

Lecture 28 - Differential Forms cont.

- This is the final in-person lecture. The next two lectures will be asynchronous. Find the video posted in the Media Gallery on Canvas and the lecture notes under the Lecture Notes module.
 - o I already recorded the final review lecture; it is posted as a single video.
- The final is next Monday (12/6) in-person from 8 am to 11 am, WLH 2001. You can bring two sheets of hand-written notes (four pages front and back).

$$\begin{array}{ccccccc} \Omega^0(\mathbb{R}^3) & \xrightarrow{d} & \Omega^1(\mathbb{R}^3) & \xrightarrow{d} & \Omega^2(\mathbb{R}^3) & \xrightarrow{d} & \Omega^3(\mathbb{R}^3) \\ | & & | & & | & & | \\ \text{points} & \xleftarrow{\partial} & \text{curves} & \xleftarrow{\partial} & \text{surfaces} & \xleftarrow{\partial} & \text{volumes} \end{array}$$

The exterior derivative

$$d: \Omega^k(\mathbb{R}^3) \longrightarrow \Omega^{k+1}(\mathbb{R}^3)$$

For 0-forms, $\Omega^0(\mathbb{R}^3) \ni f: \mathbb{R}^3 \rightarrow \mathbb{R}$,
 df is defined to be the differential of $f(x, y, z)$,

$$df = \underline{\frac{\partial f}{\partial x}} dx + \underline{\frac{\partial f}{\partial y}} dy + \underline{\frac{\partial f}{\partial z}} dz \in \Omega^1(\mathbb{R}^3)$$

$$df \sim \nabla f$$

For k -forms, when we expand the k -form in the coordinate basis with functions as the expansion coefficients, then the exterior derivative of that k -form is given by taking the exterior derivative of those functions and wedge it into the associated basis.

For 1-forms,

$$\alpha = \alpha_1 dx + \alpha_2 dy + \alpha_3 dz \in \Omega^1(\mathbb{R}^3)$$

$$d\alpha = d\alpha_1 \wedge dx + d\alpha_2 \wedge dy + d\alpha_3 \wedge dz \in \Omega^2(\mathbb{R}^3)$$

For 2-forms,

$$\dots \quad \dots \quad \dots \quad \dots \quad \dots \quad \Omega^2(\mathbb{R}^3)$$

For 2-forms,

$$\beta = \beta_1 dy \wedge dz + \beta_2 dz \wedge dx + \beta_3 dx \wedge dy \in \Omega^2(\mathbb{R}^3)$$

$$d\beta = d\beta_1 \wedge dy \wedge dz + d\beta_2 \wedge dz \wedge dx + d\beta_3 \wedge dx \wedge dy \in \Omega^3(\mathbb{R}^3)$$

More explicitly,

$$\alpha \in \Omega^1(\mathbb{R}^3)$$

$$d\alpha = d\alpha_1 \wedge dx + d\alpha_2 \wedge dy + d\alpha_3 \wedge dz$$

$$= \left(\frac{\partial \alpha_1}{\partial x} dx + \frac{\partial \alpha_1}{\partial y} dy + \frac{\partial \alpha_1}{\partial z} dz \right) \wedge dx$$

$$+ \left(\frac{\partial \alpha_2}{\partial x} dx + \frac{\partial \alpha_2}{\partial y} dy + \frac{\partial \alpha_2}{\partial z} dz \right) \wedge dy$$

$$+ \left(\frac{\partial \alpha_3}{\partial x} dx + \frac{\partial \alpha_3}{\partial y} dy + \frac{\partial \alpha_3}{\partial z} dz \right) \wedge dz$$

$$= \cancel{\frac{\partial \alpha_1}{\partial x} dx \wedge dx} + \cancel{\frac{\partial \alpha_1}{\partial y} dy \wedge dx} + \cancel{\frac{\partial \alpha_1}{\partial z} dz \wedge dx}$$

$$+ \cancel{\frac{\partial \alpha_2}{\partial x} dx \wedge dy} + \cancel{\frac{\partial \alpha_2}{\partial y} dy \wedge dy} + \cancel{\frac{\partial \alpha_2}{\partial z} dz \wedge dy} = -dy \wedge dz$$

$$+ \cancel{\frac{\partial \alpha_3}{\partial x} dx \wedge dz} + \cancel{\frac{\partial \alpha_3}{\partial y} dy \wedge dz} + \cancel{\frac{\partial \alpha_3}{\partial z} dz \wedge dz}$$

$$= 1 \left(\frac{\partial \alpha_3}{\partial y} - \frac{\partial \alpha_2}{\partial z} \right) dy \wedge dz$$

$$2 + \left(\frac{\partial \alpha_1}{\partial z} - \frac{\partial \alpha_3}{\partial x} \right) dz \wedge dx$$

$$3 + \left(\frac{\partial \alpha_2}{\partial x} - \frac{\partial \alpha_1}{\partial y} \right) dx \wedge dy$$

$\alpha \sim \vec{\alpha} = (\alpha_1, \alpha_2, \alpha_3)$

under i.d. of
2-forms ~ v.f.,
 $d\alpha \sim \nabla \times \vec{\alpha}$

$$\beta \in \Omega^2(\mathbb{R}^3)$$

$$\beta = \beta_1 dy \wedge dz + \beta_2 dz \wedge dx + \beta_3 dx \wedge dy$$

$$d\beta = d\beta_1 \wedge dy \wedge dz + d\beta_2 \wedge dz \wedge dx + d\beta_3 \wedge dx \wedge dy$$

$$= \left(\frac{\partial \beta_1}{\partial x} dx + \frac{\partial \beta_1}{\partial y} dy + \frac{\partial \beta_1}{\partial z} dz \right) \wedge dy \wedge dz$$

$$\begin{aligned}
&= \left(\frac{\partial \beta_1}{\partial x} dx + \cancel{\frac{\partial \beta_1}{\partial y} dy} + \cancel{\frac{\partial \beta_1}{\partial z} dz} \right) \wedge dy \wedge dz \\
&\quad + \left(\frac{\partial \beta_2}{\partial x} dx + \cancel{\frac{\partial \beta_2}{\partial y} dy} + \cancel{\frac{\partial \beta_2}{\partial z} dz} \right) \wedge dz \wedge dx \\
&\quad + \left(\frac{\partial \beta_3}{\partial x} dx + \cancel{\frac{\partial \beta_3}{\partial y} dy} + \cancel{\frac{\partial \beta_3}{\partial z} dz} \right) \wedge dx \wedge dy \\
&= \frac{\partial \beta_1}{\partial x} dx \wedge dy \wedge dz + \frac{\partial \beta_2}{\partial y} \overset{\curvearrowleft}{dy} \wedge \overset{\curvearrowleft}{dz} \wedge \overset{\curvearrowright}{dx} \\
&\quad + \frac{\partial \beta_3}{\partial z} \overset{\curvearrowright}{dz} \wedge \overset{\curvearrowleft}{dx} \wedge \overset{\curvearrowleft}{dy} \\
&= \left(\frac{\partial \beta_1}{\partial x} + \frac{\partial \beta_2}{\partial y} + \frac{\partial \beta_3}{\partial z} \right) dx \wedge dy \wedge dz
\end{aligned}$$

$$\beta \sim \vec{\beta} = (\beta_1, \beta_2, \beta_3) \quad d\beta \sim \nabla \cdot \vec{\beta}$$

Recall:

Given a 0-dim. region P (points). and a 0-form f ,

$$\int_P f = f(P)$$

$$\vec{\alpha} = (\alpha_1, \alpha_2, \alpha_3)$$

Given a 1-dim region C (curve) and a 1-form α ,

$$\int_C \alpha = \int_C \vec{\alpha} \cdot d\vec{r}$$

Given a 2-dim region S (surface) and a 2-form β ,

$$\int_S \beta = \iint_S \vec{\beta} \cdot d\vec{S}$$

$$\vec{\beta} = (\beta_1, \beta_2, \beta_3)$$

Given a 3-dim region W (volume) and a 3-form f

$$\int_W f dx \wedge dy \wedge dz = \iiint_W f dx dy dz$$

THE FUNDAMENTAL THEOREM OF CALCULUS

(The Generalized Stokes' Theorem)

Given a k -form α and a $(k+1)$ -dimensional region M , then

$$\int_M d\alpha = \int_{\partial M} \alpha$$

Boundary operator

(in \mathbb{R}^3)

case $k=0 \Rightarrow$ FTLI

case $k=1 \Rightarrow$ Stokes' Theorem

case $k=2 \Rightarrow$ Divergence Theorem