

Lecture 1d, 4/22/2022

○ (Continuous) OT: Monge's formulation

○ (Continuous) OT: Kantorovich's formulation

Monge's formulation

Assume:

○ $(X, \mathcal{F}), (Y, \mathcal{G})$: measurable spaces

$(X \times Y, \mathcal{F} \otimes \mathcal{G})$: the product measure space

○ $\mathcal{P}(X) = \mathcal{P}(X, \mathcal{F}), \mathcal{P}(Y) = \mathcal{P}(Y, \mathcal{G})$: spaces of probability measures

○ $c: X \times Y \rightarrow [0, \infty]$ measurable

○ $\forall \mu \in \mathcal{P}(X) \quad \forall \nu \in \mathcal{P}(Y)$:

$$\mathcal{G}(\mu, \nu) = \{T: X \rightarrow Y: \text{measurable}, T\# \mu = \nu\}$$

Define the Monge cost functional $E_M: \mathcal{G}(\mu, \nu) \rightarrow [0, \infty]$

$$E_M[T] = \int_X c(x, T(x)) d\mu(x) \quad \forall T \in \mathcal{G}(\mu, \nu).$$

Monge's OT problem $\min_{T \in \mathcal{G}(\mu, \nu)} E_M[T].$

If $\hat{T} = \arg \min_{T \in \mathcal{G}(\mu, \nu)} E_M[\cdot]$ exists, then \hat{T} is called an optimal (transport) map.

Recall (Pushforward measure): $T\# \mu = \mu \circ T^{-1}: \mathcal{G} \rightarrow \mathcal{F}$.

$$(T\# \mu)(A) = \mu(T^{-1}(A)), \quad \forall A \in \mathcal{F}.$$

T is a random variable $\Rightarrow \nu = T\# \mu$ is the distribution of T , the law of T , w.r.t. the prob. space (X, \mathcal{F}, μ) .

Kantorovich's formulation Denote

$$\mathcal{P}(X \times Y) = \{ \text{probability measures on } (X \times Y, \mathcal{F} \otimes \mathcal{G}) \}.$$

X-projection: $\pi^X: X \times Y \rightarrow X, \quad \pi^X(x, y) = x, \quad \forall (x, y) \in X \times Y.$

Y-projection: $\pi^Y: X \times Y \rightarrow Y, \quad \pi^Y(x, y) = y, \quad \forall (x, y) \in X \times Y.$

If $\gamma \in \mathcal{P}(X \times Y)$ then $\pi_{\#}^X \gamma \in \mathcal{P}(X)$ and $\pi_{\#}^Y \gamma \in \mathcal{P}(Y)$.

They are marginal probability measures.

Let $\mu \in \mathcal{P}(X), \nu \in \mathcal{P}(Y)$. Define

$$\mathcal{A}(\mu, \nu) = \{ \gamma \in \mathcal{P}(X \times Y) : \pi_{\#}^X \gamma = \mu, \pi_{\#}^Y \gamma = \nu \}.$$

Define Kantorovich's cost functional $E_K: \mathcal{A}(\mu, \nu) \rightarrow [0, \infty]$

$$E_K[\gamma] = \int_{X \times Y} c(x, y) d\gamma(x, y), \quad \gamma \in \mathcal{A}(\mu, \nu).$$

Kantorovich's OT problem: $\min_{\gamma \in \mathcal{A}(\mu, \nu)} E_K[\gamma].$

Call $\hat{\gamma} = \arg \min_{\gamma \in \mathcal{A}(\mu, \nu)} E_K[\gamma]$, if exists, an optimal (transport) plan.

Basic questions Structure / properties of $\mathcal{P}(\mu, \nu)$ and $\mathcal{A}(\mu, \nu)$; existence, uniqueness, and characterization of optimal maps / plans; duality; Wasserstein metric and its convergence properties, related gradient flows; etc.

Assumptions Unless otherwise stated, we always

assume : both X, Y : Polish spaces: complete + separable metric spaces (e.g. $\mathbb{R}^d, L^p, W^{k,p}$ $1 \leq p < \infty$), $\mathcal{F}_X = \mathcal{B}_X, \mathcal{G} = \mathcal{B}_Y$: Borel σ -algebras.

○ In the case $X=Y$, we often consider $C(x, y) = d(x, y)$ or $d(x, y)^p$ ($1 \leq p < \infty$), where $d(\cdot, \cdot)$ is the metric of d .

○ Sometimes, we shall assume that X and Y are locally compact.

○ Even more often, we assume that $X=Y=\mathbb{R}^d$, $\mathcal{F} = \mathcal{G} = \text{Lebesgue } \sigma\text{-algebra}$.

Examples ○ The discrete OT (M or K version) is a special case of (general, continuous) OT.

$X = \{x_1, \dots, x_m\}$ and $Y = \{y_1, \dots, y_n\}$.

$\mathcal{F} = \{\text{all subsets of } X\}, \mathcal{G} = \{\text{all subsets of } Y\}$

$\mu \in P(X) \Leftrightarrow a \in P_m, \nu \in P(Y) \Leftrightarrow b \in P_n, a_i = \mu(\{x_i\}), b_j = \nu(\{y_j\})$

$C: X \times Y \rightarrow [0, \infty) \Leftrightarrow C = [C_{ij}] \in \mathbb{R}^{m \times n}, C \geq 0, C_{ij} = C(x_i, y_j)$.

$J(a, \nu) \Leftrightarrow J(a, b), T: X \rightarrow Y$.

$T \in \mathcal{G}(a, b) \Leftrightarrow b_j = \sum_{i: T(x_i) = y_j} a_i \quad \forall j \Leftrightarrow \nu(\{y_j\}) = \mu(T^{-1}\{y_j\}) \quad \forall j$
 $\Leftrightarrow \nu = T \# \mu \Leftrightarrow T \in \mathcal{G}(\mu, \nu)$

$$\begin{aligned} E_M[T] &= \int_X C(x, T(x)) d\mu(x) = \sum_{i=1}^m C(x_i, T(x_i)) d\mu(x_i) \\ &= \sum_{i=1}^m \int_{\{x_i\}} C(x_i, T(x_i)) d\mu = \sum_{i=1}^m C(x_i, T(x_i)) \mu(\{x_i\}) \\ &= \sum_{i=1}^m a_i C(x_i, T(x_i)), \text{ where } a_i = \mu(\{x_i\}) \quad \forall i. \\ &= E_M^{\text{disc}}[T]. \end{aligned}$$

Now, $P \in \mathcal{A}(a, b) \iff \gamma \in \mathcal{A}(\mu, \nu)$. $\gamma(\{(x_i, y_j)\}) = P_{ij}$.

$$E_K[\gamma] = \int_{X \times Y} c(x, y) d\gamma(x, y) = \sum_{i,j} \int_{\{(x_i, y_j)\}} c(x, y) d\gamma(x, y)$$

$$= \sum_{i,j} c(x_i, y_j) \gamma(\{(x_i, y_j)\}) = \sum_{i,j} C_{ij} P_{ij} = \langle C, P \rangle = F_K^{disc}[P].$$

$\odot (X, \mathcal{F}), (Y, \mathcal{G})$: measurable spaces, $\mu \in \mathcal{P}(X)$, $\nu \in \mathcal{P}(Y)$.
 $\nu = \delta_{y_0}$. $T \in \mathcal{T}(\mu, \nu) \iff \mu(T^{-1}(B)) = \nu(B) = \begin{cases} 1 & \text{if } y_0 \in B, \\ 0 & \text{if } y_0 \notin B. \end{cases}$

clearly, $y_0 \in \text{Range}(T)$ i.e., $\exists x_0 \in X$ s.t. $T(x_0) = y_0$.
Otherwise, $y_0 \notin \text{Range}(T) =: B \subseteq Y$. $T \# \mu(B) = \mu(T^{-1}(B))$
 $= \mu(X) = 1$, and $\nu(B) = \delta_{y_0}(B) = 0$, contradicting $T \# \mu = \nu$.

Now, assume $y_0 \in \text{Range}(T)$. Denote $A_{y_0} = \{x \in X : T(x) \neq y_0\}$. Then, $T \# \mu = \delta_{y_0} \iff \mu(T^{-1}(A_{y_0})) = 0$. Thus

$$E_M[T] = \int_X c(x, T(x)) d\mu(x) = \int_{A_{y_0}} + \int_{X \setminus A_{y_0}} = \int_{X \setminus A_{y_0}} c(x, y_0) d\mu(x) = \int_X c(x, y_0) d\mu(x).$$

$$= \int_{\{x \in X : T(x) = y_0\}} c(x, T(x)) d\mu(x) = \int_{T^{-1}(\{y_0\})} c(x, y_0) d\mu(x) = \int_X c(x, y_0) d\mu(x).$$

Let $\mu \in \mathcal{P}(X)$ and $\nu = \delta_{y_0}$ with $y_0 \in Y$. If $\gamma \in \mathcal{A}(\mu, \nu)$, then
 $\gamma = \mu \times \delta_{y_0}$, i.e., $\gamma(A \times B) = \mu(A) \delta_{y_0}(B) \forall A \in \mathcal{B}(X), B \in \mathcal{B}(Y)$.
In fact, if $y_0 \notin B$, then $0 \leq \gamma(A \times B) \leq \gamma(X \times B) = \delta_{y_0}(B) = 0$,
hence $\gamma(A \times B) = \mu(A) \nu(B) = 0$. If $y_0 \in B$ then $y_0 \notin Y \setminus B$.
Hence $\gamma(A \times Y) - \gamma(A \times B) = \gamma(A \times (Y \setminus B)) = 0$, i.e., $\gamma(A \times B) = \gamma(A \times Y) = \mu(A) \nu(Y) = \mu(A) \nu(B)$ as $\nu(B) = \delta_{y_0}(B) = 1$. Now,

$$E_K[\gamma] = \int_{X \times Y} c(x, y) d\gamma(x, y) = \int_{X \times Y} c(x, y) d(\mu \times \delta_{y_0})(x, y)$$

$$= \int_X \left(\int_Y c(x, y) d\delta_{y_0}(y) \right) d\mu(x) = \int_X c(x, y_0) d\mu(x) = E_M[T].$$

So, if $\nu = \delta_{y_0}$ for some $y_0 \in Y$, and $\mu \in \mathcal{P}(X)$, then $E_K[\gamma] = E_M[T]$ for any $\gamma \in \mathcal{A}(\mu, \nu)$ and any $T \in \mathcal{T}(\mu, \nu)$.

Monge vs. Kantorovich

- $\mathcal{G}(\mu, \nu) = \emptyset$: Possible, e.g., discrete OT.

In general, let $\mu = \delta_{x_0}$ for some $x_0 \in X$. Suppose $T: X \rightarrow Y$ is measurable. Then $T\# \mu = \delta_{T(x_0)}$. In fact, let $B \in \mathcal{Q}$. $T(x_0) \in B \iff x_0 \in T^{-1}(B)$. Hence, $(T\# \mu)(B) = \mu(T^{-1}(B)) = \begin{cases} 1 & \text{if } x_0 \in T^{-1}(B) \\ 0 & \text{if } x_0 \notin T^{-1}(B) \end{cases} = \begin{cases} 1 & T(x_0) \in B \\ 0 & T(x_0) \notin B \end{cases} = \delta_{T(x_0)}(B)$. Thus, if $\mu = \delta_{x_0}$, unless $\nu = \delta_{y_0}$ for some $y_0 \in Y$, the set $\mathcal{G}(\mu, \nu) = \emptyset$.

$\mathcal{A}(\mu, \nu) \neq \emptyset$ as $\mu \times \nu \in \mathcal{A}(\mu, \nu)$.

Both $\mathcal{G}(\mu, \nu)$ and $\mathcal{A}(\mu, \nu)$ are convex.

- $\gamma \mapsto E_K[\gamma]$ is linear.

$T \mapsto E_M[T]$ is (in general) non-linear.

- K-OT is a relaxation of M-OT.

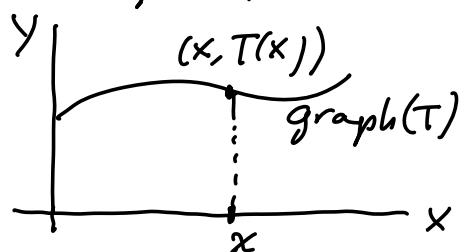
Let $T \in \mathcal{G}(\mu, \nu)$. Let $\gamma_T = (\text{Id}_X \times T)\# \mu$. Here $\text{Id}_X \times T: X \rightarrow X \times Y$ is defined by $(\text{Id}_X \times T)(x) = (x, T(x)) \forall x$. $\text{Id}_X \times T$ is measurable. Moreover,

$$\gamma_T(X \times Y) = \mu((\text{Id}_X \times T)^{-1}(X \times Y)) = \mu(X) = 1.$$

Hence $\gamma_T \in \mathcal{P}(X \times Y)$. Now,

$$\pi^X \# \gamma_T = \pi^X((\text{Id}_X \times T)\# \mu)$$

$$= ((\text{Id}_X \times T)\# \mu) \circ (\pi^X)^{-1} = \mu \circ (\text{Id}_X \times T)^{-1} \circ (\pi^X)^{-1}$$



$$= \mu \circ (\pi^Y \circ \text{Id}_{XT})^{-1} = \mu \circ (\text{Id})^{-1} = \mu.$$

$$\pi_{\#}^Y \gamma_T = \pi_{\#}^Y ((\text{Id}_{XT})_{\#} \mu) = ((\text{Id}_{XT})_{\#} \mu) \circ (\pi^Y)^{-1}$$

$$= \mu \circ (\text{Id}_{XT})^{-1} \circ (\pi^Y)^{-1} = \mu \circ (\pi^Y \circ (\text{Id}_{XT}))^{-1} = \mu \circ T^{-1} = T \# \mu = \nu.$$

Hence, $\gamma_T \in \mathcal{A}(\mu, \nu)$. Now, by the change of variable formula (see next lecture),

$$\begin{aligned} E_K[\gamma_T] &= \int_{X \times Y} c(x, y) d\gamma_T(x, y) = \int_X c \circ (\text{Id}_{XT}) d\mu \\ &= \int_X c(x, T(x)) d\mu(x) = E_M[T]. \end{aligned}$$

So, in general, $\inf_{\mathcal{G}(\mu, \nu)} E_M[\cdot] \geq \inf_{\mathcal{A}(\mu, \nu)} E_K[\cdot]$.

• Note γ_T is the measure on $(X \times Y, \mathcal{F} \otimes \mathcal{G})$ defined by

$$\int_{X \times Y} s(x, y) d\gamma_T(x, y) = \int_X s(x, T(x)) d\mu(x).$$

for any $s: X \times Y \rightarrow [0, \infty]$ measurable. [Need proper structural assumptions on $X, Y, \mathcal{F}, \mathcal{G}$.]

• $X=Y$: Polish space, $x_0, y_0 \in X$, $\mu=\delta_{x_0}$, $\nu=\delta_{y_0}$, $c(x, y)=d(x, y)$.

$$\begin{aligned} T \in \mathcal{G}(\mu, \nu) &\iff \mu \circ T^{-1} = \nu \iff \forall B \subseteq X=Y: (\mu \circ T^{-1})(B) = \nu(B) \\ &\iff \delta_{x_0}(T^{-1}(B)) = \delta_{y_0}(B) = \begin{cases} 1 & \text{if } y_0 \in B \\ 0 & \text{if } y_0 \notin B \end{cases} \iff T(x_0) = y_0. \end{aligned}$$

So, $\mathcal{G}(\mu, \nu) = \{T: X \rightarrow Y \text{ measurable}, T(x_0) = y_0\}$.

Note that $T_0(x) = y_0 \quad \forall x \in X$ defines $T_0 \in \mathcal{G}(\mu, \nu)$. So, $\mathcal{G}(\mu, \nu) \neq \emptyset$. Moreover,

$$E_M[T] = \int_X d(x, T(x)) d\mu(x) = d(x_0, T(x_0)) = d(x_0, y_0).$$

In particular, $\min_{T \in \mathcal{G}(\mu, \nu)} E_M[T] = d(x_0, y_0)$.

Now, $\gamma \in \mathcal{A}(\mu, \nu) = \mathcal{A}(d_{x_0}, d_{y_0}) \iff \gamma = S_{(x_0, y_0)}$.

$$E_K[\gamma] = \int_{X \times Y} d(x, y) d\gamma_{x_0}^*(x) d\gamma_{y_0}^*(y) = d(x_0, y_0).$$

So, $\min_{\gamma \in \mathcal{A}(\mu, \nu)} E_K[\gamma] = d(x_0, y_0)$. $K=M$ in this case.

○ A related result (A Polish space is a complete and separable metric space.)

Theorem Let X, Y be Polish spaces, $\mu \in \mathcal{P}(X)$ and $\nu \in \mathcal{P}(Y)$. Suppose $\gamma \in \mathcal{A}(\mu, \nu)$, $P \subseteq X \times Y$ is a γ -measurable graph and γ is concentrated on P . Then there exists a Borel map $T \in \mathcal{G}(\mu, \nu)$ such that $\gamma = (\text{Id}_X \times T)_\# \mu$. QED

○ The following result shows the relation between the M. and K. OT problems in the continuum setting, quite different from the discrete setting. A key assumption is that $\mu \in \mathcal{P}(X)$ is μ contains no atom, $\mu(\{x\}) = 0 \forall x \in X$.

Theorem (Pratelli) Let X, Y be Polish, and $\mu \in \mathcal{P}(X)$ and $\nu \in \mathcal{P}(Y)$. Assume $C : X \times Y \rightarrow [0, \infty]$ is continuous. Assume also that μ contains no atoms. Then

$$\inf_{\mathcal{G}(\mu, \nu)} E_M[\cdot] = \inf_{\mathcal{A}(\mu, \nu)} E_K[\cdot]. \quad \underline{\text{QED}}$$