•
$$(f \circ Z)(t) = e^t cos(t)$$

 $(f \circ Z)'(t) = e^t cos(t) - e^t sin(t)$

•
$$(f-z)'(t) = (\nabla f)(z(t)) \cdot z'(t)$$
.
 $\nabla f(z(t)) = (\gamma, x) = (cos(t), e^t)$
 $z'(t) = (e^t, -s_m(t))$.

chain rule:
$$(f \circ Z)'(t) = (\nabla f)(Z(t)) \circ Z'(t)$$

= $(cos(t), e^t) \circ (e^t, -sin(t))$
= $e^t cos(t) - e^t sint$

$$\int \int f(x,y) = (\tan(x-1)^{-e^{x}}, x^{-2})$$

$$g(x,y) = (e^{x-y}, x-y).$$

$$g(x_{1}) = (e^{x-y}, x-y).$$

$$(f \cdot y)(x,y) = f(g(x,y))$$

$$= f(e^{x-y}, x-y)$$

$$= (tan(e^{x-y}-1) - e^{x-y}, (e^{x-y})^{2} - (x-y)^{2})$$

$$e^{x-y}e^{x}(e^{x-y}-1) - e^{x-y}, -e^{x-y}se^{x}(e^{x-y}-1) + e^{x-y}$$

$$2e^{2x-2y} - 2(x-y), -2e^{2x-2y} + 2(x-y)$$

$$e^{x-y}e^{x}(e^{x-y}-1) - e^{x-y}, -e^{x-y}se^{x}(e^{x-y}-1) + e^{x-y}$$

$$2e^{x-2y} - 2(x-y), -2e^{x-2y} + 2(x-y)$$

$$2e^{x-2y} - 2(x-y), -2e^{x} + 2(x-y)$$
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$$f(u,v) = (\cos(t^2s), \log \sqrt{1+s^2})$$

$$T(s,t) = (\cos(t^2s), \log \sqrt{1+s^2})$$

Using the shortcut method, we can make the tree!

Then
$$\frac{\partial f}{\partial s} = (\frac{\partial f}{\partial u})(\frac{\partial u}{\partial s}) + (\frac{\partial f}{\partial v})(\frac{\partial v}{\partial s})$$
 $\frac{\partial f}{\partial u} = -S_{in}(u) S_{in}(v)$
 $\frac{\partial u}{\partial s} = -t^2 S_{in}(t^2 s)$

$$\cdot \frac{\partial r}{\partial t} = -2iu(r) 2iu(r)$$

$$\frac{\partial V}{\partial t} = Cos(u) Cos(u)$$

$$\cdot \frac{\partial z}{\partial r} = \frac{1+z_2}{2}$$

When
$$(5,t)=(1,0), (21,v)=(\cos(0), \log \sqrt{2})$$

= $(1,\log \sqrt{2})$

T'(t) =
$$(\nabla T)(\vec{c}'(t)) \cdot \vec{c}'(t)$$

= $(2x, 2y, 2z)|_{\vec{c}'(t)} \cdot (-s;n(t), cos(t), 1)$
= $(2\cos(t), 2s;n(t), 2t) \cdot (-s,n(t), cos(t), 1)$
= $(2t)$

we get the temp at time = + a.ol ≈

$$\frac{3^{2}}{3^{2}} = \frac{3^{2}}{3^{2}} + \left(\frac{3^{2}}{3^{2}}\right)\left(\frac{3^{2}}{3^{2}}\right)$$

$$\downarrow$$

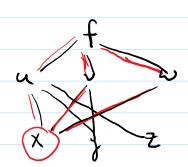
$$\downarrow$$

$$\downarrow$$

$$\downarrow$$

$$\downarrow$$





Using the tree!

$$\frac{\partial V}{\partial x} = \left(\frac{\partial V}{\partial x}\right) \left(\frac{\partial V}{\partial x}\right) + \left(\frac{\partial V}{\partial x}\right) \left(\frac{\partial V}{\partial x}\right)$$

$$\frac{2f}{3u} = (u^2 - v^2)(2u) - (u^2 + v^2)2u - \frac{-4uv^2}{(u^2 - v^2)^2}$$

$$\frac{2f}{dv} = \frac{2v(u^2-v^2) + 2v(u^2+v^2)}{(u^2-v^2)^2} - \frac{4vu^2}{(u^2-v^2)^2}$$

$$\frac{31}{3x} = \left(\frac{-4uv^{2}}{(u^{2}-v^{2})^{2}}\right)\left(-e^{-x^{2}}\right) + \left(\frac{4vu^{2}}{(u^{2}-v^{2})^{2}}\right)\left(ye^{xy}\right)$$

You should write, u, v in terms of xig but I'm oky with this-

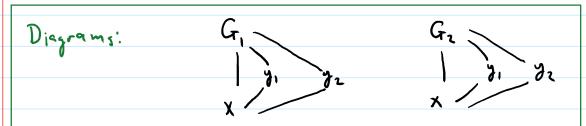
19 0 If G(x, y, (x)) =0, then

Chain rule $\Rightarrow \frac{3G}{3x} + \frac{3G}{3y} \cdot \frac{4x}{4x} = 0$

$$\Rightarrow \frac{\partial x}{\partial x} = \frac{\left(-\frac{\partial G}{\partial x}\right)}{\left(\frac{\partial G}{\partial x}\right)} \qquad \text{as long is } \frac{\partial G}{\partial y} = 0$$

Rud! This is the proof of implicit differentiation from Calc.l.

differentiate both exprs w.r.t. X using chain rule:



$$\frac{\partial}{\partial x} \left(G_{1}(x, y, (x), y_{1}(x)) = \frac{\partial}{\partial x} (a) \right)$$

$$\frac{\partial}{\partial x} + \left(\frac{\partial}{\partial y} \right) \left(\frac{\partial}{\partial x} \right) + \left(\frac{\partial}{\partial y} \right) \left(\frac{\partial}{\partial x} \right) = 0$$

$$\frac{\partial}{\partial x} + \left(\frac{\partial}{\partial y} \right) \left(\frac{\partial}{\partial x} \right) + \left(\frac{\partial}{\partial y} \right) \left(\frac{\partial}{\partial x} \right) = 0$$

$$\frac{\partial}{\partial x} + \left(\frac{\partial}{\partial y} \right) \left(\frac{\partial}{\partial x} \right) + \left(\frac{\partial}{\partial y} \right) \left(\frac{\partial}{\partial x} \right) = 0$$

Then
$$\left(\frac{\partial G_1}{\partial J_1}\right)\left(\frac{dJ_1}{dx}\right) + \left(\frac{\partial G_1}{\partial J_2}\right)\left(\frac{dJ_2}{dx}\right) = -\frac{\partial G_1}{\partial X}$$

 $\left(\frac{\partial G_2}{\partial J_1}\right)\left(\frac{dJ_2}{dx}\right) + \left(\frac{\partial G_2}{\partial J_2}\right)\left(\frac{dJ_2}{dx}\right) = -\frac{\partial G_2}{\partial X}$

Solving this system of equs gives:

$$\frac{dy_{1}}{dx} = -\frac{\left(\frac{\partial G_{1}}{\partial y_{1}}\right) \cdot \left(\frac{\partial G_{1}}{\partial x}\right) + \left(\frac{\partial G_{1}}{\partial y_{2}}\right) \cdot \left(\frac{\partial G_{1}}{\partial x}\right)}{\left(\frac{\partial G_{1}}{\partial y_{1}}\right) \cdot \left(\frac{\partial G_{1}}{\partial y_{1}}\right) - \left(\frac{\partial G_{1}}{\partial y_{1}}\right) \left(\frac{\partial G_{1}}{\partial y_{1}}\right)} = \frac{\left(\frac{\partial G_{1}}{\partial y_{1}}\right) \cdot \left(\frac{\partial G_{1}}{\partial y_{1}}\right) - \left(\frac{\partial G_{1}}{\partial y_{1}}\right) \cdot \left(\frac{\partial G_{1}}{\partial y_{1}}\right)}{\left(\frac{\partial G_{1}}{\partial y_{1}}\right) \cdot \left(\frac{\partial G_{1}}{\partial y_{1}}\right) - \left(\frac{\partial G_{1}}{\partial y_{1}}\right) \cdot \left(\frac{\partial G_{1}}{\partial y_{1}}\right)} = \frac{\left(\frac{\partial G_{1}}{\partial y_{1}}\right) \cdot \left(\frac{\partial G_{1}}{\partial y_{1}}\right) - \left(\frac{\partial G_{1}}{\partial y_{1}}\right) \cdot \left(\frac{\partial G_{1}}{\partial y_{1}}\right)}{\left(\frac{\partial G_{1}}{\partial y_{1}}\right) - \left(\frac{\partial G_{1}}{\partial y_{1}}\right) - \left(\frac{\partial G_{1}}{\partial y_{1}}\right) \cdot \left(\frac{\partial G_{1}}{\partial y_{1}}\right)}$$

19c Let
$$x^2 + y^3 + e^7 = 0$$
 and let $G(x,y) = x^2 + y^2 + e^y$.

By pat (a), $\frac{dy}{dx} = \frac{-2x}{3x^2 + e^7}$
 $\frac{2^4}{3y^2} = \frac{-2x}{3y^2 + e^7}$

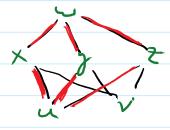
Then
$$\frac{\partial \omega}{\partial u} = \left(\frac{\partial \omega}{\partial x}\right)\left(\frac{\partial x}{\partial u}\right) + \left(\frac{\partial \omega}{\partial y}\right)\left(\frac{\partial y}{\partial u}\right) + \left(\frac{\partial \omega}{\partial z}\right)\left(\frac{\partial z}{\partial u}\right)$$

=
$$(2x)(v) + (2y)(cusv) + (2z)(sinv)$$

= $(2uv)(v) + (2ucosv)(cusv) + (2usinv)(sinv)$

So
$$\left(\frac{\partial u}{\partial u}\right)(1/0) = 0 + 2 + 0$$

$$= 2$$



\$2.6: 1, 2,4, 17,18, 22, 24, 32:

In Since
$$\vec{u} = (\frac{1}{15}, \frac{2}{15}, 0)$$
 is a unit redar,

$$(\mathcal{D}_{\vec{\alpha}}f)(1,1,2)=(\nabla f)(1,12)\cdot\vec{\alpha}.$$

- 2) Note that the direction vectors for each problem is unit, so we use $(D_{ii}f) = (\nabla f) \cdot \vec{u}$
- @ Tf = (1+2y, 2x-6y) $(\nabla f)(1,2) = (5,-10)$ $(D^3+)(1'r)=(2'-19)\cdot\left(\frac{2}{3}'\frac{2}{4}\right)$ = 3 -8
- Vf(1,0)= (1,0) (Dof)(1,0) = (1,0) · (3, 5)
- $(\nabla f)(0,-1) = (-1,0)$

$$(D_{\sigma f})(o, +) = (-1, o) \cdot (\frac{-1}{\sqrt{5}}, \frac{2}{\sqrt{5}}) = \frac{1}{\sqrt{5}}$$

$$=\frac{-92}{\sqrt{10}}+\frac{144}{\sqrt{10}}=\frac{52}{\sqrt{10}}$$

We went a vector
$$\vec{u}$$
 such that $(D_{\vec{v}}f)(z_1)=0$.
So we need \vec{u} so that $(\nabla f)(z_1)\cdot\vec{u}=0$

$$\nabla f = \left(-\pi \gamma \sin(\pi x) - \cos(\pi \gamma), \cos(\pi x) + \pi x \sin(\pi \gamma)\right) \\
(\nabla f)(2|) = \left(-\pi \sin(2\pi) - \cos(\pi), \cos(2\pi) + 2\pi \sin(\pi \gamma)\right) \\
= \left(1, 1\right).$$

If we want
$$(\mathcal{I}_{2})(2_{1}) = (\mathcal{I}_{1})(2_{1}) \cdot (u_{1},u_{1}) = 0$$

$$\Rightarrow (1,1) \cdot (u_{1},u_{1}) = 0$$

$$\Rightarrow u_{1} + u_{2} = 0.$$
So we can take $\mathcal{I}_{2} = \frac{1}{\sqrt{2}}(1,-1)$

This is essentially a chain rule quotion.

Use
$$(f \circ \gamma)'(1) = (\nabla f)(\gamma(1)) \cdot \gamma'(1)$$
.

The direction of steepest increase is
$$\nabla T$$
, so the direction of steepest decrease is
$$-\nabla T = -\left(-2x e^{-x^2-2y^2-3z^2} - 4y e^{-x^2-2y^2-3z^2}\right).$$

$$(-\nabla T)(1)(1) = \left(2e^{-\zeta}, 4e^{-\zeta}, 6e^{-\zeta}\right).$$

$$(\mathcal{D}_{\vec{u}}f)(|||)$$
 where $\vec{u} = e^{i}\left(\frac{-\nabla T(||||)}{||-\nabla T(|||||||)}\right)$

- The direction of steppost increase is

$$(\nabla z)(1) = (-2a, -2b)$$

The ball will roll in the $(\nabla z)(1) = (2a, 2b)$
direction.

by $[(Df)(x_1, x_1)]$ $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ water mate.

If
$$\begin{bmatrix} i \\ j \end{bmatrix}$$
 gets sent to $\begin{bmatrix} i \\ j \end{bmatrix}$ under $\begin{bmatrix} i \\ j \end{bmatrix} = \begin{bmatrix} i \\ j \end{bmatrix} \Rightarrow \begin{bmatrix} i \\ j \end{bmatrix} = \begin{bmatrix} i \\ j \end{bmatrix} \Rightarrow \begin{bmatrix} i \\ j \end{bmatrix} = \begin{bmatrix} i \\ j \end{bmatrix} \Rightarrow \begin{bmatrix} i \\ j \end{bmatrix} = \begin{bmatrix} i \\ j \end{bmatrix} \Rightarrow \begin{bmatrix} i \\ j \end{bmatrix} = \begin{bmatrix} i \\ j \end{bmatrix} \Rightarrow \begin{bmatrix} i \\ j \end{bmatrix} = \begin{bmatrix} i \\ j \end{bmatrix} \Rightarrow \begin{bmatrix} i \\$

which is what we wanted.