be the valuation ring of K_{ν} . We have

Theorem 1.1. Let Q be a non-degenerate isotropic quadratic form over K_{ν} in $n \geq 3$ variables and assume that Q is not a scalar multiple of a form whose coefficients are in K. Then for any $\varepsilon > 0$ there exists $\mathbf{v} \in \mathcal{O}_{\nu}^{n} - \{0\}$ such that $|Q(\mathbf{v})| < \varepsilon$.

If the Theorem 1.1 holds for n_0 then it holds for $n \ge n_0$ so it is enough to show this for n=3. Note also that the conclusion of the theorem is false for n=2. Our proof follows closely the same stream line as Margulis's original proof of the Oppenheim conjecture. There are several technical difficulties which occur in carrying out the proof from characteristic zero to our setting which are dealt with in the sequel. The main difficulty however occurs when $\operatorname{Char}(K)=3$. It was communicated to us by K. Mallahi Karai [M06] that he has a proof in the case $\operatorname{Char} K>3$.

In section 2 we state a theorem about the closure of orbits of certain groups which is equivalent to Theorem 1.1. The rest of the paper then is devoted to the proof of Theorem 2.1. We will recall some general properties from topological dynamics in section 3. In section 4 we will use the polynomial like behavior of the action of unipotent groups on the space of lattices to construct a "polynomial like" map. This construction is essential to our proof. Indeed this kind of constructions was used in Margulis's proof of Oppenheim conjecture and is a cornerstone in Ratner's proof of measure rigidity conjecture, see also [R83]. The proof of Theorem 2.1 then will be completed in section 5.

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2. Theorem 1.1 and flows on homogeneous spaces

We observed earlier that we need to prove the theorem in the case n=3. Let $G=\mathrm{SL}_3(\mathbb{K}_\nu)$ and $\Gamma=\mathrm{SL}_3(\mathscr{O}_\nu)$. We let Ω be the space of free \mathscr{O}_ν -modules of determinant one in K^3_ν . The space G/Γ can be naturally identified with Ω in the usual way. For any $y=g\Gamma\in\Omega=G/\Gamma$ we let $G_y=\{h\in G|\ hy=y\}=g\Gamma g^{-1}$ be the stabilizer of y in G. For any quadratic form Q on K^3_ν , let H_Q be the subgroup of G consisting of elements which preserve the form Q. We have

Theorem 2.1. If $x \in G/\Gamma$ such that $\overline{H_Qx}$ is compact then $H_Qx = \overline{H_Qx}$.

The reduction of Theorem 1.1 to Theorem 2.1 is well-known. This was first observed by M. S. Raghunathan. We will reproduce the argument in our case.

First recall that for any closed subgroup $P \subset G$ and any $y \in G/\Gamma$. The quotient space $P/P \cap G_y$ and the orbit Py are homeomorphic if Py is closed. Consequently we have $P/P \cap G_y$ is compact if and only if Py is compact.

Let Q be an indefinite non-degenerate quadratic form in 3 variables as in the statement of Theorem 1.1. Assume that the assertion of Theorem 1.1 does not hold. Thus there exits $\varepsilon > 0$ such that $|Q(\mathbf{v})| > \varepsilon$ for any $\mathbf{v} \in \mathcal{O}_{\nu}^3 - \{0\}$. Mahler's compactness criterion now implies that $H_Q \mathcal{O}_{\nu}^3$ is relatively compact in Ω i.e. $H_Q \Gamma$ is

relatively compact in G/Γ . By Theorem 2.1 above we have $H_Q\Gamma/\Gamma$ is compact hence $H_Q/H_Q\cap\Gamma$ is compact. Consequently $H_Q\cap\Gamma$ is a lattice in H_Q . This in view of Borel's density Theorem implies that $H_Q\cap\Gamma$ is Zariski dense in H_Q . Thus H_Q is defined over K, see [B91, Chapter AG]. Hence Q is a scalar multiple of a form with coefficients in a purely inseparable extension of K. However Q has coefficients in K_{ν} thus Q is scalar multiple of a form with coefficients in K which is a contradiction.

3. Minimal sets

Let G be an arbitrary second countable locally compact group and let Ω be a homogeneous space for G. For any closed subgroup $F \subset G$ let $N_G(F)$ denote the normalizer of F in G.

Definition 3.1. Let F be a closed subgroup of G and Y be a closed F-invariant subset of Ω . The subset Y is called F-minimal if it does not contain any proper closed F-invariant subset i.e. Fy is dense in Y for any $y \in Y$.

It is a consequence of Zorn's lemma that any compact F-invariant subset of Ω contains a compact F-minimal subset. Let F be a closed subgroup of G and Y a closed F-minimal subset of Ω . Note that if $g \in N_G(F)$ such that $gY \cap Y \neq \emptyset$ then gY = Y.

Lemma 3.2. Let $F \subset P$ and $F \subset P'$ be closed subgroups of G and let Y and Y' be closed subsets of Ω and let $M \subset G$. Suppose that

- (a) PY = Y and P'Y' = Y',
- (b) $mY \cap Y' \neq \emptyset$ for any $m \in M$,
- (c) Y is a compact F-minimal subset.

Then $hY \subset Y'$ for any $h \in N_G(F) \cap \overline{P'MP}$.

Proof. Define $S = \{g \in G | gY \cap Y' \neq \emptyset\}$. Since Y and Y' are compact S is a closed subset of G. Note also that $P'MP \subset S$. Thus we have $\overline{P'MP} \subset S$. Let $h \in N_G(F) \cap \overline{P'MP}$ then we have hy = y' for some $y \in Y$ and $y' \in Y'$. Since Fh = hF we have $Fhy = hFy \subset Y'$. We now take the closure and use the fact that Y is F-minimal and get $hY \subset Y'$.

Corollary 3.3. If P = P' and Y = Y' in the Lemma 3.2, then for every $h \in N_G(F) \cap \overline{PMP}$ we have hY = Y.

The following is a standard fact from topological dynamics about minimal sets. We recall the proof for the sake of completeness.

Lemma 3.4. Let F be a closed subgroup of G and let $y \in \Omega$ be such that \overline{Fy} is a compact F-minimal subset of Ω but $F/F \cap G_y$ is not compact (i.e. Fy is not compact). Then the closure of the subset $\{g \in G - F : gy \in Fy\}$ contains the identity.

Proof. We argue by contradiction. Assume the conclusion of the lemma does not hold. So we can find a relatively compact neighborhood of the identity, \mathcal{U} say, such

that $Fy \cap \mathcal{U}y = (F \cap \mathcal{U})y$. Let us represent $F = \bigcup_{n \geq 1} K_n$ where $K_n \subset K_{n+1}$ are compact subsets of F. Recall that Fy is not compact thus for any $n \geq 1$ we can find $z_n \in Fy$ such that $K_n z_n \cap (F \cap \mathcal{U})y = \emptyset$. Since $K_n z_n \subset Fy$ we have $K_n z_n \cap \mathcal{U}y = \emptyset$. Let $\Psi = \bigcup_n K_n z_n$. The aforementioned properties imply that the closure of Ψ does not contain y. However if we replace $\{z_n\}$ by a subsequence, if necessary, we may and will assume $z_n \to z \in Y$. Note now that Y is F-minimal and that $Fz \subset \overline{\Psi}$ thus $y \in \overline{\Psi}$, which is a contradiction.

4. Some preliminary statements

For any $\mu \in K_{\nu} - \{0\}$ let us denote by H_{μ} the subgroup of G consisting of elements which preserve the form $Q_{\mu}(x) = 2x_1x_3 - \mu x_2^2$. It is easy to see that for any indefinite non-degenerate quadratic form Q in 3 variables there exists $g_Q \in G$ and $\mu_Q \in K_{\nu} - \{0\}$ such that $H_{\mu_Q} = g_Q H_Q g_Q^{-1}$. Hence it suffices to prove Theorem 2.1 for H_{μ} . We denote $H = H_1$. We prove Theorem 2.1 in the case $\mu = 1$, the proof for arbitrary μ is identical. Let us fix some notations to be used throughout the paper. As above let $H = H_1$ and define

$$d(t) = \begin{pmatrix} t & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & t^{-1} \end{pmatrix}, \quad v_1(t) = \begin{pmatrix} 1 & t & t^2/2 \\ 0 & 1 & t \\ 0 & 0 & 1 \end{pmatrix}$$
$$v_2(t) = \begin{pmatrix} 1 & 0 & t \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Let $D(t) = \{d(t): t \in K_{\nu}^{\times}\}, V_1 = \{v_1(t): t \in K_{\nu}\}$ and $V_2 = \{v_2(t): t \in K_{\nu}\}$, more generally if for any subset $A \subset K_n u$ we let $V_2(A) = \{v_2(t): t \in A\}$. If $f: K_{\nu} \to K_{\nu}$ is a polynomial map we let $V_2(f) = V_2(\operatorname{Im}(f))$. Let

$$V = V_1 \cdot V_2 = \left\{ \begin{pmatrix} 1 & a & b \\ 0 & 1 & a \\ 0 & 0 & 1 \end{pmatrix} : a, b \in K_{\nu} \right\}$$

Note that DV is the normalizer of V_1 in G and that DV_1 is the intersection of H with the group of upper triangular matrices. Let W (resp. W^-) be the set of strictly upper triangular (resp. lower triangular) matrices in G, and also let B (resp. B^-) be the set of upper triangular (resp. lower triangular) matrices in G. For any subgroup A of W which is normalized by $d(\theta^3)$ we let

$$A_k = d(\theta^3)^k (W(\mathfrak{o}) \cap A) d(\theta^3)^{-k}$$

The full diagonal group will be denoted by T. We let $L = B^-W_1$ where

$$W_1 = \left\{ \begin{pmatrix} 1 & 0 & a \\ 0 & 1 & b \\ 0 & 0 & 1 \end{pmatrix} : a, b \in K_{\nu} \right\}$$

this is a rational cross-section for V_1 in G. Let V_1^- , W_1^- , V_2^- denote the transpose of V_1 , W_1 , V_2 respectively.

Let $x \in \Omega$ be such that \overline{Hx} is compact and $Hx \neq \overline{Hx}$. Fix once and for all a compact H-minimal subset X of \overline{Hx} and let $Y \subset X$ be a compact V_1 -minimal subset.

Lemma 4.1. Let $y \in \Omega$ be such that Dy is relatively compact in Ω . Then $W \cap G_y = \{e\}$, therefore $U/U \cap G_y$ is not compact for any non-compact subgroup U of W.

Proof. This is a consequence of the following two facts.

- (i) $W = \{ g \in G | d(t)g d(t)^{-1} \to e \text{ as } t \to 0 \}$
- (ii) If $\gamma \in G_y$, $\gamma \neq e$ and $\{d_n\}$ is a sequence in G such that $d_n \gamma d_n^{-1} \to e$ then the set $\{d_n y\}$ is not relatively compact in Ω .

Lemma 4.1 has he following consequence which is a supped up version of Lemma 3.4 in the form which needed for our construction in Lemma 4.4.

Lemma 4.2. The closure of $\{g \in G - DV | gY \cap Y \neq \emptyset\}$ contains e.

Proof. Note first that since $DV = N_G(V_1)$ and Y is V_1 -minimal we have gY = Y if $g \in DV$ and $gY \cap Y \neq \emptyset$. Thus we have

$$\mathfrak{S} = \{ g \in DV | gY \cap Y \neq \emptyset \} = \{ g \in DV | gY = Y \}$$

Which says \mathfrak{S} is a closed subgroup of G and indeed $V_1 \subset \mathfrak{S}$. Assume now that the contrary to the lemma holds. Since Y is \mathfrak{S} -minimal and compact, in view of Lemma 3.4 we get $\mathfrak{S}/\mathfrak{S} \cap G_y$ is compact. In particular $\Lambda = \mathfrak{S} \cap G_y$ is a lattice in \mathfrak{S} . Since $V_1 \subset \mathfrak{S}$ and V_1 is normal in $DV = (DV_2)V_1$ we may write $\mathfrak{S} = (\mathfrak{S} \cap DV_2)V_1$. Let $\mathfrak{S}_2 = \mathfrak{S} \cap DV_2$. We claim that $\pi(\Lambda)$ is discrete where $\pi: \mathfrak{S} \to \mathfrak{S}/V_1$ is the natural projection. Let us assume the claim for a second. Then we get ΛV_1 is a closed subgroup and since Λ is a co-compact lattice in \mathfrak{S} this implies that $\Lambda \cap V_1$ is a lattice in V_1 . Note however that $Dy \subset X$ is relatively compact hence in view of the Lemma 4.1 this is a contradiction and the lemma will be concluded. We now show the claim. First note that $(DV)(\mathfrak{o})$ has a neighborhood of identity which is a pro- \mathfrak{p} group. We call this neighborhood $(DV)_{\mathfrak{p}}$ and let $\mathfrak{S}_{2\mathfrak{p}} = \mathfrak{S}_2 \cap (DV)_{\mathfrak{p}}$. We will show that $\pi(\Lambda) \cap \pi(\mathfrak{S}_{2\mathfrak{p}}) = \{e\}$. Assume the contrary then there exists some $\lambda \in \Lambda$ such that $e \neq \pi(\lambda) \in \pi(\mathfrak{S}_{2\mathfrak{p}})$. Note that V_1 has a filtration, say $\{V_{1n}\}$, by pro- \mathfrak{p} groups which are all normalized by $\mathfrak{S}_{2\mathfrak{p}}$. Hence $\lambda \in \mathfrak{S}_{2\mathfrak{p}}V_{1n}$ for some n. This is a pro-p group. The group generated by $\langle \lambda \rangle \subset \Lambda$ is a discrete subgroup of this pro-p-group which implies that it is a finite p-group. Write $\lambda = dv$, where $d \in D$ and $v \in V$. Note that in view of the Lemma 4.1 we have $\lambda \notin V$ thus $d = d(t) \neq e$.. Modding out by the normal subgroup V of DV this implies that d has order a power of \mathfrak{p} which implies d=e. This contradiction establishes the claim.

We will need a construction from [MT94], see also [Mar86] and [R90a, R83]. As was mentioned one of the main ingredients in the proof of Theorem 2.1 is the polynomial like behavior of the way two unipotent orbits diverge from each other. Since one needs to deal with quasi-affine spaces rather than affine spaces we don not quite get polynomials but rather certain rational maps which become polynomial if we embed our quasi-affine space into an affine space. The following definition, from [MT94], is the precise formulation.

Definition 4.3. (cf. [MT94, Definition 5.3])

(i) Let \mathbb{E} be a K_{ν} -algebraic group, F a K_{ν} -algebraic subgroup of $\mathbb{E}(K_{\nu})$ and \mathbb{M} a K_{ν} -algebraic variety. A K_{ν} -rational map $f: \mathbb{M}(K_{\nu}) \to \mathbb{E}(K_{\nu})$ is called

F-quasiregular if the map from $\mathbb{M}(K_{\nu})$ to \mathbb{V} given by $x \mapsto \rho(f(x)p)$ is K_{ν} regular for every K_{ν} -rational representation $\rho : \mathbb{E} \to \mathrm{GL}(\mathbb{V})$ and every point $p \in \mathbb{V}(K_{\nu})$ such that $\rho(F)p = p$.

- (ii) If $E = \mathbb{E}(K_{\nu})$ and $\mathcal{W} \subset E$ is a split unipotent subgroup then a map $\phi : \mathcal{W} \to E$ is called *strongly* \mathcal{W} -quasiregular if there exist
 - (a) a sequence $g_n \in E$ such that $g_n \to e$.
 - (b) a sequence $\{\alpha_n : \mathcal{W} \to \mathcal{W}\}\$ of K_{ν} -regular maps.
 - (c) a sequence $\{\beta_n : \mathcal{W} \to \mathcal{W}\}\$ of K_{ν} -rational maps.
 - (d) a Zariski open nonempty subset $\mathscr{X} \subset \mathscr{W}$

such that $\phi(u) = \lim_{n\to\infty} \alpha_n(u) g_n \beta_n(u)$ and the convergence is uniform on the compact subsets of $\mathscr X$

Note that if ϕ is strongly \mathcal{W} -quasiregular then it indeed is \mathcal{W} -quasiregular. Let $\rho: E \to \mathrm{GL}(\Phi)$ be a K_{ν} -rational representation and let $p \in \Phi$ be a \mathcal{W} -fixed vector. For any $u \in \mathcal{X}$ we have

$$\rho(\phi(u))p = \lim_{n \to \infty} \rho(\alpha_n(u)g_n)p.$$

Identify \mathscr{W} with an affine space, as we may, thanks to the fact \mathscr{W} is split. The sequence $\{\psi_n : \mathscr{W} \to \Phi, u \mapsto \rho(\alpha_n(u)g_n)p\}$ is a sequence of polynomial maps of bounded degree and also the family is uniformly bounded on compact sets so it converges to a polynomial map with coefficients in K_{ν} . This says ϕ is \mathscr{W} -quasiregular.

The following is an important application of the polynomial like behavior of the action of V_1 on Ω . Actually later on we will need it for some other subgroup which share similar features with V_1 i.e. split unipotent algebraic subgroups of G after change of the base field. The proof in the more general setting is the same as it is clear from the proof given here.

Lemma 4.4. Let $\{g_n\} \subset G - DV$ be such that $g_n \to e$. Then $N_G(V_1) \cap \overline{V_1\{g_n\}V_1}$ contains the image of a non-constant strongly V_1 -quasiregular map ϕ . Furthermore $Im(\phi) \not\subset KV_1$ for any compact subset $K \subset G$.

Proof. Let $\{g_n\} \subset G - DV$ be such that $g_n \to e$. We define the rational morphisms $\tilde{\phi}_n : V_1 \to L$ and $\omega_n : V_1 \to V_1$ to be the maps so that $v_1(t)g_n = \tilde{\phi}_n(t)\omega_n(t)$ holds for all $v_1(t)$ in a Zariski open dense subset of V_1 .

By Chevalley's Theorem there exits a K_{ν} -rational representation $\rho: G \to \mathrm{GL}(\Phi)$ and $g \in \Phi$ such that

$$V_1 = \{g \in G | \rho(g)q = q\}$$
 and $N_G(V_1) = \{g \in G | \rho(V_1)\rho(g)q = \rho(g)q\}$

Let $\mathscr{B}(v) \subset \rho(G)q$ be a bounded neighborhood of q in V. Since on $\{g_n\} \not\in N_G(V_1)$ we have; there exists a sequence of positive integers $\{r(n)\}$ with $r(n) \to \infty$ such that $V_{1r(n)}g_nq \not\subset \mathscr{B}(q)$ and $V_{1k}g_nq \subset \mathscr{B}(q)$ for all k < r(n), where

$$V_{1n} = \{v_1(t) \mid t \in K_{\nu} \text{ and } |t| < \mathfrak{q}^{3n}\}$$

For any $n \in \mathbb{N}$ let $\alpha_n : V_1 \to V_1$ be the conjugation by $d(\theta^3)^{r(n)}$. Define the K_{ν} -rational maps ϕ_n by $\phi_n = \tilde{\phi}_n \circ \alpha_n : V_1 \to L$. Let

$$\phi_n' = \rho_L \circ \phi_n : V_1 \to \Phi$$

We have $\phi'_n(t) = \alpha_n(v_1(t))g_nq$, thus $\phi'_n: V_1 \to \Phi$ is a K_{ν} -regular map whose degree is independent of n. This is to say $\{\phi'_n\}$ is a set of polynomial maps of bounded degree. Using the definition of ϕ'_n we also have $\{\phi'_n\}$ is a uniformly bounded family of polynomials. Thus passing to a subsequence, which we will still denote it by ϕ'_n , there is a polynomial map $\phi': V_1 \to \Phi$ such that

$$\phi'(t) = \lim_{n \to \infty} \phi'_n(t)$$
 for every $t \in K_{\nu}$

Note that $\phi'(e) = q$ as $g_n \to e$ and that ϕ' is non-constant since $g_n \notin N_G(V_1)$.

Recall that L is a rational cross-section for G/V_1 which contains e. Thus L gets mapped onto a Zariski open dense subset \mathscr{M} of Zariski closure of $\rho(G)q$ and that $q \in \mathscr{M}$. Hence we can define a K_{ν} -rational map $\phi: V_1 \to L$ by

$$\phi = \rho_L^{-1} \circ \phi'$$

The construction above gives $\phi(e) = e$ and ϕ is non-constant.

We now show; the map ϕ satisfies the conditions of the lemma i.e.

- (i) ϕ is strongly V_1 -quasiregular
- (ii) $\operatorname{Im}(\phi) \subset N_G(V_1)$.
- (iii) $\operatorname{Im}(\phi) \not\subset KV_1$ for any compact subset $K \subset G$.

Note that by above construction we have if $v_1(t) \in \phi'^{-1}(\mathcal{M})$ then

$$\phi(t) = \lim_{n \to \infty} \phi_n(t)$$

and the convergence above is uniform on the compact set of $\phi'^{-1}(\mathcal{M})$. We have

$$\phi_n(t) = \alpha_n(v_1(t))g_n\beta_n(t)$$
 where $\beta_n(t) = \omega_n(\alpha_n(v_1(t)))^{-1}$

Above says for $v_1(t) \in \phi'^{-1}(\mathcal{M})$ we can write

$$\phi(t) = \lim_{n \to \infty} \alpha_n(v_1(t)) g_n \beta_n(t),$$

this establishes (i).

To prove (ii) above recall that $N_G(V_1) = \{g \in G | V_1 \rho(g) q = \rho(g) q\}$. We remarked above that $\phi(t) = \lim_{n \to \infty} \alpha_n(v_1(t)) g_n \beta_n(t)$. Let $v_1(s) \in V_1$ be an arbitrary element we need to show $v_1(s) \rho(\phi(t)) q = \rho(\phi(t)) q$. Note that

$$\rho(v_1(s)\alpha_n(v_1(t))g_n)q = \rho(\alpha_n(\alpha_n^{-1}(v_1(s))t)g_n)q$$

The result is immediate now if we note that $\alpha_n^{-1}(v_1(s)) \to e$ as $n \to \infty$. This finishes the proof of (ii) and of the lemma.

To see (iii) note that $\phi = \rho_L^{-1} \circ \phi'$ and ϕ' is a non-constant (hence unbounded) polynomial map.

For later use we need to explicitly determine various polynomials which where constructed in Lemma 4.4. Let

(1)
$$g_n = \begin{pmatrix} a_{1n} & a_{2n} & a_{3n} \\ b_{1n} & b_{2n} & b_{3n} \\ c_{1n} & c_{2n} & c_{3n} \end{pmatrix}$$

Then we have

$$v_1(t)g_n = \begin{pmatrix} a_{1n} + b_{1n}t + c_{1n}\frac{t^2}{2} & a_{2n} + b_{2n}t + c_{2n}\frac{t^2}{2} & a_{3n} + b_{3n}t + c_{3n}\frac{t^2}{2} \\ b_{1n} + c_{1n}t & b_{2n} + c_{2n}t & b_{3n} + c_{3n}t \\ c_{1n} & c_{2n} & c_{3n} \end{pmatrix}$$

Write $\alpha_n(v_1(t))g_n\beta_n(t) = \sigma_n(t)\vartheta_n(t)$ where $\sigma_n: V_1 \to B^-$ and $\vartheta_n: V_1 \to W_1$ are K_{ν} -rational morphisms. That is

$$(2) \quad \sigma_n(t) = \begin{pmatrix} \sigma_{11}^n(t) & 0 & 0\\ \sigma_{21}^n(t) & \sigma_{22}^n(t) & 0\\ \sigma_{31}^n(t) & \sigma_{32}^n(t) & \sigma_{33}^n(t) \end{pmatrix} \text{ and } \vartheta_n(t) = \begin{pmatrix} 1 & 0 & \vartheta_{13}^n(t)\\ 0 & 1 & \vartheta_{23}^n(t)\\ 0 & 0 & 1 \end{pmatrix}$$

Note that our construction above says $\phi(t) \in L \cap N_G(V_1) = DV_2$ so all we need from above are the maps $\{\sigma_{11}^n(t)\}$ and $\{\vartheta_{13}^n(t)\}$ which are easily calculated. Let $\alpha_n(t) = \theta^{3r(n)}t$. Then

- $\begin{array}{ll} (\dagger) & \sigma_{11}^n(t) = a_{1n} + b_{1n}\alpha_n(t) + c_{1n}\frac{\alpha_n(t)^2}{2} = a_{1n} + b'_{1n}t + c''_{1n}\frac{t^2}{2} \\ (\dagger) & \vartheta_{13}^n(t) = \frac{2(v_1(\alpha_n(t))g_n)_{13}(v_1(\alpha_n(t))g_n)_{11} ((v_1(\alpha_n(t))g_n)_{12})^2}{2((v_1(\alpha_n(t))g_n)_{11})^2} = \frac{\vartheta_{0n}(t)}{(\sigma_{11}^n(t))^2}, \text{ where } \vartheta_{0n}(t) \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \end{array}$

Passing to the limit we have

(3)
$$\phi(t) = d(\sigma(t)) \ v_2(\vartheta_0(t)) = d(\sigma(t)) \ v_2\left(\frac{\vartheta(t)}{\sigma(t)^2}\right)$$

where $\sigma(t)$ is a polynomial of degree at most 2 and $\vartheta(t)$ is a polynomial of degree at most 4. Moreover $d(\sigma(0)) = v_2(\vartheta_0(0)) = e$.

In the sequel we need some more properties of the map constructed in Lemma 4.4. Let us fix some notation. It follows from standard facts in algebraic group theory, see [B91], that the product map defines an isomorphism between $W^- \times T \times W$ and a Zariski open dense subset of G which contains e. In particular there exists an open neighborhood of the identity in G such that for all g in that neighborhood

$$g = W^{-}(g)T(g)W(g) = V_{1}^{-}(g)W_{1}^{-}(g)T(g)W_{1}(g)V_{1}(g)$$

where $V_1^-(g) \in V_1^-$, $W_1^-(g) \in W_1^-$, $T(g) \in T$, $V_1(g) \in V_1$, $W_1(g) \in W_1$, $W^-(g) = V_1$ $V_1^-(g)W_1^-(g)$ and $W(g)=W_1(g)V_1(g)$. The following lemma follows from a more general result proved in [MT94, Proposition 6.7] in characteristic zero case. That proof works in our setting also however our particular case here allows a hands on proof. We give this proof here for the sake of completeness and refer to [MT94, Proposition 6.7 for a conceptual proof.

Lemma 4.5. Let $\{g_n\} \subset W_1^-B - DV$ be a sequence such that $g_n \to e$. Let ϕ be the V_1 -quasiregular map constructed in Lemma 4.4 using $\{g_n\}$. Then $\operatorname{Im}(\phi) \subset W$.

Proof. The proof of Lemma 4.4 implies that $\phi(t) = \lim_n \alpha_n(v_1(t)) g_n \beta_n(t)$ for all t such that $v_1(t) \in (\phi')^{-1}(\mathcal{M})$. The calculation following Lemma 4.4 gives $\phi(t) =$ $\lim_n \sigma_n(t)\vartheta_n(t)$ for all $v_1(t) \in (\phi')^{-1}(\mathscr{M})$ where σ_n and ϑ_n are as in (2). As was mentioned above we need only σ_{11}^n and ϑ_{13}^n . Our assumption, $g_n \in W_1^- B$, is to say that in (1) $b_{1n} = 0$ for all n. This using the above calculations implies that

 $\sigma_{11}^n(t) = a_{1n} + c_{1n}t^2/2$ and

(4)
$$\vartheta_{13}^{n}(t) = \frac{2(a_{1n} + c_{1n}\frac{t^{2}}{2})(a_{3n} + b_{3n}t + c_{3n}\frac{t^{2}}{2}) - (a_{2n} + b_{2n}t + c_{2n}\frac{t^{2}}{2})^{2}}{2(a_{1n} + c_{1n}\frac{t^{2}}{2})^{2}}$$

If we expand (4), we get: in the expression for the nominator the coefficient of t^3 is $b_{3n}c_{1n}-b_{2n}c_{2n}$ and the coefficient of t^4 is $(2c_{1n}c_{3n}-c_{2n}^2)/4$. Now $\sigma(t)$ is non-constant if and only if $\lim_n \theta^{3r(n)}c_{1n} \neq 0$. However this in view of the fact that $g_n \to e$ implies that either $\lim_n \theta^{3r(n)}(b_{3n}c_{1n}-b_{2n}c_{2n}) \neq 0$ or $\lim_n \theta^{3r(n)}(2c_{1n}c_{3n}-c_{2n}^2) \neq 0$. Either case implies that $\{\vartheta_{13}^n(\alpha_n(\alpha_n(t))\}$ diverges. This is a contradiction thus $\phi(t) \subset W$ for all t such that $v_1(t) \in (\phi')^{-1}(\mathscr{M})$. Since this is a Zariski dense subset of V_1 the lemma follows.

Let the notation and conventions be as before. Recall in particular that $x \in G/\Gamma$ such that \overline{Hx} is compact and $\overline{Hx} \neq Hx$. We fixed $X \subset \overline{Hx}$ an H-minimal subset and $Y \subset X$ a V_1 -minimal subset.

Proposition 4.6. At least one of the following holds

- (i) There exists a non-constant polynomial, $\sigma(t)$, and a polynomial of degree at most four, $\vartheta(t)$, such that $\phi(t)Y = Y$ where $\phi(t) = d(\sigma(t)) v_2\left(\frac{\vartheta(t)}{\sigma(t)^2}\right)$.
- (ii) $V_2 y \subset \overline{Hx}$ for some $y \in \overline{Hx}$.
- (iii) Y is $V_2(f)$ -invariant, where $f(t) = at^3$ for some $a \in K_{\nu} \{0\}$.

Proof. Using Lemma 4.2 above we can find $\{g_n\} \subset G - DV$ such that $g_n \to e$ and that $g_nY \cap Y \neq \emptyset$. Applying Lemma 3.3 with $P = F = V_1$, Y = Y and $M = \{g_n\}$ one has hY = Y for every $h \in N_G(V_1) \cap \overline{V_1MV_1}$. Note that we are in the situation of Lemma 4.4, using that lemma and the calculation after loc. cit. in particular (3) we have; there are polynomials $\sigma(t)$ of degree at most 2 and $\vartheta(t)$ of degree at most 4 such that $\phi(t)Y = Y$, where $\phi(t) = d(\sigma(t))$ $v_2\left(\frac{\vartheta(t)}{\sigma(t)^2}\right)$. We may assume $\sigma(t)$ is a constant polynomial else (i) above holds and there is nothing to show.

Thus we may and will assume that $\sigma(t) = \sigma(0) = 1$ for all $t \in K_{\nu}$ i.e. $\phi(t) = v_2(\vartheta(t))$. There are 3 possibilities for $\vartheta'(t)$, the derivative $\vartheta(t)$;

- (a) $\vartheta'(t) = 0$ for all $t \in K_{\nu}$. Note that $\vartheta(t)$ is a non-constant polynomial of degree at most 4 hence this can only happen if $\operatorname{Char} K = 3$ (recall that $\operatorname{Char} K \neq 2$). Since $\vartheta(0) = 0$ this says $\vartheta(t) = at^3$ for some nonzero $a \in K_{\nu}$, which means case (iii) of the proposition holds.
- (b) $\vartheta'(t)$ is a non-constant polynomial.
- (c) $\vartheta'(t)$ is constant but it is not zero. This in view of the same considerations as in (b) implies $\vartheta(t) = at^3 + bt$ where $a, b \in K_{\nu}$ and $b \neq 0$.

We will now show (ii) holds in either cases (b) and (c). The occurrence of these thanks to the inverse function Theorem implies that the image of ϑ contains some open set. Since $V_2(\vartheta(t))Y = Y$ the same holds true for the group generated by $\{v_2(\vartheta(t)): t \in K_{\nu}\}$. Thus we get that there exists some open neighborhood \mathfrak{o}' of the origin such that Y is invariant under $V_2(\mathfrak{o}')$. Let $z \in Y$. Since X is H-invariant and $V_2(\mathfrak{o}')z \in Y$ we have $d(\theta^3)^n V_2(\mathfrak{o}')z \subset X$ for any $n \in \mathbb{N}$. We have

$$d(\theta^3)^n V_2(\mathfrak{o}') z = d(\theta^3)^n V_2(\mathfrak{o}') d(\theta^3)^{-n} d(\theta^3)^n z = V_{2n} d(\theta^3)^n z$$

Let $z_n = d(\theta^3)^n z$. Since X is compact there is $y \in X$ such that $z_n \to y$. Note also that $V_{2n} \subset V_{2(n+1)}$ are compact sets and $V_2 = \bigcup_{n \geq 1} V_{2n}$. Thus $V_2 y \subset X$.

5. Proof of Theorem 2.1

We will prove Theorem 2.1 in this section using the construction in Section 4. We will first reduce the proof of Theorem 2.1 to the "inseparable" case. The existence of this inseparable case in some sense is the main difference with the proof in the characteristic zero case.

Lemma 5.1. If (i) in Proposition 4.6 holds, then there exists $y \in \overline{Hx}$ and a polynomial f whose derivative is non-constant such that $V_2(f)y \subset \overline{Hx}$.

Proof. We have Y is invariant under

$$R = \langle d(\sigma(t)) \ v_2 \left(\frac{\vartheta(t)}{\sigma(t)^2} \right) : \ t \in K_{\nu} \rangle$$

where $\langle \bullet \rangle$ denotes the group generated by \bullet . Recall also that $\sigma(t)$ is a non-constant polynomial.

Recall that Hx is not closed. We claim that for any $y \in Y$ the closure of the subset $M = \{g \in G - H : gy \in \overline{Hx}\}$ contains the identity. Assume the contrary. In particular since $y \in \overline{Hx}$ we have; the closure of $\{g \in G - H : gy \in Hy\}$ does not contain the identity. Then since $y \in X$ and X is H-minimal Lemma 3.4 implies that Hy is compact. Also note that since $y \in \overline{Hx}$ and $e \notin \overline{M}$ we have $y \in Hx$. These imply that Hx is closed which is a contradiction.

We now apply Lemma 3.2 with $M, Y' = \overline{Hx}, Y, P' = H, F = V_1$ and $P = V_1$. Hence for any $h \in N_G(V_1) \cap HMV_1$ we have $hY \subset Y' = \overline{Hx}$. Pick $\{g_n\} \subset M$ such that $g_n \to e$. Let us first assume that there exists some subsequence $\{g_{n_i}\} \subset G-HV_2$. Abusing the notation we continue to denote this subsequence by $\{g_n\}$. For n large enough we have $g_n = V_1^-(g_n)W_1^-(g_n)T(g_n)W_1(g_n)V_1(g_n)$. Multiplying on left by H we may and will assume that $V_1^-(g_n) = e$. Thus we have a sequence $\{g_n\}$ such that $g_n \to e$, $V_1^-(g_n) = e$ and $\{g_n\} \not\subset HV_2$. We now apply the construction of Lemma 4.4 with $\{g_n\}$. We get a non-constant strongly V_1 -quasiregular map ϕ_1 such that $Im(\phi_1) \subset N_G(V_1)$ and $\phi_1(s)Y \subset Y'$ for all $s \in K_{\nu}$.

Recall that $g_n \in W_1^- TW = W_1^- B$ hence Lemma 4.5 implies that $\operatorname{Im}(\phi_1) \subset W$. This in view of the fact $N_G(V_1) = DV$ gives $\operatorname{Im}(\phi_1) \subset V_2$ i.e. $\phi_1(s) = v_2(\vartheta_1(s))$ and for any $s \in K_{\nu}$ we have $v_2(\vartheta_1(s))Y \subset X$. Define the polynomial $f_u(t) = \vartheta_1(s)\sigma^2(t) - \vartheta(t)$, where $u = v_2(\vartheta_1(s))$. Since $\vartheta_1(s)$ and $\sigma(t)$ are non-constant polynomials and $\operatorname{deg}(\sigma(t)) \leq 2$, we can find $u_0 = \phi_1(s_0)$ such that both f_{u_0} and also its derivative f'_{u_0} are non-constant polynomials.

We now turn to the case $\{g_n\} \subset HV_2$. Thus there are infinitely many elements $v_n = v_2(t_n) \in V_2$ such that $v_n y \in \overline{Hx}$. Thus we may find $u_0 = v_2(t_k)$ for some k such that $f_{u_0}(t) = t_k \sigma^2(t) - \vartheta(t)$ and f'_{u_0} are both non-constant polynomials.

Now apply Lemma 3.2 with $M = \{u_0\}$ which is defined above, $Y' = \overline{Hx}$, $Y, P' = H, F = V_1$ and $P = \langle R, V_1 \rangle$, the closed group generated by R and V_1 . According

to Lemma 3.2 we have $hY \subset \overline{Hx}$ for any $h \in N_G(V_1) \cap \overline{HMP}$. Note that for any t one has

$$d(\sigma(t)) u_0 \left[d(\sigma(t)) v_2 \left(\frac{\vartheta(t)}{\sigma(t)^2} \right) \right]^{-1} = v_2(f_{u_0}(t)) \in HMP$$
Thus $v_2(f_{u_0}(t))Y \subset \overline{Hx}$ for any $t \in K_{\nu}$.

We make the following elementary observation

Lemma 5.2. Let L be a lattice in Ω and $B(t_0, r_0)$ an open ball of radius r_0 about t_0 in K_{ν} . Then there exists some nonzero $\mathbf{v} \in V_2(B(r_0, t_0))L$ such that $Q(\mathbf{v}) = 0$.

Proof. Indeed we may and will assume $r_0 < 1$. Let $B = B(t_0, r_0)$. For any $\mathbf{w} \in K_{\nu}^3$ and r > 0 let $B(\mathbf{w}, r)$ denote the ball of radius r about \mathbf{w} in K_{ν}^3 . For any $\mathbf{u} = (u_1, u_2, u_3) \in K_{\nu}^3$ with $u_3 \neq 0$ define $q(\mathbf{u}) = -\frac{Q(\mathbf{u})}{2u_3^2}$. Fix some $\mathbf{w}_r = (-t_0 w_3, 0, w_3)$ with $|w_3| > \max\{r/r_0, |t_0|r/r_0\}$. Then the map $q : B(\mathbf{w}_r, r) \to K_{\nu}$ is defined on $B(\mathbf{w}_r, r)$ and $\operatorname{Im}(q) \subset B$. Since L is a lattice in K_{ν}^3 there exists some r = r(L) > 0 such that $L \cap B(\mathbf{w}, r) \neq \emptyset$ for all $\mathbf{w} \in K_{\nu}^3$. Let \mathbf{w}_r be given as above corresponding to this r. Let $\mathbf{y} \in L \cap B(\mathbf{w}_r, r)$. Then $y_3 \neq 0$ and $s = q(\mathbf{y}) = -\frac{Q(\mathbf{y})}{2y_3^2} \in B$.

For any $\mathbf{u} \in K^3_{\nu}$ we have

$$v_2(t)\mathbf{u} = v_2(t) \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix} = \begin{pmatrix} u_1 + tu_3 \\ u_2 \\ u_3 \end{pmatrix}$$

Hence $Q(v_2(t)\mathbf{u}) = 2tu_3^2 + Q(\mathbf{u})$. Thus $Q(v_2(s)\mathbf{y}) = 0$.

Corollary 5.3. Theorem 2.1 holds if one of the following holds

- (a) $\operatorname{Char} K > 3$
- (b) (i) or (ii) in Proposition 4.6 holds.

Proof. Note that if $\operatorname{Char} K > 3$, then case (iii) of Proposition 4.6 above is contained in case (ii) of that proposition. So we need to show Theorem 2.1 holds if (b) above holds.

By Lemma 5.2 the corollary is immediate if case (ii) holds and follows from Lemma 5.1 and the inverse function Theorem if case (i) holds. \Box

The inseparable case. The Corollary 5.3 reduces the proof of Theorem 2.1 to the case where (iii) in Proposition 4.6 holds. In particular from now on we assume Char K = 3. We keep all the assumptions and the notation as before. Let us fix some further notation. Define $K_{\nu}^{(3)} = \{k^3 | k \in K_{\nu}\}$. This is a subfield of K_{ν} and $K_{\nu}/K_{\nu}^{(3)}$ is a purely inseparable extension of degree 3. For any nonzero element $a \in K_{\nu}$ we will let $V_2^a = V_2(f)$ where $f(t) = at^3$. The subgroups V_2^a and $V^a = V_1V_2^a$ are closed subgroups of V. They are actually unipotent algebraic groups if we change our base field to $K_{\nu}^{(3)}$. To be more precise one needs to use Weil's restriction of scalars and replace SL_3 by $\mathrm{R}_{K_{\nu}/K_{\nu}^{(3)}}(\mathrm{SL}_3)$ then V^a is a $K_{\nu}^{(3)}$ -split unipotent algebraic subgroup of $\mathrm{R}_{K_{\nu}/K_{\nu}^{(3)}}(\mathrm{SL}_3)(K_{\nu}^{(3)}) = G$. We will try to avoid these and instead will keep our calculations explicit and down to earth. If $\{a,b,c\}$ is a basis for K_{ν} over $K_{\nu}^{(3)}$, then

we let pr_{yz}^x (resp. pr_z^{xy}) denote the projection onto the space $y K_{\nu}^{(3)} + z K_{\nu}^{(3)}$ (resp. $z K_{\nu}^{(3)}$) parallel to $x K_{\nu}^{(3)}$ (resp. $x K_{\nu}^{(3)} + y K_{\nu}^{(3)}$) where x, y, z are distinct elements in $\{a, b, c\}$. For a basis $\{a, b, c\}$ of K_{ν} over $K_{\nu}^{(3)}$ define

$$W_1^{b,c} = \left\{ \begin{pmatrix} 1 & 0 & x \\ 0 & 1 & y \\ 0 & 0 & 1 \end{pmatrix} : x \in bK_{\nu}^{(3)} + cK_{\nu}^{(3)}, y \in K_{\nu} \right\}$$

Lemma 4.2 shows that we can find a sequence $\{g_n\} \subset G - DV$ such that $g_n \to e$ and $g_n Y \cap Y \neq \emptyset$. We construct a V_1 -quasiregular map ϕ as in Lemma 4.4 using this sequence $\{g_n\}$. The calculations following Lemma 4.4 show

(5)
$$\phi(t) = d(\sigma(t)) \ v_2\left(\frac{\vartheta(t)}{\sigma(t)^2}\right)$$

Furthermore thanks to Corollary 5.3 we may and will assume that σ is constant map and $\vartheta(t) = at^3$ for some $a \neq 0$ and $V_1V_2^aY = Y$. Extend $\{a\}$ to a basis $\{a,b,c\}$ for K_{ν} over $K_{\nu}^{(3)}$.

Note that Y is a (minimal) invariant set for V^a . We apply Lemma 3.3 with $M = \{g_n\}$ the same sequence as above, $P = V^a$ and $F = V_1$. Hence hY = Y for all $h \in N_G(V_1) \cap \overline{PMP}$. Write as before

$$g_n = \begin{pmatrix} a_{1n} & a_{2n} & a_{3n} \\ b_{1n} & b_{2n} & b_{3n} \\ c_{1n} & c_{2n} & c_{3n} \end{pmatrix}$$

A simple calculation shows that

$$N_G(V^a) \subset \{g \in G : gV_1g^{-1} \subset V^a\} = DV$$

For any $t,s,a\in K_{\nu}$ let $v^a(t,s)=v_1(t)v_2(as^3)$. Since $\{g_n\}\subset G-DV$ and $N_G(V^a)\subset DV$ we get: $v^a(t,s)g_n(V^a)\subset G/V^a$ is a non-constant polynomial map of bounded degree into some affine space over $K_{\nu}^{(3)}$, here indeed we are using Chevalley's Theorem for the algebraic subgroup V^a of G as we mentioned above. Let \mathfrak{B}^a be some relatively compact neighborhood of the coset V^a in G/V^a . Choose $r^a(n)$ such that $V^a_{r^a(n)}g_nV\not\subset \mathfrak{B}^a$ but $V^a_kg_nV\subset \mathfrak{B}^a$ for all $k< r^a(n)$. Denote by α^a_n the conjugation with $d(\theta^3)^{r^a(n)}$ and let $\sigma^a_n:V^a\to B^-$, $\vartheta^a_n:V^a\to W^{b,c}_1$ and $\vartheta_n:V^a\to W_1$ be K_{ν} -rational morphisms defined by

 $\alpha_n(v^a(t,s))g_n\beta_n^a(t,s) = \sigma_n^a(t,s)\vartheta_n^a(t,s)$ and $\alpha_n(v^a(t,s))g_n\beta_n(t,s) = \sigma_n(t,s)\vartheta_n(t,s)$ where $\beta_n^a(t,s) \in V^a$ and $\beta_n(t,s) \in V_1$. In coordinates we have

$$\sigma_n^a(t,s) = \begin{pmatrix} \sigma_{11}^n(t,s) & 0 & 0\\ \sigma_{21}^n(t,s) & \sigma_{22}^n(t,s) & 0\\ \sigma_{31}^n(t,s) & \sigma_{32}^n(t,s) & \sigma_{33}^n(t,s) \end{pmatrix}$$

$$\vartheta_n^a(t,s) = \begin{pmatrix} 1 & 0 & \vartheta_{13}^{an}(t,s) \\ 0 & 1 & \vartheta_{23}^{an}(t,s) \\ 0 & 0 & 1 \end{pmatrix} \text{ and } \vartheta_n(t,s) = \begin{pmatrix} 1 & 0 & \vartheta_{13}^n(t,s) \\ 0 & 1 & \vartheta_{23}^n(t,s) \\ 0 & 0 & 1 \end{pmatrix}$$

Define

$$\phi_n^a(t,s) = \alpha_n(v^a(t,s))g_n\beta_n^a(t,s) = \sigma_n^a(t,s)\vartheta_n^a(t,s)$$

Note that this construction fits into the same frame work as in Lemma 4.4. Thus as in the proof of loc. cit. we may pass to the limit and get a non-constant strongly V^a -quasiregular map $\phi^a(t,s)$ such that $\text{Im}(\phi^a) \subset N_G(V^a) \subset DV$. We have

$$\begin{array}{l} (\dagger^a) \ \ (\sigma_n^a)_{11}(t,s) = a_{1n} + b_{1n} \theta^{3r^a(n)} t + c_{1n} \theta^{6r^a(n)} \frac{t^2 + 2as^3}{2} = a_{1n} + b_{1n}' t + c_{1n}'' \frac{t^2 + 2as^3}{2} \\ (\ddagger^a) \ \ \vartheta_{13}^{an}(t,s) = \frac{\vartheta_n(t,s)^a}{((\sigma_n^a)_{11}(t,s))^3}, \ \text{where} \ \vartheta_n(t,s)^a \ \text{is a polynomial.} \end{array}$$

Passing to the limit we have

$$\phi^{a}(t,s) = d(\sigma^{a}(t,s)) \ v_{2}\left(\frac{\vartheta^{a}(t,s)}{(\sigma^{a}(t,s))^{3}}\right)$$

We need a more explicit description of $\vartheta_n(t,s)^a$. Let us recall from (\ddagger) that

$$\vartheta_{13}^n(t) = \frac{2(v_1(\alpha_n(t))g_n)_{13}(v_1(\alpha_n(t))g_n)_{11} - ((v_1(\alpha_n(t))g_n)_{12})^2}{2((v_1(\alpha_n(t))g_n)_{11})^2} = \frac{\vartheta_{0n}(t)}{(\sigma_n(t))^2}$$

are pre-limit functions for the construction of $\phi(t)$ in $\overline{V_1MV_1}$. Similarly we have $\vartheta_{13}^n(t,s)=\frac{\vartheta_{0n}(t,s)}{(\sigma_n(t,s))^2}$. If we apply the renormalization $\mathfrak{t}=\theta^{3r^a(n)}t$ and $\mathfrak{s}^3=\theta^{6r^a(n)}s^3$, we may write

(6)
$$\vartheta_{0n}(\mathfrak{t}) = A_{0n} + A_{1n}\mathfrak{t} + A_{3n}\mathfrak{t}^2 + A'_{3n}\mathfrak{t}^2/2 + A_{4n}\mathfrak{t}^3/2 + A'_{4n}(\mathfrak{t}^2/2)^2$$

(7)

$$\vartheta_{0n}(\mathfrak{t},\mathfrak{s}) = A_{0n} + A_{1n}\mathfrak{t} + A_{3n}\mathfrak{t}^2 + A_{3n}'(\mathfrak{t}^2/2 + a\mathfrak{s}^3) + A_{4n}\mathfrak{t}(\mathfrak{t}^2/2 + a\mathfrak{s}^3) + A_{4n}'(\mathfrak{t}^2/2 + a\mathfrak{s}^3)^2$$

In view of these formulas $\vartheta_n(t,s)^a$ is

$$\operatorname{pr}^a_{bc}\{\vartheta_{0n}(\mathfrak{t},\mathfrak{s})(a_{1n}+b_{1n}^{'a}\mathfrak{t}+c_{1n}^{''a}(\mathfrak{t}^2/2+a\mathfrak{s}^3))\}$$

Recall that thanks to Corollary 5.3 in the equation (5) we have $\sigma(t) = 1$ for all $t \in K_{\nu}$ and $\vartheta(t) = at^3$ for some $a \neq 0$. Thus $\vartheta(t) = \lim_n A_{4n} (\theta^{3r(n)}t)^3/2$ where A_{4n} is as in (6).

We claim that there exists some constant $\mathfrak{b} > 0$, depending on \mathfrak{B} chosen in the proof of Lemma 4.4 and \mathfrak{B}^a which we chose here, such that $r^a(n) \leq \mathfrak{b} r(n)$. To see the claim note that the above paragraph implies that

$$\max_{|t| \le 1} A_{4n}(\theta^{3r(n)}t)^3/2 \ge C = C(\mathfrak{B}) \text{ for all } n$$

thus $\max_{|t|,|s|\leq 1} |A_{4n}\theta^{9r(n)}t(t^2/2+as^3)| \geq C$ for all n. Also note that for $s\neq 0$ the image of the polynomial $A_{4n}\theta^{9r(n)}t(t^2/2+as^3)$, as a polynomial of t, contains an open neighborhood of 0 thus

$$\lim_{n} \operatorname{pr}_{bc}^{a} \{ a_{1n} (A_{4n} \theta^{9r(n)} t(t^{2}/2 + as^{3})) \}$$

is a nontrivial polynomial. This implies the claim.

From this claim and \dagger^a we conclude that $\sigma^a(t,s)=1$ is the constant polynomial. Hence

$$\phi^a(t) = v_2(\vartheta^a(t,s))$$
 and $\vartheta^a(t,s) = \lim_n \operatorname{pr}_{bc}^a(a_{1n}\vartheta_{0n}(\mathfrak{t},\mathfrak{s}))$

This in view of (7) and the above discussion implies that

$$\vartheta^{a}(t,s) = \lim_{n} \operatorname{pr}_{bc}^{a} \{ a_{1n} (A'_{3n} a \mathfrak{s}^{3} + A_{4n} \mathfrak{t}(\mathfrak{t}^{2}/2 + a \mathfrak{s}^{3})) \}$$

There are two possibilities: either $\lim_n \operatorname{pr}_{bc}^a \{a_{1n}(A_{4n}\mathfrak{t}(\mathfrak{t}^2/2 + a\mathfrak{s}^3))\} = 0$ is the constant polynomial or this limit is non-constant. Let us first assume the later holds. This in particular implies that $\lim_n A_{4n}\theta^{9r^a(n)} = A \neq 0$. Thus we have

$$\lim_{n} a_{1n} (A_{4n} \mathfrak{t}(\mathfrak{t}^2/2 + a\mathfrak{s}^3)) = A(t^3/2 + ats^3)$$

On the other hands $\operatorname{Im}(A(t^3/2 + ats^3))$ contains an open neighborhood of 0 which then implies that $R = aK_{\nu}^{(3)} + \operatorname{Im}\vartheta^a(t,s)$ contains and open subset of K_{ν} . Besides $V_2(R)Y = Y$ hence an argument similar to the proof of Proposition 4.6 implies that (ii) in loc. cit. holds and Theorem 2.1 follows from Corollary 5.3 in this case.

In view of the above we may and will assume that $\lim_n \operatorname{pr}_{bc}^a \{a_{1n}(A_{4n}\mathfrak{t}(\mathfrak{t}^2/2+a\mathfrak{s}^3))\}$ is constant. This is to say $\vartheta^a(t,s) = \lim_n \operatorname{pr}_{bc}^a(a_{1n}A'_{3n}a(\mathfrak{s}^3)) = a's^3$ for some non-zero $a' \in bK_{\nu}^{(3)} + cK_{\nu}^{(3)}$.

Thus Y is invariant under $V^{aa'}=V_1V_2^aV_2^{a'}$ and is indeed V_1 -minimal. We repeat the construction above one further time i.e. we construct $V^{aa'}$ -quasi regular map. A simple calculation shows that $N_G(V^{aa'}) \subset DV$ hence $\{g_n\}$ chosen above can be used again. We apply Lemma 3.3 with $M=\{g_n\}$ the above sequence, $P=V^{aa'}$ and $F=V_1$. In view of that lemma we have hY=Y for any $h\in N_G(V_1)\cap \overline{PMP}$. We use the notations as above with the obvious modification e.g. ϕ^a there is replaced by $\phi^{aa'}$ in here etc. Same argument as above gives: there exists some $\mathfrak{b}'>0$ such that $r^{aa'}(n)\leq \mathfrak{b}'r(n)$. Hence $\sigma^{aa'}(t,s,r)=1$ is constant and

$$\phi^{aa'}(t,s,r) = v_2(\vartheta^{aa'}(t,s,r))$$

Let $\{a, a', a''\}$ be a basis for K_{ν} over $K_{\nu}^{(3)}$. Define the renormalized variables $\mathfrak{t} = \theta^{3r^{aa'}(n)}t$, $\mathfrak{s}^3 = \theta^{6r^{aa'}(n)}s^3$ and $\mathfrak{r}^3 = \theta^{6r^{aa'}(n)}r^3$. We have

$$\vartheta^{aa'}(t,s,r) = \lim_n \operatorname{pr}_{a''}^{aa'} \left\{ a_{1n} (A'_{3n} (a\mathfrak{s}^3 + a'\mathfrak{r}^3) + A_{4n} \mathfrak{t}(\mathfrak{t}^2/2 + a\mathfrak{s}^3 + a'\mathfrak{r}^3)) \right\}$$

Now either $\lim_n \operatorname{pr}_{a''}^{aa'}(a_{1n}A_{4n}\mathfrak{t}(\mathfrak{t}^2/2+a\mathfrak{s}^3+a'\mathfrak{r}^3)))=0$ is constant or a non-constant polynomial. If the later holds the argument goes through the same lines of the argument above. If the first holds then

$$\vartheta^{aa'}(t, s, r) = \lim_{n} \operatorname{pr}_{a''}^{aa'} \{ a_{1n}(A'_{3n}(a\mathfrak{s}^3 + a'\mathfrak{r}^3)) \}$$

Thus $\vartheta^{aa'}(t,s,r)=a''(l_1s^3+l_2r^3)$ where $l_i\in K_{\nu}^{(3)}$ and at least one of them is nonzero. Hence we get Y is invariant under $V_2^{a''}$ and since $\{a,a',a''\}$ is a basis for K_{ν} over $K_{\nu}^{(3)}$ we have $V_2=V_2^aV_2^{a'}V_2^{a''}$. This gives $V_2Y=Y$ i.e. we are in case (ii) of Proposition 4.6. Thus Corollary 5.3 finishes the proof.

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