## Longo: Math 20C - Winter 2017 Lecture Notes

## Date:

Section: §2.5 (part 2)

Topics Covered: The chain rule for multivariable functions

Multivariable Chain Rule:

Let  $f, g: \mathbb{R} \to \mathbb{R}$  be diffible forms. Then for  $\mathbb{R} \to \mathbb{R}$  is also diffible and  $(fog)'(x) = f'(g(x)) \cdot g'(x)$ . In Leibnize notation, if y = f(x) and w = g(y), we see w is a for of x and  $\frac{dw}{dx} = \left(\frac{dw}{dy}\right) \cdot \left(\frac{dx}{dx}\right)$ .  $\frac{dw}{dx} = \left(\frac{dw}{dy}\right) \cdot \left(\frac{dx}{dx}\right)$ .  $\frac{dw}{dx} = \left(\frac{dw}{dy}\right) \cdot \left(\frac{dx}{dx}\right)$ .  $\frac{dw}{dx} = \frac{dw}{dx} =$ 

Suppose w is a function of 3 variables! X, y, z. Suppose X, y, z all depend on a single variable, t. Suppose Then w is a function x y Z of t, so it makes sense to as to how w changes with respect to a change in t. It turns out  $\frac{d\omega}{dt} = \left(\frac{\partial\omega}{\partial x}\right) \left(\frac{dx}{dt}\right) + \left(\frac{\partial\omega}{\partial y}\right) \left(\frac{dy}{dt}\right) + \left(\frac{\partial\omega}{\partial x}\right) \left(\frac{dx}{dt}\right)$ 

We will discuss where this formula comes from shortly, but for now think of it as the sum of the contributions in Change Coming from the changes in each of the variables.

<u>Example</u>: A bee flies around the room. Suppose at time too, the position of the bee is given by

$$\frac{\partial}{\partial t} (t) = (t^{1}+1, t^{2}+2t, -\frac{1}{t}) \quad \text{Suppose the temperature,}$$

$$T, \text{ in Fahrahet at any point in the nom is}$$

$$\frac{\partial}{\partial t} T(x, y, z) = 10 e^{-x-2y-4t} + 80.$$

$$(1) \quad \text{After 2 seconds, what is the beis temperature.}$$

$$(2) \quad \text{How is the bees temperature changing at 2 seconds?}$$

$$(3) \quad \text{Aft the 2 second wark, the bem is at the point  $\partial(2) = (2^{1}+1, 2^{1}+2i\partial_{1}, \frac{1}{2}).$  The basis temperature is temperature is  $T(2(u)) = 10 e^{-S-24-2} + 80 = \frac{10}{e^{-71}} + 80$ 

$$(2) \quad \text{The change in the besis temperature at time t=2 is given b_{1}^{2}: (\frac{dT}{dt})|_{z=1} = (\frac{2T}{2x})|_{Z(u)} (\frac{dS}{dt}) + (\frac{2T}{2})|_{Z(u)} (\frac{dS}{dt})|_{z=1} (\frac{dT}{2x})|_{Z(u)} = (-10e^{-X-2y-4E})|_{Z(u)} = -10e^{-31}$$

$$(\frac{2T}{dt})|_{z=1} = (-10e^{-X-2y-4E})|_{Z(u)} = -20e^{-31}$$

$$(\frac{2T}{dt})|_{z=2} = (-40e^{-X-2y-4E})|_{Z(u)} = -40e^{-31}$$

$$(\frac{dX}{dt})|_{z=2} = (2L)|_{z=2} = 4$$

$$(\frac{dX}{dt})|_{z=2} = (3L^{1})|_{z=2} = 12$$$$

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All together, we get  $\binom{dT}{dt}\Big|_{t=2} = (-10e^{-31})(4) + (-20e^{-31})(12) + (-40e^{-31})(-\frac{1}{4}) = -240e^{-31}$ Where did this formula come from? Notice we could rewrite  $\frac{d\omega}{dt} = \left(\frac{\partial\omega}{\partial\lambda}\right) \left(\frac{dx}{dt}\right) + \left(\frac{\partial\omega}{\partial\gamma}\right) \left(\frac{dy}{dt}\right) + \left(\frac{\partial\omega}{\partial\tau}\right) \left(\frac{dz}{dt}\right)$ as ∇w(c(t)) • c'(t) uhere c(t)=(x(t), z(t), z(t)) Recall that  $\nabla w$  and  $\vec{c}'(t)$  are just special notations for the total derivatives [Dw] and  $[D\vec{c}]$ , So we could further rewrite the above equation as  $\left[ D(\omega \cdot \vec{z}) \right]_{(t)} = \left[ D_{\omega} \right] (\vec{z}(t)) \left[ D_{\omega} \vec{z} \right] (t)$ This is a matrix This is 3x1 matrix 1x3 matrix mult. makes sense here The (total) derivative of w.2 at t is the total cherivative of w, evaluated at  $\vec{c}(t)$  times the (total) derivative of 2 evaluated at t. This is essentially the same as in single variable, except now you multiply matrices. More generally.  $\begin{array}{c} f: \mathbb{R}^{n} \to \mathbb{R}^{m} \\ g: \mathbb{R}^{p} \to \mathbb{R}^{n} \end{array}$ Theorem: (Chain Rule): Suppose are both diff'ble. Then

$$(f \cdot y)(\vec{x}) = f(y(\vec{x})) \quad i: a f cn from  $\mathbb{R}^{p}$  to  $\mathbb{R}^{n}$   

$$\mathbb{R}^{p} \qquad \mathbb{R}^{n} \qquad \mathbb{R}^{n}$$

$$f \cdot y$$
If  $\vec{x}$  is a p-dim. vector,  $f(\vec{x})$  is m-dim. so it makes  
scase to play it into  $f$ .  $f(y(\vec{x}) = [Df](q(\vec{x}))[Dg](\vec{x})$ .  
Chind  $[D(f \circ g_{i})](\vec{x}) = [Df](q(\vec{x}))[Dg](\vec{x})$ .  

$$= \underbrace{\mathsf{X} \alpha \mathsf{up} \mathsf{k}:}_{n \neq 1} = \underbrace{\mathsf{R}^{2} \to \mathbb{R}^{2}}_{n \neq 1} \quad y(r, \mathfrak{G}) = (r \cos \theta, r \sin \theta)$$

$$f : \mathbb{R}^{2} \to \mathbb{R}^{2} \quad y(r, \mathfrak{G}) = (r \cos \theta, r \sin \theta)$$

$$f : \mathbb{R}^{2} \to \mathbb{R}^{2} \quad f(x_{i}) = (g_{i}^{2}, x_{i}^{2}, x_{j}^{2})$$
Compute:  $O[Dg](2, \overline{\Xi})$   

$$@ [Df](q(2, \overline{\Xi}))$$

$$@ [Df](q(2, \overline{\Xi}))$$

$$[Dg] = \begin{bmatrix} 2y_{i} & \frac{2y_{i}}{2} & \frac{2y_{i}}{3} \\ \frac{2y_{i}}{3} & \frac{2y_{i}}{3} & \frac{2y_{i}}{3} \\ \frac{2y_{i}}{3} & \frac{2y_{i}}{3} & \frac{2y_{i}}{3} \end{bmatrix} = \begin{bmatrix} \cos(\theta - r \sin \theta) \\ \sin(\theta - r \cos \theta) \end{bmatrix}$$

$$[Dg](2, \overline{\Xi}) = \begin{bmatrix} \cos(\overline{\Xi}) & -2\sin(\overline{\Xi}) \\ \sin(\theta - r \cos \theta) \end{bmatrix}$$

$$[Dg](2, \overline{\Xi}) = \begin{bmatrix} \cos(\overline{\Xi}) & -2\sin(\overline{\Xi}) \\ \sin(\overline{\Xi}) & 2\cos(\overline{\Xi}) \end{bmatrix} = \begin{bmatrix} 0 & -2 \\ 1 & 0 \end{bmatrix}$$

$$[Df] = \begin{bmatrix} 0 & 2y_{i} \\ 2x_{i} \\ 1 & -2y_{i} \end{bmatrix}$$$$

Notice: 
$$g(2, \overline{z}) = (2\cos(\overline{z}), 2\sin(\overline{z}))$$
  
 $= (0, 2)$   
 $[Df](g(2, \overline{z})) = [Df](g(2, \overline{z})) [D_{j}](2, \overline{z})$   
 $g[D(f, j)](2, \overline{z}) = [Df](g(2, \overline{z})) [D_{j}](2, \overline{z})$   
 $= \begin{bmatrix} 0 & 4 \\ 0 & 1 \\ 1 & -4 \end{bmatrix} \begin{bmatrix} 0 & -2 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 0 + 0k(1) & (0k(1) + 0k(9) \\ (0k(4) + 0k(0) & (0k(4) + 0k(9) \\ (k(4) + 0k(0) & (0k(4) + 0k(9) \end{bmatrix}) \\ (k(4) + 0k(0) & (0k(4) + 0k(9) \end{bmatrix}$   
 $g[\frac{4 & 0}{1 & 0} \\ 1 & 0 \\ -4 & -2 \end{bmatrix}$   
Remark: If we write  $(f_{2})(r, 0) = ((f_{2})(r, 0), (f_{2})(r, 0), (f_{2})(r, 0))$ .  
Then Since  $[Uf_{2}j_{1}](2, \pi_{2}) = (f_{2}, f_{2}) = (f_{2},$ 

Shortcut diagram for partial derivatives / implicit differentiation / tangent planes to surfaces.