

Lecture 6 - COV for Spherical Coordinates; Vector Fields

- (Re)read section 4.3 on vector fields
- Read section 7.1 on path integrals for next time
- OH today from 9 am to 10 and tomorrow 11 am - 12

Recall 3D C.O.V

Let  $T: W^* \rightarrow W$  be a cont. diff. bijection, then

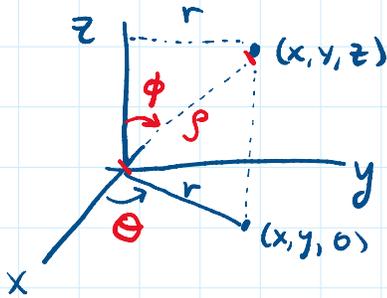
$$\iiint_W f(x,y,z) dx dy dz = \iiint_{W^*} f(T(u,v,w)) |\det DT(u,v,w)| du dv dw$$

or, if  $T(u,v,w) = (x(u,v,w), y(u,v,w), z(u,v,w))$

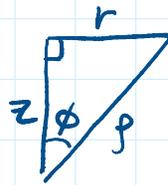
$$= \iiint_{W^*} f(x(u,v,w), y(u,v,w), z(u,v,w)) \left| \frac{\partial(x,y,z)}{\partial(u,v,w)} \right| du dv dw$$


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Spherical Coordinates



$(\rho, \theta, \phi)$



$$z = \rho \cos \phi$$

$$r = \rho \sin \phi$$

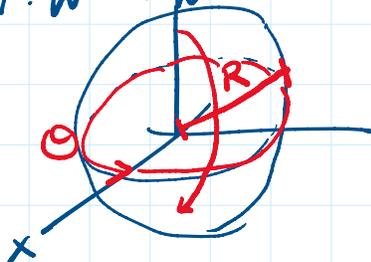
$$x = r \cos \theta = \rho \sin \phi \cos \theta$$

$$y = r \sin \theta = \rho \sin \phi \sin \theta$$

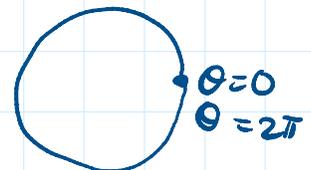
$$T: (\rho, \theta, \phi) \mapsto (\underbrace{\rho \sin \phi \cos \theta}_{x(\rho, \theta, \phi)}, \underbrace{\rho \sin \phi \sin \theta}_{y(\rho, \theta, \phi)}, \underbrace{\rho \cos \phi}_{z(\rho, \theta, \phi)})$$

Ball of radius R in xyz:  $\{x^2 + y^2 + z^2 \leq R^2\} = W$

$$T: W^* \rightarrow W$$



$$\begin{aligned} 0 &\leq \rho \leq R \\ 0 &\leq \theta < 2\pi \\ 0 &\leq \phi \leq \pi \end{aligned}$$



$$W^* = [0, R] \times [0, 2\pi) \times [0, \pi]$$

$$\int \dots \int \rho^2$$



$$W^* = [0, R] \times [0, 2\pi) \times [0, \pi]$$

Jacobian determinant

$$\int_{[a,b]} \int_a^b$$

$$|\det DT(\rho, \theta, \phi)| = \left| \frac{\partial(x,y,z)}{\partial(\rho, \theta, \phi)} \right| = \rho^2 \sin \phi.$$

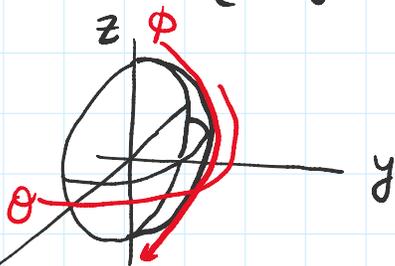
ex/ Volume of a ball of radius  $R = W$

$$\begin{aligned} \text{Vol}(W) &= \iiint_W 1 \, dx \, dy \, dz \\ &= \int_0^\pi \int_0^{2\pi} \int_0^R 1 \cdot \overset{\text{Jacobian}}{\rho^2 \sin \phi} \, d\rho \, d\theta \, d\phi \\ &= \underbrace{\int_0^\pi \sin \phi \, d\phi}_{2} \cdot \underbrace{\int_0^{2\pi} d\theta}_{2\pi} \cdot \underbrace{\int_0^R \rho^2 \, d\rho}_{\frac{R^3}{3}} = \frac{4\pi}{3} R^3. \end{aligned}$$

ex/  $\iiint_W \exp((x^2 + y^2 + z^2)^{3/2}) \, dV$

$y=0 \Leftrightarrow xz$  plane

where  $W = \{(x,y,z) : \overline{x^2 + y^2 + z^2} \leq 1 \text{ and } y \geq 0\}$



$$\left\{ \begin{array}{l} 0 \leq \rho \leq 1 \\ 0 \leq \theta \leq \pi \\ 0 \leq \phi \leq \pi \end{array} \right\} = W^*$$

$$\begin{aligned} &\iiint_W e^{(x^2 + y^2 + z^2)^{3/2}} \, dV \\ &= \iiint e^{(x(\rho, \theta, \phi)^2 + y(\rho, \theta, \phi)^2 + z(\rho, \theta, \phi)^2)^{3/2}} \, \rho^2 \, d\rho \, d\theta \, d\phi \end{aligned}$$

. |det DT(\rho, \theta, \phi)| \rho^2 d\rho d\theta d\phi

$$= \iiint_{W^*} e^{(x(\rho, \theta, \phi) + y(\rho, \theta, \phi) + z(\rho, \theta, \phi))^{1/2}} \cdot |\det DT(\rho, \theta, \phi)| d\rho d\theta d\phi$$

$$(\rho \sin \phi \cos \theta)^2 + (\rho \sin \phi \sin \theta)^2 + (\rho \cos \phi)^2$$

$$= \rho^2 \sin^2 \phi (\underbrace{\cos^2 \theta + \sin^2 \theta}_{=1}) + \rho^2 \cos^2 \phi = \rho^2$$

$$= \int_0^\pi \int_0^\pi \int_0^1 e^{(\rho^2)^{3/2}} \cdot \rho^2 \sin \phi d\rho d\theta d\phi$$

$$= \underbrace{\int_0^\pi \sin \phi d\phi}_2 \underbrace{\int_0^\pi d\theta}_\pi \int_0^1 \underbrace{e^{\rho^3} \rho^2 d\rho}_{\frac{d}{d\rho} \left( \frac{1}{3} e^{\rho^3} \right)}$$

$$= 2\pi \frac{1}{3} e^{\rho^3} \Big|_0^1 = \frac{2\pi}{3} (e-1).$$

## Change of Variables

2D Linear Transformations (Bijection/Invertible)

Polar Coordinates

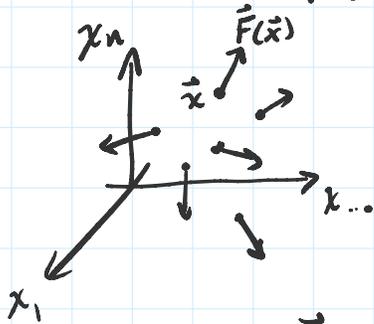
3D Cylindrical Coordinates

Spherical Coordinates

## Vector Fields (read section 4.3)

Def: A vector field on (a subset of)  $\mathbb{R}^n$  is a map  $\vec{F}: \mathbb{R}^n \rightarrow \mathbb{R}^n$ ; assigning to each  $\vec{x} \in \mathbb{R}^n$  a vector  $\vec{F}(\vec{x})$ .

$f: \mathbb{K} \rightarrow \mathbb{K}$ ; assigning to each  $x \in \mathbb{K}$  a vector  $\vec{F}(x)$ .



describe for ex,  
velocity of a fluid  
electric field

In components,  $\vec{F}(\vec{x}) = (F_1(\vec{x}), F_2(\vec{x}), \dots, F_n(\vec{x}))$

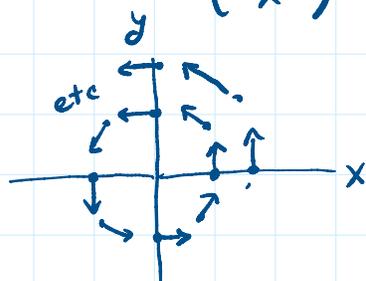
$$n=2 \quad \vec{F}(x,y) = (F_1(x,y), F_2(x,y))$$

$$n=3 \quad \vec{F}(x,y,z) = (F_1(x,y,z), F_2(x,y,z), F_3(x,y,z)).$$

(if the components are cont., diff., etc, then we say  $\vec{F}$  is as well. Generally, we'll assume continuously differentiable (C<sup>1</sup>) vector fields)

$$\text{ex/ } \vec{F}(x,y) = \underline{(-y, x)} = -y\hat{i} + x\hat{j} \quad \hat{i} = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$= \begin{pmatrix} -y \\ x \end{pmatrix} \quad \hat{j} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$



$$\vec{F}(1,0) = (0,1)$$

Important class of vector fields

Gradient Vector Fields

$\mathbb{R}^n$   
U

Recall for a differentiable function  $f: A \rightarrow \mathbb{R}$

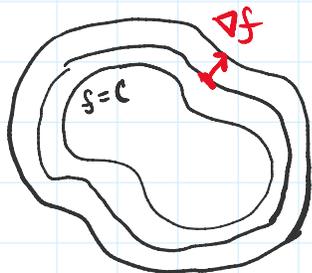
$$\nabla f(\vec{x}) = \left( \frac{\partial f}{\partial x^1}(\vec{x}), \dots, \frac{\partial f}{\partial x^n}(\vec{x}) \right)$$

$$n=3 \quad \nabla f(x,y,z) = \left( \frac{\partial f}{\partial x}(x,y,z), \frac{\partial f}{\partial y}(x,y,z), \frac{\partial f}{\partial z}(x,y,z) \right)$$

$$n=3 \quad \nabla f(x, y, z) = \left( \frac{\partial f}{\partial x}(x, y, z), \frac{\partial f}{\partial y}(x, y, z), \frac{\partial f}{\partial z}(x, y, z) \right)$$

Important?

• Optimization



gradient points in steepest ascent.

• Conservation of Energy

In physics, a force is called conservative

if  $\vec{F} = -\nabla V$  ↪ scalar function: potential energy

Newton's 2<sup>nd</sup> law force = mass × accel.

$$m \vec{x}''(t) = \vec{F}(\vec{x}(t)) = -\nabla V(\vec{x}(t))$$

claim:

The energy Kinetic potential

$$E = \frac{1}{2} m \vec{x}'(t) \cdot \vec{x}'(t) + V(\vec{x}(t))$$

is conserved

pf:

$$\frac{d}{dt} E = m \vec{x}'(t) \cdot \vec{x}''(t) + \nabla V(\vec{x}(t)) \cdot \vec{x}'(t)$$

$$= \vec{x}'(t) \cdot \underbrace{\left( m \vec{x}''(t) + \nabla V(\vec{x}(t)) \right)}_{=0} = 0$$