

Lecture 6. Friday, 4/8/2022

① OT: Measure-theoretical descriptions

Consider two probability spaces $(X, \mathcal{P}(X), \mu)$ and $(Y, \mathcal{P}(Y), \nu)$.

$$X = \{x_1, \dots, x_m\} \text{ and } Y = \{y_1, \dots, y_n\}.$$

$$\mathcal{P}(X) = \{\text{all subsets of } X\}, \quad \mathcal{P}(Y) = \{\text{all subsets of } Y\}.$$

$\mu: \mathcal{P}(X) \rightarrow [0, 1]$ and $\nu: \mathcal{P}(Y) \rightarrow [0, 1]$ are probability measures (additive, and the total measure = 1).

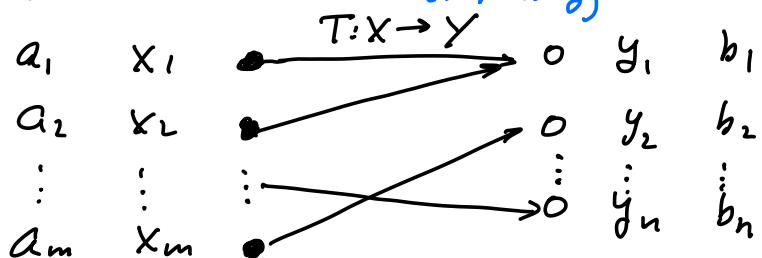
Note. μ and ν are completely determined by $\mu(\{x_i\})$ ($i=1, \dots, m$) and $\nu(\{y_j\})$ ($j=1, \dots, n$), respectively.

Denote $a = (\mu(\{x_i\})) \in \mathbb{R}^m$ and $b = (\nu(\{y_j\})) \in \mathbb{R}^n$.

Since $\mu(\{x_i\}) \geq 0 \quad \forall i$ and $\sum_{i=1}^m \mu(\{x_i\}) = \mu(X) = 1$, we have $a \in \mathbb{R}_+^m$. Similarly, $b \in \mathbb{R}_+^n$.

Recall: In Monge's formulation of the discrete OT prob., we define

$$\mathcal{G}(a, b) = \{T: X \rightarrow Y : b_j = \sum_{i: T(x_i) = y_j} a_i, \forall j \in \{1, \dots, n\}\}.$$



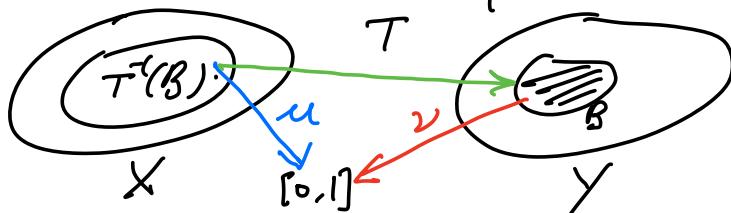
Since $a = \mu(\{x_i\})$ and $b = \nu(\{y_j\})$, the constraints $b_j = \sum_{i: T(x_i) = y_j} a_i \quad \forall j$, for $T: X \rightarrow Y$, really means

$$\nu(\{y_j\}) = \sum_{i: T(x_i) = y_j} \mu(\{x_i\}) = \mu\left(\bigcup_{i: T(x_i) = y_j} \{x_i\}\right) \quad \forall j.$$

$$\text{Fix } j: \bigcup_{i: T(x_i) = y_j} \{x_i\} = T^{-1}(\{y_j\}).$$

Recall: $T: X \rightarrow Y \Rightarrow T^{-1}: P(Y) \rightarrow P(X)$.

$T^{-1}(B) = \{\alpha \in X : T(\alpha) \in B\}$, pre-image of B .



T^{-1} is additive:
 $T^{-1}(\{y_{i_1}, \dots, y_{i_k}\}) = \bigcup_{l=1}^k T^{-1}(\{y_{i_l}\})$.

$$v(\{y_j\}) = u(T^{-1}(\{y_j\})) \quad \forall j.$$

Since both u and T^{-1} are additive (and X and Y are finite), we have

$$\forall B \subseteq Y: \quad v(B) = u(T^{-1}(B)) = (u \circ T^{-1})(B)$$

Definition Given two measurable spaces (X, \mathcal{A}) and (Y, \mathcal{B}) , μ a measure on (X, \mathcal{A}) , and $T: X \rightarrow Y$.

Define $T \# \mu: \mathcal{B} \rightarrow \mathcal{A}$ by $T \# \mu(B) = (\mu \circ T^{-1})(B) = \mu(T^{-1}(B))$. $\forall B \in \mathcal{B}$, i.e. $T \# \mu = \mu \circ T^{-1}$.

One can verify that $T \# \mu$ is a measure on (Y, \mathcal{B}) . Call $T \# \mu = \mu \circ T^{-1}$ the push-forward measure.

Denote $\mathcal{M}(X) = \mathcal{M}(X, \mathcal{A})$ and $\mathcal{M}(Y) = \mathcal{M}(Y, \mathcal{B})$ the sets of all measures on (X, \mathcal{A}) and (Y, \mathcal{B}) resp.

Call the operator $T \# : \mathcal{M}(X) \rightarrow \mathcal{M}(Y)$, $T \# \mu = \mu \circ T^{-1}$. $\forall \mu \in \mathcal{M}(X)$, the push-forward operator.

Now, back to $X = \{x_1, \dots, x_m\}$, $Y = \{y_1, \dots, y_n\}$, and μ, ν are prob. measures on $(X, P(X))$, $(Y, P(Y))$, resp.

Denote $\mathcal{G}(\mu, \nu) = \{T: X \rightarrow Y : T \# \mu = \nu\}$.

Mass[↑] conservation!

Given $C: X \times Y \rightarrow [0, \infty)$. It is completely determined by $(C(x_i, y_j))$ ($i=1, \dots, m$; $j=1, \dots, n$). Define the cost

$$E_M[T] = \int_X C(x, T(x)) d\mu(x) \quad \forall T \in \mathcal{G}(\mu, \nu)$$

Monge's OT: Find $\hat{T} \in \mathcal{G}(\mu, \nu)$ such that

$$E_M[\hat{T}] = \min_{T \in \mathcal{G}(\mu, \nu)} E_M[T].$$

$$\begin{aligned} E_M[T] &= \int_X C(x, T(x)) d\mu(x) = \int_X \sum_{i=1}^m \sum_{j=1}^n C(x, T(x_i)) \mu(\{x_i\}) \\ &= \sum_{i=1}^m \int_{\{x_i\}} C(x_i, T(x_i)) d\mu = \sum_{i=1}^m C(x_i, T(x_i)) \mu(\{x_i\}) \\ &= \sum_{i=1}^m a_i C(x_i, T(x_i)), \text{ where } a_i = \mu(\{x_i\}) \quad \forall i. \end{aligned}$$

Same as
before!

Now, consider measure-theoretic Kantorovich's OT formulation.

Given $X = \{x_1, \dots, x_m\}$, μ : a prob. measure on X ,

$Y = \{y_1, \dots, y_n\}$, ν : a prob. measure on Y .

$C: X \times Y \rightarrow [0, \infty)$: a cost function.

Denote $a = (a_i) = (\mu(\{x_i\})) \in \mathbb{P}_m$, $b = (b_j) = (\nu(\{y_j\})) \in \mathbb{P}_n$.

Recall $\mathcal{A}(a, b) = \{P = [P_{ij}] \in \mathbb{R}^{m \times n}: P \geq 0, \sum_j P_{ij} = a_i \quad \forall i, \sum_i P_{ij} = b_j \quad \forall j\}$.

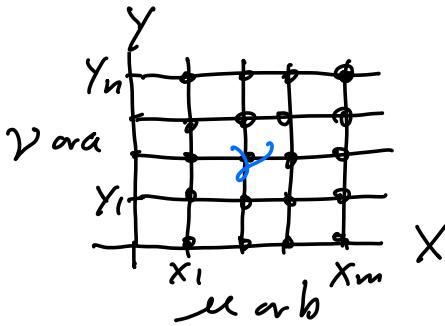
$P \in \mathcal{A}(a, b) \Rightarrow P_{ij} \geq 0, \sum_{ij} P_{ij} = 1$. So, each $P \in \mathcal{A}(a, b)$ defines a prob. measure γ on $X \times Y$ or $(X \times Y, \mathcal{P}(X \times Y))$.

$\gamma((x_i, y_j)) = P_{ij} \quad \forall i, j$. Or: for any

$S = \{(x_i, y_j) \in X \times Y : i \in I, j \in J\} \subseteq X \times Y, \quad I \subseteq \{1, \dots, m\}, J \subseteq \{1, \dots, n\}$

$$\gamma(S) = \sum_{i \in I} \sum_{j \in J} P_{ij}.$$

Row sum of $P = \alpha \Leftrightarrow \mu_i : \alpha_i = \sum_{j=1}^n p_{ij}$. i.e.,
 $\mu(\{x_i\}) = \sum_{j=1}^n \gamma((x_i, y_j)) = \gamma(\bigcup_{j=1}^n (x_i, y_j)) = \gamma(\{x_i\} \times Y)$
 Hence, for any $A \subseteq X$, $\mu(A) = \gamma(A \times Y)$. Similarly,
 $\forall B \subseteq Y$, $\nu(B) = \gamma(X \times B)$. Moreover $\gamma(A \times B) = \mu(A)\nu(B)$.



Row sum of $P = \alpha \Rightarrow \gamma|_X = \mu$
 Col. sum of $P = \beta \Rightarrow \gamma|_Y = \nu$.

Define $\pi_X : X \times Y \rightarrow X$ and $\pi_Y : X \times Y \rightarrow Y$

$$\pi_X(x, y) = x, \quad \pi_Y(x, y) = y \quad \forall (x, y) \in X \times Y$$

$A \subseteq X \Rightarrow \mu(A) = \gamma(A \times Y)$. But $A = \pi_X^{-1}(A \times Y)$. So,

$$A \times Y = \pi_X^{-1}(A), \text{ and } \mu(A) = \gamma(\pi_X^{-1}(A)) = (\pi_X)_* \gamma(A).$$

$\mu = (\pi_X)_* \gamma$ and $\nu = (\pi_Y)_* \gamma$: marginal probabilities.

Define $\mathcal{D}(\mu, \nu) = \{\text{probability measures } \gamma \text{ on } X \times Y \text{ with marginal measures on } X, Y \text{ being } \mu, \nu, \text{ resp.}\}$

Given $X = \{x_1, \dots, x_m\}$, μ : a prob. measure on X ,
 $Y = \{y_1, \dots, y_n\}$, ν : a prob. measure on Y ,
 $c : X \times Y \rightarrow [0, \infty]$: a cost function.

Define $\mathcal{D}(\mu, \nu)$ as above.

Define the cost $E_K[\gamma] = \int_{X \times Y} c(x, y) d\gamma(x, y)$.

Kantorovich's (discrete) OT prob.

$$\min_{\gamma \in \mathcal{D}(\mu, \nu)} E_K[\gamma].$$

Given $\gamma \in \mathcal{A}(\mu, \nu)$. What is the cost $E_K[\gamma]$ in terms of a and b ?

$$E_K[\gamma] = \int_{X \times Y} c(x, y) d\gamma(x, y) = \sum_{i,j} \int_{\{(x_i, y_j)\}} c(x, y) d\gamma(x, y)$$
$$= \sum_{i,j} c(x_i, y_j) \gamma(\{(x_i, y_j)\}) = \sum_{i,j} C_{ij} P_{ij} = \langle C, P \rangle, P \in \mathcal{P}(a, b).$$

Thus, the discrete OT can be formulated using measures.

- Plan:
- Regularization of discrete OT problems
 - Sinkhorn's algorithm and related topics.