

Solutions/Hints to Practice Problems

for Midterm Exam 1. (Math 18, Spring 2017)

1. Yes $x_3 = 0, x_2 = 4, x_1 = -1 - 5 \cdot 4 = -21$.

2.
$$\begin{bmatrix} 1 & h & 2 \\ 4 & 8 & k \end{bmatrix} \sim \begin{bmatrix} 1 & h & 2 \\ 0 & 8-4h & k-8 \end{bmatrix}$$

(a) no sol'n $8-4h=0, k-8 \neq 0$ i.e. $h=2, k \neq 8$

(b) $8-4h \neq 0$ $h \neq 2$ — one and only one sol'n.

(c) infinitely many sol'n: $8-4h=0, k-8=0$
 $h=2, k=8$

3.
$$\begin{bmatrix} 1 & 0 & -2 & 9 \\ 0 & 1 & 1 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & 9 \\ 0 & 3 & -6 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & 9 \\ 0 & 1 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 5 \\ 0 & 1 & -2 \end{bmatrix}$$

$x_1 = 5, x_2 = -2$ $x_1 = 9 + 2x_3, x_2 = 3 - x_3$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 9+2x_3 \\ 3-x_3 \\ x_3 \end{bmatrix} = \begin{bmatrix} 9 \\ 3 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} \quad x_3 = \text{free variable}$$

4.
$$\begin{bmatrix} 1 & 5 & -3 & 0 \\ 1 & -1 & 1 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & 5 & -3 & 0 \\ 0 & -6 & 4 & -2 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 5 & -3 & 0 \\ 0 & 1 & -\frac{2}{3} & \frac{1}{3} \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & \frac{1}{3} & -\frac{5}{3} \\ 0 & 1 & -\frac{2}{3} & \frac{1}{3} \end{bmatrix}$$

$x_1 = -\frac{5}{3} - \frac{1}{3}x_3$
 $x_2 = \frac{1}{3} + \frac{2}{3}x_3$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -\frac{5}{3} \\ \frac{1}{3} \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -\frac{1}{3} \\ \frac{2}{3} \\ 1 \end{bmatrix}$$

5.
$$A = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Idea: $A = \begin{bmatrix} a & b & c \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$ $a \cdot 2 + b(-1) + c \cdot 2 = 0$.
 Many choices of a, b, c .

$$6. \quad x_1 \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} + x_3 \begin{bmatrix} 5 \\ -6 \\ 8 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 6 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & 5 & 2 \\ -2 & 1 & -6 & -1 \\ 0 & 2 & 8 & 6 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 5 & 2 \\ 0 & 1 & 4 & 3 \\ 0 & 2 & 8 & 6 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 5 & 2 \\ 0 & 1 & 4 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Yes many sol's of x_1, x_2, x_3 .

$$x_1 = 2 - 5x_3 \quad \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -5 \\ -4 \\ 1 \end{bmatrix}$$

$$x_2 = 3 - 4x_3$$

7. ~~No.~~ Yes.

$$8. \quad \begin{bmatrix} 2 & 0 & 3 \\ -1 & 1 & -2 \\ 3 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} -1 & 1 & -2 \\ 2 & 0 & 3 \\ 3 & 1 & 0 \end{bmatrix} \sim \begin{bmatrix} -1 & 1 & -2 \\ 0 & 2 & -1 \\ 0 & 4 & -6 \end{bmatrix}$$

$\sim \begin{bmatrix} -1 & 1 & -2 \\ 0 & 2 & -1 \\ 0 & 0 & -4 \end{bmatrix}$ Yes, since these three vectors in \mathbb{R}^3 are L.I.

$$9. \quad x_1 \begin{bmatrix} -3 \\ 1 \\ 0 \end{bmatrix} + x_2 \begin{bmatrix} -5 \\ 4 \\ 7 \end{bmatrix} + x_3 \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix} = \begin{bmatrix} -4 \\ 3 \\ h \end{bmatrix}$$

$$\begin{bmatrix} -3 & -5 & 1 & -4 \\ 1 & 4 & -1 & 3 \\ 0 & 7 & -2 & h \end{bmatrix} \sim \begin{bmatrix} 1 & 4 & -1 & 3 \\ -3 & -5 & 1 & -4 \\ 0 & 7 & -2 & h \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 4 & -1 & 3 \\ 0 & 7 & -2 & 5 \\ 0 & 7 & -2 & h \end{bmatrix} \sim \begin{bmatrix} 1 & 4 & -1 & 3 \\ 0 & 7 & -2 & 5 \\ 0 & 0 & 0 & h-5 \end{bmatrix}$$

$h = 5$

10. Yes. $c_1 \vec{u}_1 + \dots + c_5 \vec{u}_5 = \vec{0}$ c_1, \dots, c_5 : not all 0.
 $\Rightarrow c_1 \vec{u}_1 + \dots + c_5 \vec{u}_5 + 0 \vec{u}_6 + \dots + 0 \vec{u}_{10} = \vec{0}$
↙ ↘
 not all 0.

11. Yes. More unknowns, less equations.

$$12. \begin{bmatrix} 1 & -3 & 2 & 0 \\ -2 & 7 & 1 & 0 \\ -4 & 6 & h & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -3 & 2 & 0 \\ 0 & 1 & 5 & 0 \\ 0 & -6 & 8+h & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -3 & 2 & 0 \\ 0 & 1 & 5 & 0 \\ 0 & 0 & 38+h & 0 \end{bmatrix}$$

$38+h=0 \implies \boxed{h=-38}$

13. If $\vec{u}_1, \vec{u}_2, \vec{u}_3$ are L.D., then there are numbers c_1, c_2, c_3 , not all 0, such that $c_1\vec{u}_1 + c_2\vec{u}_2 + c_3\vec{u}_3 = \vec{0}$.

Let's say, $c_1 \neq 0$, then $\vec{u}_1 = (-\frac{c_2}{c_1})\vec{u}_2 + (-\frac{c_3}{c_1})\vec{u}_3$.
So, \vec{u}_1 is a L.C. of \vec{u}_2, \vec{u}_3 .

If, say, \vec{u}_1 is a L.C. of \vec{u}_2, \vec{u}_3 , $\vec{u}_1 = a_2\vec{u}_2 + a_3\vec{u}_3$,
then $\vec{u}_1 - a_2\vec{u}_2 - a_3\vec{u}_3 = \vec{0}$, $1, -a_2, -a_3$ are not all 0. So, $\vec{u}_1, \vec{u}_2, \vec{u}_3$ are L.D.

14. No $T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = (3, 0) \neq (6, 0)$.

15. No. The term x_1x_2 is not linear in x_1, x_2 .

Let $\vec{x} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$, $c=2$. $c\vec{x} = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$

$$T(c\vec{x}) = T\left(\begin{bmatrix} 2 \\ 4 \end{bmatrix}\right) = (2 \cdot 2 \cdot 2, 3 \cdot 2 - 2) = (8, 4)$$

$$cT(\vec{x}) = 2T\left(\begin{bmatrix} 1 \\ 2 \end{bmatrix}\right) = 2(2 \cdot 1 \cdot 1, 3 \cdot 1 - 1) = 2(2, 2) = (4, 4)$$

$T(c\vec{x}) \neq cT(\vec{x})$. So, not linear.

16. Yes. $T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$, $T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$. $A = \begin{bmatrix} 2 & -1 \\ -1 & 3 \end{bmatrix}$.

17. If $\vec{u} = a\vec{u}_1 + b\vec{u}_2$ is in the span of $\{\vec{u}_1, \vec{u}_2\}$,
then $T(\vec{u}) = aT(\vec{u}_1) + bT(\vec{u}_2) = a\vec{0} + b\vec{0} = \vec{0}$.

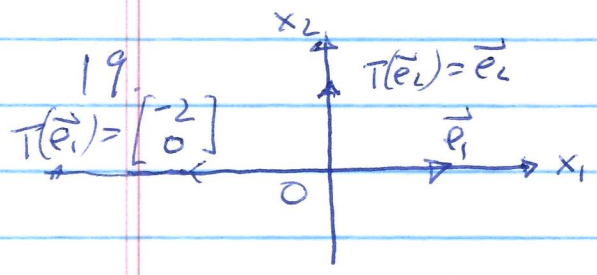
18. $x_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \Rightarrow x_1 = \frac{1}{2}, x_2 = \frac{1}{2}$

$T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \frac{1}{2} T\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) + \frac{1}{2} T\left(\begin{bmatrix} 1 \\ -1 \end{bmatrix}\right) = \frac{1}{2} \begin{bmatrix} 3 \\ 0 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{5}{2} \\ \frac{1}{2} \end{bmatrix}$

$x_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} + x_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \Rightarrow x_1 = \frac{1}{2}, x_2 = -\frac{1}{2}$

$T\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}\right) = \frac{1}{2} T\left(\begin{bmatrix} 1 \\ 1 \end{bmatrix}\right) - \frac{1}{2} T\left(\begin{bmatrix} 1 \\ -1 \end{bmatrix}\right) = \frac{1}{2} \begin{bmatrix} 3 \\ 0 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}$

So, $A = [T(\vec{e}_1), T(\vec{e}_2)] = \begin{bmatrix} \frac{5}{2} & \frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} \end{bmatrix}$



$A = \begin{bmatrix} -2 & 0 \\ 0 & 1 \end{bmatrix}$

20. $A\vec{x} = \vec{0} \Rightarrow \begin{bmatrix} 5 & -4 & 5 & 0 \\ 1 & -2 & -1 & 0 \\ -1 & 5 & 6 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & -1 & 0 \\ 5 & -4 & 5 & 0 \\ -1 & 5 & 6 & 0 \end{bmatrix}$

$\sim \begin{bmatrix} 1 & -2 & -1 & 0 \\ 0 & 6 & 10 & 0 \\ 0 & 3 & 5 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & -1 & 0 \\ 0 & 6 & 10 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ infinitely many solns. (nonzero soln)

Not one-to-one.

$A\vec{x} = \vec{b} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} \Rightarrow \begin{bmatrix} 5 & -4 & 5 & b_1 \\ 1 & -2 & -1 & b_2 \\ -1 & 5 & 6 & b_3 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & -1 & b_2 \\ 5 & -4 & 5 & b_1 \\ -1 & 5 & 6 & b_3 \end{bmatrix}$

$\sim \begin{bmatrix} 1 & -2 & -1 & b_2 \\ 0 & 6 & 10 & 5b_2 + b_1 \\ 0 & 3 & 5 & b_2 + b_3 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 & -1 & b_2 \\ 0 & 3 & 5 & b_2 + b_3 \\ 0 & 6 & 10 & 5b_2 + b_1 \end{bmatrix}$

$\sim \begin{bmatrix} 1 & -2 & -1 & b_2 \\ 0 & 3 & 5 & b_2 + b_3 \\ 0 & 0 & 0 & 3b_2 + b_1 - b_3 \end{bmatrix}$ No soln if $3b_2 + b_1 - b_3 \neq 0$. So, not onto.

$b_1 = 1, b_2 = -1, b_3 = 0$. $3b_2 + b_1 - b_3 = -3 + 1 = -2 \neq 0$. So, not in the range of T.

21. No. $T(x) = \begin{bmatrix} a_1 \\ a_2 \end{bmatrix} (x) = \begin{bmatrix} a_1 x \\ a_2 x \end{bmatrix}$

$\frac{a_1 x}{a_2 x} = \frac{a_1}{a_2}$ fixed, but \mathbb{R}^2 -vectors $\begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 1 \end{bmatrix}$ will have $\frac{2}{1}, \frac{3}{1}$ different ratios.

22. $(AB)^T = B^T A^T = \begin{bmatrix} -5 & 0 & 1 \\ 1 & 3 & 0 \end{bmatrix} \begin{bmatrix} 0 & 2 & 1 \\ -1 & 1 & 0 \\ 3 & -2 & 2 \end{bmatrix} = \begin{bmatrix} 3 & -12 & -3 \\ -3 & 5 & 1 \end{bmatrix}$

$-3B + 2C = -3 \begin{bmatrix} -5 & 1 \\ 0 & 3 \\ 1 & 0 \end{bmatrix} + 2 \begin{bmatrix} 4 & -1 \\ 1 & 3 \\ -3 & -4 \end{bmatrix} = \begin{bmatrix} 23 & -5 \\ 2 & -3 \\ -9 & -8 \end{bmatrix}$

23. $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ $B = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$.

24. $A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ $B = \begin{bmatrix} 0 & 1 \\ 0 & -1 \end{bmatrix}$ $AB = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = \mathbf{0}$ $A \neq \mathbf{0}, B \neq \mathbf{0}$

The 2×2 zero matrix.

25. $A^{-1} = \frac{1}{-2} \begin{bmatrix} 4 & -2 \\ -3 & 1 \end{bmatrix} = \begin{bmatrix} -2 & 1 \\ \frac{3}{2} & -\frac{1}{2} \end{bmatrix}$.

26. $[A \ I] = \begin{bmatrix} -5 & -1 & 9 & 1 & 0 & 0 \\ 3 & 1 & -2 & 0 & 1 & 0 \\ 1 & 0 & 2 & 0 & 0 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 2 & 0 & 0 & 1 \\ -5 & -1 & 9 & 1 & 0 & 0 \\ 3 & 1 & -2 & 0 & 1 & 0 \end{bmatrix}$

$\sim \begin{bmatrix} 1 & 0 & 2 & 0 & 0 & 1 \\ 0 & -1 & 14 & 1 & 0 & 5 \\ 0 & 1 & -8 & 0 & 1 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 2 & 0 & 0 & 1 \\ 0 & 1 & -8 & 0 & 1 & -3 \\ 0 & -1 & 14 & 1 & 0 & 5 \end{bmatrix}$

$\sim \begin{bmatrix} 1 & 0 & 2 & 0 & 0 & 1 \\ 0 & 1 & -8 & 0 & 1 & -3 \\ 0 & 0 & 6 & 1 & 1 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 2 & 0 & 0 & 1 \\ 0 & 1 & -8 & 0 & 1 & -3 \\ 0 & 0 & 1 & \frac{1}{6} & \frac{1}{6} & \frac{1}{3} \end{bmatrix}$

$\sim \begin{bmatrix} 1 & 0 & 0 & -\frac{1}{3} & -\frac{1}{3} & \frac{1}{3} \\ 0 & 1 & 0 & \frac{4}{3} & \frac{2}{3} & -\frac{1}{3} \\ 0 & 0 & 1 & \frac{1}{6} & \frac{1}{6} & \frac{1}{3} \end{bmatrix}$ $A^{-1} = \begin{bmatrix} -\frac{1}{3} & -\frac{1}{3} & \frac{1}{3} \\ \frac{4}{3} & \frac{2}{3} & -\frac{1}{3} \\ \frac{1}{6} & \frac{1}{6} & \frac{1}{3} \end{bmatrix}$

27. $E_1 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$, $E_1^{-1} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$.

$E_2 = \begin{bmatrix} \frac{1}{2} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$, $E_2^{-1} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$E_3 = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$, $E_3^{-1} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$.