

Part II. Surface Motion with Application
to Molecular Solvation, Cell Shapes,
and Cell Dynamics

[Part I: Continuum Electrostatics]

References: [1] Differential Geometry by E. Kreyszig,
Dover, 1991

[2] Differential Geometry of Curves and Surfaces,
by M. P. Do Carmo, Prentice-Hall, 1976.

[3] Surface Evolution Equations A Level Set
Approach, by Y. Giga, Birkhäuser, 2006.

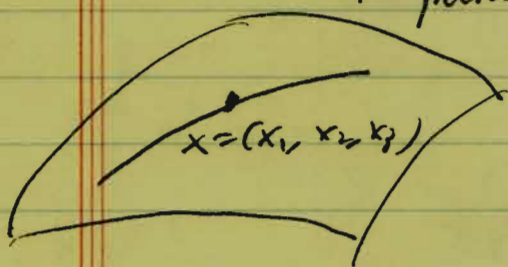
[4] Notes on Differential Geometry, by N. J. Hicks,
Van Nostrand Reinhold, Co. 1965.

- Plan:
- Basics
 - Variations of surface and volume integrals
 - Level set approach.
 - The mean curvature flow.
 - Hadwiger's Theorem. application to the calculation of solvation free energy of nonpolar systems
 - ~~Discussion~~
 - Willmore flow. bending energy
 - New models of cell shapes and cell dynamics
 - Discussions
 - The level-set method

Surface description. basic definition

parametric representation:

$$\vec{x} = \vec{x}(u^1, u^2) = (x_1(u^1, u^2), x_2(u^1, u^2), x_3(u^1, u^2))$$



$$\vec{x}_\alpha = \frac{\partial \vec{x}}{\partial u^\alpha} \quad \alpha = 1, 2$$

$$\vec{x}_{\alpha\beta} = \frac{\partial^2 \vec{x}}{\partial u^\alpha \partial u^\beta}, \quad \alpha, \beta = 1, 2$$

Jacobian $J = \begin{bmatrix} \frac{\partial x_1}{\partial u^1} & \frac{\partial x_1}{\partial u^2} \\ \frac{\partial x_2}{\partial u^1} & \frac{\partial x_2}{\partial u^2} \\ \frac{\partial x_3}{\partial u^1} & \frac{\partial x_3}{\partial u^2} \end{bmatrix} = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 \end{bmatrix} = \begin{bmatrix} \frac{\partial \vec{x}}{\partial u^1} & \frac{\partial \vec{x}}{\partial u^2} \end{bmatrix}$

$J = \frac{\partial \vec{x}}{\partial u}$

Assume: J is full-rank everywhere of a (u^1, u^2) region. i.e. $\frac{\partial \vec{x}}{\partial u^1}, \frac{\partial \vec{x}}{\partial u^2}$ are not parallel. or $\frac{\partial \vec{x}}{\partial u^1} \times \frac{\partial \vec{x}}{\partial u^2} \neq 0$.

a curve on a surface $\begin{cases} u^1 = u^1(t) \\ u^2 = u^2(t) \end{cases}$

$$\vec{x} = (x_1(u^1(t), u^2(t)), x_2(u^1(t), u^2(t)), x_3(u^1(t), u^2(t)))$$

First fundamental form

curve on a surface as above.

arc length element: ds

$$ds^2 = \frac{d\vec{x}}{dt} \cdot \frac{d\vec{x}}{dt} dt^2$$

$$= \left(\frac{\partial \vec{x}}{\partial u^1} du^1 + \frac{\partial \vec{x}}{\partial u^2} du^2 \right) \cdot \left(\frac{\partial \vec{x}}{\partial u^1} du^1 + \frac{\partial \vec{x}}{\partial u^2} du^2 \right) dt^2$$

$$= \left(\frac{\partial \vec{x}}{\partial u^1} \cdot \frac{\partial \vec{x}}{\partial u^1} \right) (du^1)^2 + 2 \frac{\partial \vec{x}}{\partial u^1} \cdot \frac{\partial \vec{x}}{\partial u^2} du^1 du^2 + \frac{\partial \vec{x}}{\partial u^2} \cdot \frac{\partial \vec{x}}{\partial u^2} (du^2)^2$$

$$= (\vec{x}_1 \cdot \vec{x}_1) (du^1)^2 + 2 \vec{x}_1 \cdot \vec{x}_2 du^1 du^2 + (\vec{x}_2 \cdot \vec{x}_2) (du^2)^2$$

Denote $g_{\alpha\beta} = \vec{x}_\alpha \cdot \vec{x}_\beta = \frac{\partial \vec{x}}{\partial u^\alpha} \cdot \frac{\partial \vec{x}}{\partial u^\beta}$ ($\alpha, \beta = 1, 2$)
 $g = \det(g_{\alpha\beta}) = g_{11}g_{22} - g_{12}^2$

Note: $g_{12} = g_{21}$

Easy to verify: $g = |\vec{x}_1 \times \vec{x}_2|^2$

$|\vec{x}_1 \times \vec{x}_2|^2 = |\vec{x}_1|^2 |\vec{x}_2|^2 \sin^2 \alpha$
 $= g_{11}g_{22}(1 - \cos^2 \alpha)$
 $= g_{11}g_{22} - (\vec{x}_1 \cdot \vec{x}_2)^2 = g$

The 1st fundamental form:

$ds^2 = g_{11}(du^1)^2 + 2g_{12}du^1du^2 + g_{22}(du^2)^2$

Gauss's notation

$ds^2 = E(du^1)^2 + 2Fdu^1du^2 + G(du^2)^2$

$E = g_{11}, F = g_{12} = g_{21}, G = g_{22}$

Always positive definite!

change of coordinates:

$u^\alpha = u^\alpha(\bar{u}^1, \bar{u}^2), \alpha = 1, 2$

Inverse: $\bar{u}^\mu = \bar{u}^\mu(u^1, u^2), \mu = 1, 2$

Relations: $(\bar{g}_{\mu\nu}) = (g_{\alpha\beta}) \frac{\partial u^\alpha}{\partial \bar{u}^\mu} \cdot \frac{\partial u^\beta}{\partial \bar{u}^\nu}$

i.e. $\bar{g}_{\mu\nu} = \sum_{\alpha, \beta=1}^2 g_{\alpha\beta} \frac{\partial u^\alpha}{\partial \bar{u}^\mu} \cdot \frac{\partial u^\beta}{\partial \bar{u}^\nu}$

Similarly, $g_{\alpha\beta} = \sum_{\mu, \nu=1}^2 \bar{g}_{\mu\nu} \frac{\partial \bar{u}^\mu}{\partial u^\alpha} \frac{\partial \bar{u}^\nu}{\partial u^\beta}$

Also, $\bar{g} = D^2 g, g = \bar{D}^2 \bar{g}$

where $\bar{g} = \det(\bar{g}_{\mu\nu}), g = \det(g_{\alpha\beta})$
 $D = \frac{\partial(u^1, u^2)}{\partial(\bar{u}^1, \bar{u}^2)}, \bar{D} = \frac{\partial(\bar{u}^1, \bar{u}^2)}{\partial(u^1, u^2)}$

or: by Lagrange's identity
 $|\vec{x}_1 \times \vec{x}_2|^2 = (\vec{x}_1 \times \vec{x}_2) \cdot (\vec{x}_1 \times \vec{x}_2)$
 $= (\vec{x}_1 \cdot \vec{x}_1)(\vec{x}_2 \cdot \vec{x}_2) - (\vec{x}_1 \cdot \vec{x}_2)^2$
 $= g_{11}g_{22} - g_{12}^2 = g$

$u = \begin{pmatrix} u^1 \\ u^2 \end{pmatrix}$

Unit normal to a surface

$$\vec{n} = \frac{\vec{x}_1 \times \vec{x}_2}{|\vec{x}_1 \times \vec{x}_2|} = \frac{\vec{x}_1 \times \vec{x}_2}{\sqrt{g}}$$

length of a curve $u^1 = u^1(t), u^2 = u^2(t)$
on a surface $\vec{x} = \vec{x}(u^1, u^2)$

$$s = \int_{t_0}^{t_1} |\dot{\vec{x}}(t)| dt = \int_{t_0}^{t_1} \sqrt{\sum_{\alpha, \beta=1}^2 \frac{du^\alpha}{dt} \frac{du^\beta}{dt} \vec{x}_\alpha \cdot \vec{x}_\beta} dt$$

Surface area

$$A = \int_U \sqrt{g} du^1 du^2$$

surface element: $dA = \sqrt{g} du^1 du^2$

Second fundamental form Curvatures

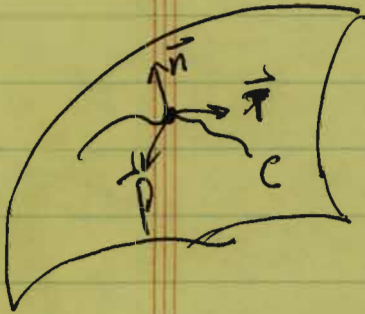
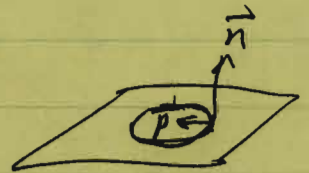
unit tangent vector $\vec{t}(s) = \dot{\vec{x}}(s)$

principal normal vector

$$\vec{p} = \frac{\dot{\vec{t}}(s)}{|\dot{\vec{t}}(s)|} = \frac{\ddot{\vec{x}}}{\kappa}$$

curvature: $\kappa = |\dot{\vec{t}}(s)|$

$$\vec{p} \cdot \vec{n} = \frac{1}{\kappa} \ddot{\vec{x}} \cdot \vec{n} = \cos \gamma$$



s: arc length
 $\kappa \vec{p} = \dot{\vec{t}} = \ddot{\vec{x}}$
 (by Frenet's)

~~Notation~~

$$\dot{\vec{x}} = \sum_{\alpha=1,2} \vec{x}_\alpha \dot{u}^\alpha$$

$$\vec{x}_\alpha \cdot \vec{n} = 0$$

$$\Rightarrow \ddot{\vec{x}} \cdot \vec{n} = \sum_{\alpha, \beta} (\dot{\vec{x}}_\alpha \cdot \vec{n}) \dot{u}^\alpha \dot{u}^\beta$$

(\therefore arc length
~~derivable~~)

Notation

$$b_{\alpha\beta} = \vec{x}_\alpha \cdot \vec{n}$$

The second fundamental form

Formulas of Frenet

$$\begin{bmatrix} \dot{\vec{t}} \\ \dot{\vec{p}} \\ \dot{\vec{b}} \end{bmatrix} = \begin{bmatrix} 0 & \kappa & 0 \\ -\kappa & 0 & \tau \\ 0 & -\tau & 0 \end{bmatrix} \begin{bmatrix} \vec{t} \\ \vec{p} \\ \vec{b} \end{bmatrix}$$

\vec{b} - binormal vector

$$\vec{b} \equiv \vec{t} \times \vec{p}$$

$$b_{11} (du^1)^2 + 2b_{12} du^1 du^2 + b_{22} (du^2)^2$$

$$L = b_{11}, \quad M = b_{12}, \quad N = b_{22}$$

$$L (du^1)^2 + 2M du^1 du^2 + N (du^2)^2$$

$$\vec{x}_2 \cdot \vec{n} = 0 \Rightarrow \frac{d}{du^\beta} \vec{x}_{\alpha\beta} \cdot \vec{n} + \vec{x}_\alpha \cdot \vec{n}_\beta = 0$$

$$\Rightarrow \boxed{b_{\alpha\beta} = -\vec{x}_\alpha \cdot \vec{n}_\beta}$$

$$\Rightarrow \boxed{d \sum_{\alpha, \beta=1}^2 b_{\alpha\beta} du^\alpha du^\beta = -d\vec{x} \cdot d\vec{n}}$$

Also, $b_{\alpha\beta} = \vec{x}_{\alpha\beta} \cdot \vec{n} = \vec{x}_{\alpha\beta} \cdot \frac{\vec{x}_1 \times \vec{x}_2}{\sqrt{g}}$

$$\boxed{b_{\alpha\beta} = \frac{1}{\sqrt{g}} |\vec{x}_1 \ \vec{x}_2 \ \vec{x}_{\alpha\beta}|}$$

Normal curvature

using $s = s(t)$:

$$k_n = \frac{\sum_{\alpha, \beta=1}^2 b_{\alpha\beta} du^\alpha du^\beta}{\sum_{\alpha, \beta=1}^2 g_{\alpha\beta} du^\alpha du^\beta}$$

$$\begin{aligned} \vec{u}^\alpha &= \frac{du^\alpha}{ds} = \frac{du^\alpha}{dt} \frac{dt}{ds} \\ \Rightarrow \vec{x} \cdot \ddot{\vec{x}} &= \sum_{\alpha, \beta} (\vec{x}_{\alpha\beta} \cdot \vec{n}) u^\alpha u^\beta \\ &= \frac{\sum_{\alpha, \beta} b_{\alpha\beta} du^\alpha du^\beta}{(ds)^2} \end{aligned}$$

$$k_n = k \cos \gamma = \ddot{\vec{x}} \cdot \vec{n} = k \vec{p} \cdot \vec{n}$$

[Depends on the curve under consideration.]

Which directions lead to max. and min. values of k_n ?

$\gamma = \langle \vec{p}, \vec{n} \rangle$
...angle.

$$\sum_{\alpha, \beta=1}^2 (b_{\alpha\beta} - k_n g_{\alpha\beta}) l^\alpha l^\beta = 0$$

where $l^\alpha = du^\alpha$ ($\alpha = 1, 2$)

Differentiate it w.r.t. l^γ , treating k_n as a constant ∇ (since $dk_n = 0$ is the necessary condition for k_n to be extremal.)

$$\sum_{\alpha, \beta=1}^2$$

$$\begin{aligned} \frac{\partial}{\partial l^\gamma} (a_{\alpha\beta} l^\alpha l^\beta) &= a_{\alpha\beta} \left(\frac{\partial l^\alpha}{\partial l^\gamma} l^\beta + l^\alpha \frac{\partial l^\beta}{\partial l^\gamma} \right) \\ &= a_{\alpha\beta} (\delta_\gamma^\alpha l^\beta + l^\alpha \delta_\gamma^\beta) = (a_{\gamma\beta} + a_{\alpha\gamma}) l^\alpha \end{aligned}$$

~~symmetry~~
 $a_{\gamma\alpha} = a_{\alpha\gamma}$

By the symmetry: $a_{\alpha\alpha} = a_{\alpha\alpha}$.

$$\sum_{\alpha=1,2} (b_{\alpha\gamma} - k_n g_{\alpha\gamma}) l^\alpha = 0 \quad \gamma = 1, 2.$$

$$\beta l = k_n G l \iff \begin{cases} (b_{11} - k_n g_{11}) l^1 + (b_{21} - k_n g_{21}) l^2 = 0 \\ (b_{12} - k_n g_{12}) l^1 + (b_{22} - k_n g_{22}) l^2 = 0 \end{cases} \iff \det(B - k_n G) = 0$$

$B = (b_{\alpha\beta}), G = (g_{\alpha\beta})$
 $k_n = \text{eigenvalues}$

Eliminate k_n :

$$\begin{vmatrix} \sum_{\alpha=1,2} g_{1\alpha} du^\alpha & \sum_{\beta=1,2} b_{1\beta} du^\beta \\ \sum_{\alpha=1,2} g_{2\alpha} du^\alpha & \sum_{\beta=1,2} b_{2\beta} du^\beta \end{vmatrix} = 0.$$

$$\iff \begin{vmatrix} (du^2)^2 & -du^1 du^2 & (du^1)^2 \\ g_{11} & g_{12} & g_{21} \\ b_{11} & b_{12} & b_{22} \end{vmatrix} = 0.$$

~~direction~~ \Rightarrow principal directions of normal curvature.

(α : curvature directions)

Thus Roots are real, the principal directions are orthogonal.

$$G^{-1} B l = k_n l, \quad l = (l^1, l^2) \neq 0.$$

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$$k_n^2 - b \left(\sum_{\alpha, \beta=1}^2 b_{\alpha\beta} g^{\alpha\beta} \right) k_n + \frac{b}{g} = 0$$

$$(g^{\alpha\beta}) = (g_{\alpha\beta})^{-1}$$

$\Rightarrow k_n = k_1, k_2$ the principal curvatures.

where $b = \det(b_{\alpha\beta}) = b_{11} b_{22} - b_{12}^2$.

Definition Mean curvature

$$H = \frac{1}{2} (k_1 + k_2) = \frac{1}{2} \sum_{\alpha, \beta=1}^2 b_{\alpha\beta} g^{\alpha\beta} = \frac{1}{2} \text{trace}(G^{-1} B) = \frac{1}{2} G^{-1} : B$$

Gaussian curvature (or total curvature)

$$K = k_1 k_2 = \frac{b}{g}$$

Euler's Theorem let α = angle between the direction at a point and the principal dir. for k_1 . Then

$$k_n = k_1 \cos^2 \alpha + k_2 \sin^2 \alpha$$

[Need to add some good examples of H, K , etc.
For instance, the surface is a (patch) of ~~shape~~ sphere, cylinder, ...]

Some parameterizations of surfaces

1. Monge (graph) parameterization

$$x_3 = h(x_1, x_2).$$

$$\vec{x} = (x_1, x_2, h(x_1, x_2)) \quad u^1 = x_1, u^2 = x_2.$$

$$\vec{x}_1 = \frac{\partial \vec{x}}{\partial x_1} = (1, 0, h_1), \quad \vec{x}_2 = \frac{\partial \vec{x}}{\partial x_2} = (0, 1, h_2)$$

$$h_\alpha = \frac{\partial h}{\partial x_\alpha}, \quad h_{\alpha\beta} = \frac{\partial^2 h}{\partial x_\alpha \partial x_\beta}$$

$$(g_{\alpha\beta}) = (\vec{x}_\alpha \cdot \vec{x}_\beta) = \begin{pmatrix} 1+h_1^2 & h_1 h_2 \\ h_1 h_2 & 1+h_2^2 \end{pmatrix}$$

$$g = \det(g_{\alpha\beta}) = 1+h_1^2+h_2^2$$

$$G^{-1} = (g_{\alpha\beta})^{-1} = (g^{\alpha\beta}) = \frac{1}{1+h_1^2+h_2^2} \begin{pmatrix} 1+h_2^2 & -h_1 h_2 \\ -h_1 h_2 & 1+h_1^2 \end{pmatrix}$$

$$\vec{x}_1 \times \vec{x}_2 = \begin{pmatrix} -h_1 \\ -h_2 \\ 1 \end{pmatrix}$$

$$\vec{n} = \frac{\vec{x}_1 \times \vec{x}_2}{\sqrt{g}} = \frac{1}{\sqrt{1+h_1^2+h_2^2}} \begin{pmatrix} -h_1 \\ -h_2 \\ 1 \end{pmatrix}$$

$$B = (b_{\alpha\beta}) = (\vec{x}_\alpha \cdot \vec{n}) = \frac{1}{\sqrt{1+h_1^2+h_2^2}} \begin{pmatrix} h_{11} & h_{12} \\ h_{12} & h_{22} \end{pmatrix}$$

Hessian of h .

Mean curvature

$$H = \frac{1}{2} G^{-1} : B = \frac{1}{2(1+h_1^2+h_2^2)^{3/2}} \begin{bmatrix} h_{11}(1+h_2^2) + h_{22}(1+h_1^2) \\ -2h_1 h_2 h_{12} \end{bmatrix}$$

$$H = \frac{1}{2} \nabla \cdot \left(\frac{\nabla h}{\sqrt{1+h_1^2+h_2^2}} \right)$$

Gaussian curvature

$$K = \frac{b}{g} = \frac{h_{11} h_{22} - h_{12}^2}{(1+h_1^2+h_2^2)^2}$$

Linearization around a flat surface

$$h = h_0 + \varepsilon \tilde{h}_1(x_1, h_1) + \dots \quad |\varepsilon| \ll 1, \quad h_0 = \text{const.}$$

$$h_\alpha = \varepsilon \tilde{h}_\alpha + \dots \quad h_{\alpha\beta} = \varepsilon \tilde{h}_{\alpha\beta} + \dots$$

$$H = H(h) = ?$$

$$1 + h_1^2 + h_2^2 = 1 + O(\varepsilon^2)$$

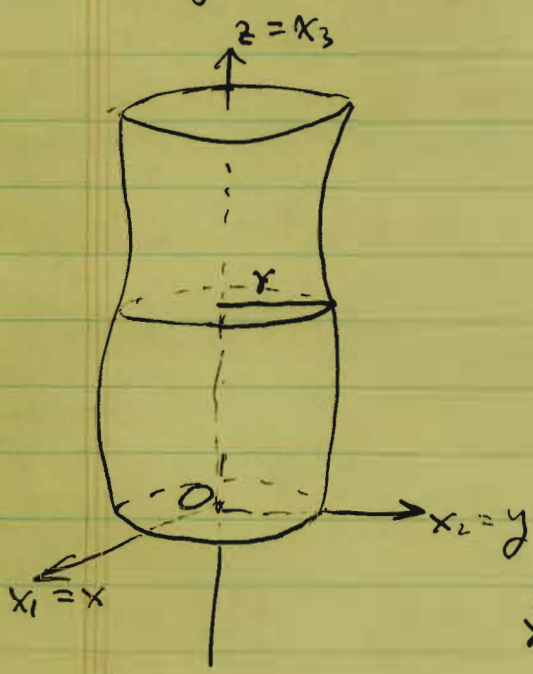
$$h_\alpha^2 = O(\varepsilon^2)$$

$$h_\alpha h_\beta \quad h_{12} = O(\varepsilon) \quad O(\varepsilon) \quad h_{12} = O(\varepsilon^2)$$

$$H = \frac{1}{2} (\tilde{h}_{11} + \tilde{h}_{22}) = \frac{1}{2} \Delta \tilde{h}$$

$$K = O(\varepsilon^2)$$

2. Cylindrically symmetric surfaces



$$\vec{x} = \vec{x}(r, \theta, z) = \vec{x}(r, \theta, z)$$

$$\vec{x} = \vec{x}(\theta, z) = \begin{bmatrix} r(z) \cos \theta \\ r(z) \sin \theta \\ z \end{bmatrix}$$

$u^1 = \theta, u^2 = z$

$$\vec{x}_1 = \begin{bmatrix} -r(z) \sin \theta \\ r(z) \cos \theta \\ 0 \end{bmatrix}$$

$$\vec{x}_2 = \begin{bmatrix} r'(z) \cos \theta \\ r'(z) \sin \theta \\ 1 \end{bmatrix}$$

$$\vec{x}_1 \times \vec{x}_2 = \begin{bmatrix} r \cos \theta \\ r \sin \theta \\ -r r' \end{bmatrix}$$

$$|\vec{x}_1 \times \vec{x}_2| = \sqrt{r^2(1+r'^2)} = r\sqrt{1+r'^2}$$

$$\vec{n} = \frac{1}{r\sqrt{1+r'^2}} \begin{bmatrix} r \cos \theta \\ r \sin \theta \\ -r r' \end{bmatrix} = \frac{1}{\sqrt{1+r'^2}} \begin{bmatrix} \cos \theta \\ \sin \theta \\ -r' \end{bmatrix}$$

$$G = (g_{\alpha\beta}) = \begin{bmatrix} r^2 & 0 \\ 0 & 1+r'^2 \end{bmatrix}$$

$$\vec{x}_{11} = \begin{bmatrix} -r \cos \theta \\ -r \sin \theta \\ 0 \end{bmatrix} \quad \vec{x}_{22} = \begin{bmatrix} r'' \cos \theta \\ r'' \sin \theta \\ 0 \end{bmatrix}$$

$$\vec{x}_{12} = \begin{bmatrix} -r' \sin \theta \\ r' \cos \theta \\ 0 \end{bmatrix}$$

$$B = (b_{\alpha\beta}) = (\vec{x}_{\alpha\beta} \cdot \vec{n}) = \frac{1}{\sqrt{1+r'^2}} \begin{bmatrix} -r & 0 \\ 0 & r'' \end{bmatrix}$$

$$G^{-1} = \begin{bmatrix} \frac{1}{r^2} & 0 \\ 0 & \frac{1}{1+r'^2} \end{bmatrix}$$

$$H = \frac{1}{2} G^{-1} : B = \frac{1}{2\sqrt{1+r'^2}} \left(-\frac{1}{r} + \frac{r''}{1+r'^2} \right)$$

$$H = \frac{1}{2\sqrt{1+r'^2}} \left(\frac{r''}{1+r'^2} - \frac{1}{r} \right)$$

$$K = \det G^{-1} \cdot \det B = \frac{r^2(1+r'^2)}{\sqrt{1+r'^2}} \frac{(-r)r''}{\sqrt{1+r'^2}} = -\frac{r^3}{\sqrt{1+r'^2}} r''$$

$$= -\frac{r''}{r(1+r'^2)^{3/2}}$$