§ 4.1: 5,6,7,8,12,13,15,19,20:

For
$$5-8$$
: $\overrightarrow{C}_{i}(t)=(e^{t}, sint, t^{3})$ \Rightarrow $\overrightarrow{C}_{i}(t)=(e^{t}, cost, 3t^{2})$ $\overrightarrow{C}_{i}(t)=(e^{t}, cost, -2t^{3})$ \Rightarrow $\overrightarrow{C}_{i}'(t)=(-e^{t}, -sint, -6t^{2})$

(5) 1st way:
$$\vec{c}(t) = (e^t + e^{-t}, s_{int} + c_{int}, -t^3)$$

$$\vec{d}_t(\vec{c}(t) + \vec{c}(t)) = (e^t - e^{-t}, cost - s_{int}, -t^3).$$

$$2^{nd}$$
 way (using rules)! $\frac{d}{dt}(\vec{c}_{i}(t) + \vec{c}_{i}(t) = \vec{c}_{i}(t) + \vec{c}_{i}(t)$
= $(e^{t}, \cos t, 3t^{2}) + (-e^{t}, -\sin t, -6t^{2})$
= $(e^{t} - e^{-t}, \cos t - \sin t, -3t^{2})$ \(\tag{e}^{t}\)

2nd way (using rules).

$$\frac{1}{dt}(\vec{c}(t) \cdot \vec{c}(t)) = (\vec{c}'_{i}(t) \cdot \vec{c}_{i}(t)) + (\vec{c}'(t) \cdot \vec{c}'_{i}(t))$$

$$= ((e^{t}, cost, 3t) \cdot (e^{-t}, cost, -2t)) + ((e^{t}, s_{in}t_{i}^{2}) \cdot (-e^{t}, -s_{in}t_{i}, -t_{i}^{2}))$$

$$= 1 + cos^{2}t - 6t^{5} + (-1 - s_{in}^{2}(t) - 6t^{5})$$

$$= -12t^{5} - s_{in}t_{i} + cos^{2}t$$

$$= (-2t^{3}s_{i}nt - t^{3}cost, t^{3}e^{t} + 2t^{3}e^{t}, e^{t}cost - e^{-t}s_{i}nt)$$

$$= (t^{3}(-2s_{i}nt - cost), t^{3}(e^{-t} + 2e^{t}), e^{t}cost - e^{-t}s_{i}nt)$$

$$= (3t^{3}(-2s_{i}nt - cost) + t^{3}(-2cost + s_{i}nt))i^{3} + (3t^{3}(e^{t} - 2e^{t}) + t^{3}(-e^{t} - 2e^{t}))i^{3}$$

$$+ (cost(e^{t} - e^{t}) + s_{i}nt(e^{t} - e^{t}))i^{3}$$

$$2^{\frac{1}{2}} \log_{2} (u_{5} \log_{2} m_{5} \log_{2}) \cdot \frac{1}{4t} (z_{1}(t) \times z_{1}(t)) = (z_{1}(t) \times z_{1}(t)) + (z_{1}(t) \times z_{1}(t))$$

$$= \begin{vmatrix} z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} \\ e^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} \end{vmatrix} + \begin{vmatrix} z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} \\ z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} \end{vmatrix} + \begin{vmatrix} z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} \\ z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} \\ -2t^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} \\ -2t^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} \\ -2t^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} \\ -2t^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} \\ -2t^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} & z^{\frac{1}{2}} \\ -2t^{\frac{1}{2}} & z^{\frac{1}{2}} \\ -2t^{\frac{1}{2}} & z^{\frac{1}{2}} & z$$

 $\vec{V}(t) = (0,0,6) \implies \vec{V}(t) = (0,0,6t) + \vec{U}, \quad \vec{u} = (0,0,6t)$

$$\vec{V}(0) = (1,1,-2) \implies (1,1,-2) = (0,0,0) + \vec{U}_1$$

$$\Rightarrow \vec{U}_1 = (1,1,-2)$$

$$\Rightarrow \vec{V}(t) = (1,1,6t-2).$$

Now
$$Z'(t) = (1,1,6t-2)$$

$$\Rightarrow Z(t) = (t,t,3t-2t) + \vec{u}_{z}, \quad \vec{u}_{z} \quad a \quad constant \quad vector.$$

$$\vec{C}(0) = (3,4,0)
\Rightarrow (3,4,0) = (0,0,36)^{2} - 2(6) + U_{2}$$

$$\vec{E}(0) = (3,4,0) = (0,0,36)^{2} - 2(6) + U_{2}$$

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$$\vec{a}(t) = (2, -6, -4) \implies \vec{a}(t) = (2t, -6t, -4t) + \vec{a}(t), \vec{a}(t) = (-5,1,3)$$

$$\Rightarrow (-5,1,3) = (20), -60, -4(4) + \vec{u},$$

$$\Rightarrow \vec{u}_{i} = (-5,1,3)$$

$$\Rightarrow$$
 $\sqrt[3]{t} = (2t-5, -6t+1, -4t+3).$

Now
$$\vec{r}(t) = (t^2-5t, -3t^2+t, -2t^2+3t) + \vec{u}_1, \vec{u}_2$$
 const.
 $\vec{r}(4=(6,-1,1) \Rightarrow$

$$(6,-2,1)=(0,0,0)+\vec{u_i}$$

$$\overrightarrow{r}(t)$$
 intersects $y \ge -p$ lane when $x=0 \Rightarrow t^2 - 5t + 6 = 0$ $\Rightarrow (t-3)(t-1) \Rightarrow t=3 \text{ or } 2.$

So the two points are:
$$\vec{r}(1) = (0, -12, -1)$$

 $\vec{r}(3) = (0, -26, -8)$

$$\vec{v}(t) = (6t, 3t^{2}, t^{2})$$

$$\vec{v}(t) = (6, 6t, 3t^{2})$$

$$\vec{c}(t) = (0, 6, 6t).$$

$$\vec{c}(0) = (0, 6, 0).$$

19 Assume 2"(t) L Z'(t) for all t.

Note: 112'(t) 11 is constant = 112'(t) 11 is constant.

Speed.

We calculate
$$\frac{d}{dt}(S(t)) = \frac{d}{dt}(1|Z'(t)|1^2)$$

 $= \frac{d}{dt}(|Z'(t)|1^2)$
 $= \frac{d}{dt}(|Z'(t)|1^2)$
 $= (|Z''(t)|1|2'(t)|1^2)$
 $= (|Z''(t)|1|2'(t)|1^2)$
 $= (|Z''(t)|1|2'(t)|1^2)$

Since
$$\overline{C''(t)} \perp \overline{C'(t)}$$
 for all t ,

$$\frac{d}{dt} (||Z'(t)||^2) = 2(|\overline{C''(t)} \cdot \overline{C''(t)}|)$$

$$= 0.$$
Now Since the derivative of $||Z'(t)||^2 = 0$,
$$||Z''(t)||^2 \text{ is constant} \Rightarrow S(t) = ||Z''(t)|| \text{ is}$$

Therefore, Ilritill has extreme values when $\frac{d}{dt}$ (Irky11) =0

(at critical points)

constant.

but
$$\frac{1}{dt}(||\vec{r}(t)||) = \frac{d}{dt}(|\vec{r}(t) \cdot \vec{r}(t)|)$$
 $= \frac{1}{2||\vec{r}(t)||}(|\vec{r}(t) \cdot \vec{r}(t)| + |\vec{r}(t) \cdot \vec{r}(t)|)$
 $= \frac{\vec{r}'(t) \cdot \vec{r}(t)}{||\vec{r}(t)||}$
 $= ||\vec{r}'(t)|| ||\vec{r}(t)|| \cos \theta$
 $= ||\vec{r}'(t)|| \cos \theta$

When θ is the angle between $\vec{r}'(t)$, $\vec{r}'(t)$.

Thus, $\frac{d}{dt}(||\vec{r}(t)||) = 0 \Leftrightarrow (\cos \theta = 0 \text{ or } ||\vec{r}'(u)| \cos \theta) \Leftrightarrow \theta = 90^{\circ}$.

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