

A vector (or scalar) function  $\mathbf{F}(\mathbf{R})$  is called *homogeneous of degree  $d$*  if  $\mathbf{F}(t\mathbf{R}) = t^d\mathbf{F}(\mathbf{R})$  for all vectors  $\mathbf{R}$  and real numbers  $t$  such that  $\mathbf{R}$  and  $t\mathbf{R}$  are in the domain of  $\mathbf{F}$ . (If  $d = 0$ , we define  $0^d = 1$ .)

**S1.** Suppose  $\mathbf{F}(\mathbf{R})$  is defined in a domain that is star shaped with respect to the origin and is homogenous of degree  $d$ . Using the integral formulas from Sections 4.4 and 4.5 with  $\mathbf{R}_0 = \mathbf{0}$ , prove the following:

(a) If  $\mathbf{F}$  has a scalar potential, then  $\frac{1}{d+1}\mathbf{F}(\mathbf{R}) \cdot \mathbf{R}$  is a scalar potential for  $\mathbf{F}$  and it is homogeneous of degree  $d + 1$ .

(b) If  $\mathbf{F}$  has a vector potential, then  $\frac{1}{d+2}\mathbf{F}(\mathbf{R}) \times \mathbf{R}$  is a vector potential for  $\mathbf{F}$  and it is homogeneous of degree  $d + 1$ .

Remark: Since the star-shaped domain contains the origin, we may take  $t = 0$  and  $\mathbf{R}$  any point in the domain to get  $\mathbf{F}(0\mathbf{R}) = 0^d\mathbf{F}(\mathbf{R})$ . It follows that  $d \geq 0$ .

**S2.** Show that the vector functions  $\mathbf{F}$  of Examples 4.9, 4.10 and 4.12 and the vector function in Exercise 4.5.2 are all homogeneous and compute their degrees.

**S3.** Using Exercises S1 and S2, derive vector (and, for Example 4.12, scalar) potentials for Examples 4.9, 4.10 and 4.12 and Exercise 4.5.2.

**S4.** For Example 4.12 and Exercise 4.5.2 the vector potentials  $\mathbf{G}$  obtained in the previous exercise do not agree with the result in the book. For instance, for Example 4.12 you should obtain  $\frac{1}{3}(-yz\mathbf{i} - xz\mathbf{j} + 2xy\mathbf{k})$ . Explain why both answers are correct.