

Summary of the third week's lectures

How to find equation of a plane.

Exp. 1. [Given: a normal vector $\langle a, b, c \rangle$ and a point (x_0, y_0, z_0) .

Equation: $ax + by + cz = ax_0 + by_0 + cz_0$.]

Find an equation of a plane containing $(1, 2, 3)$ with a normal vector $\langle 1, -1, 1 \rangle$.

Solution $(1)x + (-1)y + (1)z = (1)(1) + (-1)(2) + (1)(3)$

So $x - y + z = 2$.

Exp. 2 [Given: three points P_1, P_2 and P_3 .

$\vec{n} = \vec{P_1P_2} \times \vec{P_1P_3}$ is a normal vector. Now we

can use Exp. 1 for \vec{n} and P_1 .]

Find an equation of a plane which contains

$P_1 = (1, 0, 1)$, $P_2 = (0, 1, 1)$ and $P_3 = (1, 1, 0)$.

Solution. $\vec{n} = \vec{P_1P_2} \times \vec{P_1P_3}$ is a normal vector.

$$\vec{n} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ -1 & 1 & 0 \\ 0 & 1 & -1 \end{vmatrix} = \left\langle \begin{vmatrix} 1 & 0 \\ 1 & -1 \end{vmatrix}, -\begin{vmatrix} -1 & 0 \\ 0 & -1 \end{vmatrix}, \begin{vmatrix} -1 & 1 \\ 0 & 1 \end{vmatrix} \right\rangle$$
$$= \langle -1, -1, -1 \rangle.$$

So $-x - y - z = -1 - 0 - 1 = -2$ is an equation of this plane.

Exp. 3 [Given: Two parallel vectors \vec{v} and \vec{w} and a point (x_0, y_0, z_0) .

$\vec{n} = \vec{v} \times \vec{w}$ is a normal vector. Now we can use Exp. 1.]

Exp. 4 [Given: Contains two intersecting lines:

$$\vec{r}_1(t) = \vec{OP}_0 + t \vec{v}_1$$

$$\text{and } \vec{r}_2(t) = \vec{OP}_0 + t \vec{v}_2.$$

Then $\vec{n} = \vec{v}_1 \times \vec{v}_2$ is a normal vector and again we can use Exp. 1.]

Exp. 5 [Given: A parallel plane: $ax + by + cz = d$
A point: (x_0, y_0, z_0)

Two parallel planes share normal vectors. So $\langle a, b, c \rangle$ is a normal vector of the considered plane. Hence an equation of this plane is $ax + by + cz = ax_0 + by_0 + cz_0$.]

Exp. 6 [Given: Contains two parallel lines

$$\vec{r}_1(t) = \vec{OP}_1 + t \vec{v}$$

and $\vec{r}_2(t) = \vec{OP}_2 + t \vec{v}.$

Then $\vec{n} = \vec{P}_1\vec{P}_2 \times \vec{v}$ is a normal vector. Now we can use Exp 1 for \vec{n} and the point P_1 .]

Vector-valued Functions

A function $\vec{r}(t) = \langle x(t), y(t), z(t) \rangle$ is called a vector-valued function (for now).

This type of function is helpful to

- Parametrize a curve
- Describe the position vector of a moving particle.
- Find velocity or acceleration of a moving particle.
- etc.

Exp 1. Parametrize the segment PQ where

$$P = (1, 0, 1) \quad \text{and} \quad Q = (2, 3, 4).$$

Solution. $\vec{r}(t) = t \vec{OQ} + (1-t) \vec{OP}$ for $0 \leq t \leq 1$.

$$\vec{r}(t) = t \langle 2, 3, 4 \rangle + (1-t) \langle 1, 0, 1 \rangle$$

$$= \langle 1+t, 3t, 1+3t \rangle \quad \text{for } 0 \leq t \leq 1.$$

Exp 2. Parametrize the line through $P_0 = (1, 2, 3)$
and parallel to $\vec{v} = \langle 4, 5, 6 \rangle$.

Solution. $\vec{r}(t) = \vec{OP}_0 + t \vec{v}$
 $= \langle 1, 2, 3 \rangle + t \langle 4, 5, 6 \rangle$
 $= \langle 1+4t, 2+5t, 3+6t \rangle$.

Exp 3. Parametrize the circle of radius 2, centered at
the origin in the yz -plane.

Solution. $x = 0$ (since in the yz -plane)
 $y = 2 \cos \theta$ and $z = 2 \sin \theta$ for $0 \leq \theta < 2\pi$.

So $\vec{r}(\theta) = \langle 0, 2 \cos \theta, 2 \sin \theta \rangle$ for $0 \leq \theta < 2\pi$.

Remark. Whenever you see $A^2 + B^2 = 1$, you should think
of $A = \cos \theta$ and $B = \sin \theta$!

Exp 4. Parametrize an ellipse with center $(1, -2, -1)$
which is a translation of the ellipse

$$\left(\frac{x}{2}\right)^2 + \left(\frac{y}{3}\right)^2 = 1$$

in the xy -plane.

Solution. A parametrization of the ellipse

$$\left(\frac{x}{2}\right)^2 + \left(\frac{y}{3}\right)^2 = 1$$

in the xy -plane is

$$\left. \begin{array}{l} \frac{x}{2} = \cos \theta \\ \frac{y}{3} = \sin \theta \\ z = 0 \end{array} \right\} \Rightarrow \langle 2 \cos \theta, 3 \sin \theta, 0 \rangle.$$

So a parametrization of its translate with center

$$(1, -2, -1)$$

$$\begin{aligned} \text{is } \vec{r}(\theta) &= \langle 1, -2, -1 \rangle + \langle 2 \cos \theta, 3 \sin \theta, 0 \rangle \\ &= \langle 1 + 2 \cos \theta, -2 + 3 \sin \theta, -1 \rangle \end{aligned}$$

for $0 \leq \theta < 2\pi$.

Exp 5. Parametrize the curve of intersection of the cylinder $x^2 + y^2 = 1$ and the plane $x + y + z = 1$.

Solution. $x = \cos \theta$, $y = \sin \theta$, for $0 \leq \theta < 2\pi$.

$$z = 1 - x - y = 1 - \cos \theta - \sin \theta.$$

So $\vec{r}(\theta) = \langle \cos \theta, \sin \theta, 1 - \cos \theta - \sin \theta \rangle$ for $0 \leq \theta < 2\pi$.

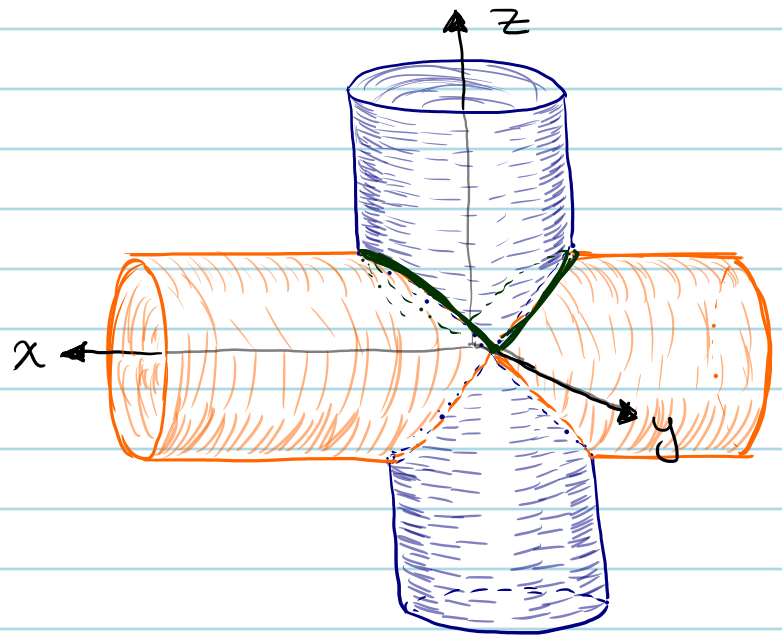
Exp 6. Parametrize the curve of intersection of the cylinders $x^2 + y^2 = 1$ and $y^2 + z^2 = 1$, and $z \geq 0$.

Solution. $x = \cos \theta$, $y = \sin \theta$, for $0 \leq \theta < 2\pi$.

$$z^2 = 1 - y^2 = 1 - \sin^2 \theta = \cos^2 \theta$$

Since $z \geq 0$, $z = |\cos \theta|$. So

$$\vec{r}(\theta) = \langle \cos \theta, \sin \theta, |\cos \theta| \rangle.$$



Calculus of vector-valued functions

$$\lim_{t \rightarrow a} \vec{r}(t) = \langle \lim_{t \rightarrow a} x(t), \lim_{t \rightarrow a} y(t), \lim_{t \rightarrow a} z(t) \rangle$$

Exp. Find $\lim_{t \rightarrow 0} \langle \frac{e^t - 1}{t}, \frac{\sin t}{t}, \cos t \rangle$.

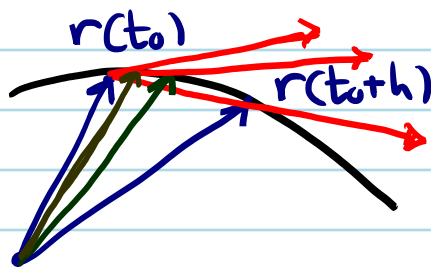
Solution. $\lim_{t \rightarrow 0} \langle \frac{e^t - 1}{t}, \frac{\sin t}{t}, \cos t \rangle =$

$$\left\langle \lim_{t \rightarrow 0} \frac{e^t - 1}{t}, \lim_{t \rightarrow 0} \frac{\sin t}{t}, \lim_{t \rightarrow 0} \cos t \right\rangle =$$

(L'Hopital's rule) $\left\langle \lim_{t \rightarrow 0} \frac{e^t}{1}, \lim_{t \rightarrow 0} \frac{\cos t}{1}, \cos(0) \right\rangle =$

$$\langle 1, 1, 1 \rangle.$$

Derivative $\vec{r}'(t_0) = \lim_{h \rightarrow 0} \frac{\vec{r}(t_0+h) - \vec{r}(t_0)}{h}$



So $\vec{r}'(t_0)$ is parallel to the tangent line of $\vec{r}(t)$ at $\vec{r}(t_0)$.

Also we have $\vec{r}'(t) = \langle x'(t), y'(t), z'(t) \rangle$.

Exp. [Parametrization of the tangent line of $\vec{r}(t)$ at $\vec{r}(t_0)$:

$$\vec{L}(t) = \vec{r}(t_0) + t \vec{r}'(t_0)]$$

Find a parametrization of the tangent line of a helix $\vec{r}(t) = \langle \cos(2t), t, \sin(2t) \rangle$ at

$$\vec{r}(\pi/4) = \langle 0, \pi/4, 1 \rangle.$$

Solution. $\vec{L}(t) = \vec{r}(\pi/4) + t \vec{r}'(\pi/4).$

$$\vec{r}'(t) = \langle -2 \sin(2t), 1, 2 \cos(2t) \rangle.$$

$$\begin{aligned} \text{So } \vec{L}(t) &= \langle 0, \pi/4, 1 \rangle + t \langle -2, 1, 0 \rangle \\ &= \langle -2t, t + \pi/4, 1 \rangle. \end{aligned}$$

A moving particle

If $\vec{r}(t)$ is the position vector of a moving particle, then

its velocity $\vec{v}(t) = \vec{r}'(t).$

its acceleration $\vec{a}(t) = \vec{v}'(t) = \vec{r}''(t).$

its speed $s(t) = \|\vec{v}(t)\| = \|\vec{r}'(t)\|.$

Exp. The position vector of a moving particle is

$$\vec{r}(t) = \langle \ln t, t+1, t^2 \rangle$$

(a) Find its velocity at $t=1$.

(b) Find its acceleration at $t=1$.

(c) Find its speed at $t=1$.

Solution. $r'(t) = \left\langle \frac{1}{t}, 1, 2t \right\rangle$

$$r''(t) = \left\langle -\frac{1}{t^2}, 0, 2 \right\rangle$$

(a) $r'(1) = \langle 1, 1, 2 \rangle$

(b) $r''(1) = \langle -1, 0, 2 \rangle$

(c) $\|r'(1)\| = \sqrt{1+1+4} = \sqrt{6}$.

Warning. Non-zero acceleration does NOT mean that the speed is not constant. It only means that the velocity is not constant.

Exp. The position vector of a moving particle is

$$\vec{r}(t) = \langle \cos(t), \sin(t), t \rangle$$

(a) Find its speed.

(b) Find its acceleration.

Solution. (a) $s(t) = \|r'(t)\| = \|\langle -\sin t, \cos t, 1 \rangle\|$
 $= \sqrt{\sin^2 t + \cos^2 t + 1} = \sqrt{2}$.

(b) $a(t) = r''(t) = \langle -\cos t, -\sin t, 0 \rangle$

$r'(t) = \langle -\sin t, \cos t, 1 \rangle$

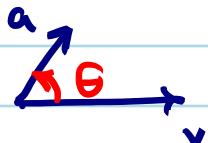
Notice In the above example, speed is constant,
but acceleration is NOT zero.

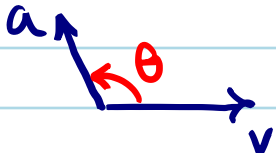
Q How can we determine if a moving particle is speeding up or slowing down at $t=t_0$?

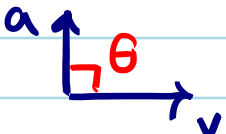
Intuition • If $\text{Proj}_{\vec{v}} \vec{a}$ and \vec{v} have the same direction, then it is speeding up.

• If $\text{Proj}_{\vec{v}} \vec{a}$ and \vec{v} have opposite directions, then it is slowing down.

• If $\text{Proj}_{\vec{v}} \vec{a} = 0$, then the speed is constant.

Geometrically  acute \Rightarrow speeding up

 obtuse \Rightarrow slowing down

 $\theta = \pi/2 \Rightarrow$ constant speed.

Computational $\vec{a} \cdot \vec{v} > 0 \Rightarrow$ speeding up

$$\vec{a} \cdot \vec{v} < 0 \Rightarrow \text{Slowing down}$$

$$\vec{a} \cdot \vec{v} = 0 \Rightarrow \text{Constant speed}$$

Mathematical reasoning

It is speeding up at $t = t_0$ if and only if

$$s'(t_0) > 0 \text{ where } s(t) = \|\vec{v}(t)\| = \|\vec{r}'(t)\|$$

is the speed function.

$$s'(t) = \frac{d}{dt} \sqrt{\vec{v}(t) \cdot \vec{v}(t)}$$

(Chain rule)

$$= \frac{1}{2\sqrt{\vec{v}(t) \cdot \vec{v}(t)}} \frac{d}{dt} (\vec{v}(t) \cdot \vec{v}(t))$$

(Dot product rule)

$$= \frac{1}{2\|\vec{v}(t)\|} (\vec{v}'(t) \cdot \vec{v}(t) + \vec{v}(t) \cdot \vec{v}'(t))$$

$$= \frac{2\vec{a}(t) \cdot \vec{v}(t)}{2\|\vec{v}(t)\|} = \frac{\vec{a}(t) \cdot \vec{v}(t)}{\|\vec{v}(t)\|}$$

(This is actually the component of \vec{a} along \vec{v} .)

The total distance traveled over $a \leq t \leq b$ is

$$\int_a^b \|\vec{r}'(t)\| dt.$$