Longo: Math 20C - Winter 2017 Lecture Notes
Date:
Section: §2.5 (cont.)
Topics Covered: Chain rule for partial derivatives revisited.

Chain Ruk for Partials: Last time we sa:

Theorem: (Chain Rule): Suppose $f: \mathbb{R}^m \to \mathbb{R}^r$ $g: \mathbb{R}^n \to \mathbb{R}^r$

are both diff'ble. Then

 $h := f_{g} : \mathbb{R}^{n} \to \mathbb{R}^{n} \quad \text{is also diffible}$ and $[Dh](\vec{x}) = [Df](g^{(x)})[D_{\vec{x}}](\vec{x})$

This means that we can obtain the full matrix of partial derivatives of h=f-s by multiplying the matrices of partial derivatives of f and g. This is often more efficient than actually composing the functions and Calculating the partials of h directly.

On the other hand, if we only need certain partials of hand not the entire matrix [Dh]), we can do it in a quicker (and less confusing (!)) way.

Shortcut diagram for calculating partials of a composition.

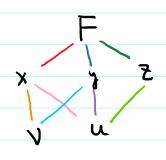
It is easiest to explain this via an example:

Suppose: BF(x,y,Z) is a fen of x,y,Z,

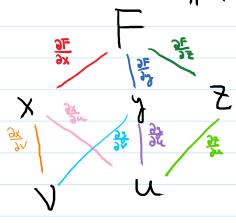
2 x, y are fens of u,v

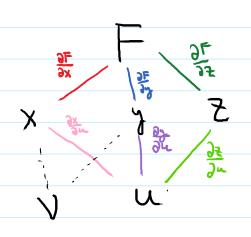
3 Z is a fen of only u.

Then we can draw a dependancy diagram



Here, we attach a line from one node to another if the higher node depends on the lower node. On this diagram, We attach the appropriate partial derivative:





Now to find $\frac{\partial F}{\partial u}$, isolate 'u' in the tree and look at all paths from F to u.

On each path, multiply

$$\frac{\partial r}{\partial E} = \left(\frac{\partial x}{\partial E}\right)\left(\frac{\partial x}{\partial x}\right) + \left(\frac{\partial y}{\partial E}\right)\left(\frac{\partial x}{\partial x}\right) + \left(\frac{\partial z}{\partial E}\right)\left(\frac{\partial z}{\partial E}\right)$$

X 3 Z

If we do the same for v, we jet:

$$\frac{\partial V}{\partial F} = \left(\frac{\partial x}{\partial x}\right)\left(\frac{\partial x}{\partial x}\right) + \left(\frac{\partial y}{\partial x}\right)\left(\frac{\partial y}{\partial x}\right)$$

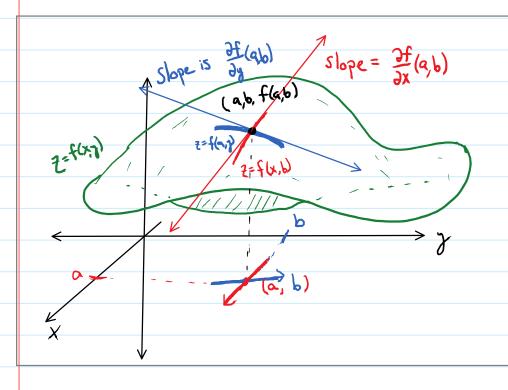
Warning: To avoid messy notation, I didn't write whom these fews should be evaluated. Partials of f should be evaluated at (X(u,v), y(u,v), z(u)), partials of X,y,z, should be evaluated at (u,v).

Note: This notation means when (u,v)=(1,2), (x,y,z)=(3,5,6)So F's partials w.r.t. x,y,z should be evaluated at (3,5,6).

§2.6: Directional derivatives and the geometry of the gradient:

In this section, we stick to fins from $\mathbb{R}^2 \to \mathbb{R}$ or $\mathbb{R}^2 \to \mathbb{R}$

Let $f: \mathbb{R}^2 \to \mathbb{R}$. We saw that $\frac{\partial f}{\partial x}(a,b)$ (resp. $\frac{\partial f}{\partial y}(a,b)$) tell you the rate of change in f as we move from the point (a,b) in the positive x-direction (resp. positive y director).



How do

we determine the

rate of change of f

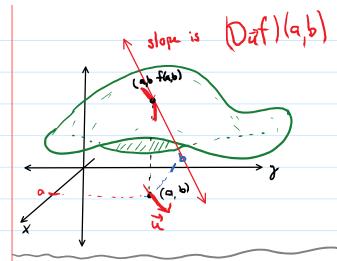
as we move from

(a,b) in an

arbitrary direction

determined by a

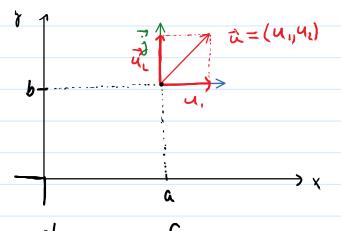
unit vector \vec{u} ?



We will call this the directional derivative of f in the direction of it, denoted (Dif)(a,b)

How do ve calculate (Daf)(9,6)?

Look at the domain of



vi direction is

na=(u,,ui) Decompose il into its components · は= は、ご+ は、了 Since I "goes u, in the i and uz in the Change in f as you move from (a,b) in the

> $\left(\mathcal{D}_{\mathcal{A}} f \right) (q,b) = \frac{\partial f}{\partial x} (a,b) \mathcal{U}_{1} + \frac{\partial f}{\partial y} (a,b) \mathcal{U}_{2}$ rate of change distance rate of change distance in x dir. in x dir. in y dir. in y dir.

> > $= (\nabla f)(a,b) \cdot \overrightarrow{u}$

Example: Find the rate of change of $f(x,y,z)=2xy-e^{x^2y}+2z$ at (2,1,6)direction of == (1,-1,1).

1) According to my definition, we need
$$\vec{u}$$
 to be a unit vector. So we first normalize \vec{u} .

Replace \vec{u} by $\vec{e}_{\vec{u}} = \frac{1}{|\vec{u}|} \vec{u} = \frac{1}{\sqrt{1+1+1}} (1,-1,1)$

$$= \left(\frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}\right)$$

The equation above was for fons from R'to R', but the same formula works.

$$(\nabla f)(2,1,0) = (2y-2xye^{x^2y}, 2x-x^2e^{x^3y}, 2z-x^2e^{x^3y}, 2z-x^2e^{x^3$$

$$(D_{ii}f)(2,1,0) = (2-4e^{4}, 4-4e^{4}, 0) \cdot (\frac{1}{55}, \frac{1}{55}, \frac{1}{55})$$

$$= \frac{1}{55}(2-4e^{4}) - \frac{1}{55}(4-4e^{4})$$

$$= \frac{-2}{55}$$

Differences with the book:

Warnings! (1) Your book also considers Daf when we is not a unit veger. They call this the directional derivative along is.

We will only lash at directional derivative in the direction of it.

The book uses the notation [Df](a,b)(\vec{v}) instead of (D\vec{v})(a,b).

This is because
$$(D_{\vec{a}}f)(q_b) = (\nabla f)(q_b) \cdot \vec{u}$$

$$= [Df](q_b) \cdot \vec{u}$$
the total as a derivative of column vector.

(3) The book has a nice explanation as to what this means in higher dimension. We will ignore this, but I encourage you to read it since it may provide insight for the significance of [Df](2).

Geometry of the gradient: If it is a unit vector,

 $(\mathcal{D}_{\vec{u}}f)(a,b) = (\nabla f)(a,b) \cdot \vec{u}$ is the rate of change in the \vec{u} direction.

On the other hand:

(マf)(a,b)· ゼ= 11(マf)(a,b)11·11ゼ11 cose = 11 マf(a,b)1 cose

where Θ is the angle between \vec{v} and $\nabla f(q,b)$.

Note: 1 (a,b) is maximal when cose=1

⇔ 6 = 0

⇔ \(\tilde{\pi} \) points in the same

direction as \(\bar{\pi} \) \(\bar{\pi} \) \(\alpha_1 \bar{\bar{\pi}} \)

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So (Vf)(a, b) points in the direction of maximal

increase for f.

2) If $\vec{u} = \frac{\nabla f(a,b)}{\|\nabla f(a,b)\|}$ is the unit vector in the

 $\nabla f(a,b)$ direction, $(\nabla_{\vec{a}} f)(a,b) = \nabla f(a,b) \cdot (\frac{\nabla f(a,b)}{\|\nabla f(a,b)\|})$

 $= \frac{\nabla f(a,b) \cdot \nabla f(a,b)}{\|\nabla f(a,b)\|}$

= 11 \(\nabla f(\s, 1) 11^2\)

= 11 7 f(c,b) 1

So the maximal rate of change of f in any direction is 11 $\nabla f(a,b)11$

Example: Farmer Corey is standing near the middle of his carn field in the great city of Omaha, NE (say he is standing at the point (0,1)). The temperature at the point (x,y) is given by $T(x,y) = 30e^{-(x-1)^2 - (2y-1)^2}$. Farmer Corey is very cold what direction Should he walk to varm up the fastest?

Sol! He should walk in the direction of (DT)(0,1). $DT = \left(-60(x-1)e^{-(x-1)^2-(xy-1)^2}, -120(2y-1)e^{-(x-1)^2-(2y-1)^2}\right)$ $(DT)(0,1) = \left(60e^{-2}, -120e^{-2}\right).$