

## Practice problems:

(2) The Poincaré plane:

upper half plane  $\{(u, v) \mid v > 0\}$ .

with metric:  $\langle w_1, w_2 \rangle := \frac{w_1 \cdot w_2}{r^2}$

at a point  $p = (u, v) \in \text{half plane}$

$$E_1 = r U_1 \quad E_2 = r U_2$$

(a)  $\theta_1 = \frac{1}{r} du \quad \theta_2 = \frac{1}{r} dr$ .

$$\omega_{12} = \omega_{12}(E_1)\theta_1 + \omega_{12}(E_2)\theta_2$$

$$\omega_{12}(E_1) dr = d\theta_1(E_1, E_2)$$

$$\omega_{12}(E_2) = d\theta_2(E_1, E_2)$$

$$d\theta_1 = d\left(\frac{1}{r} du\right) = d\left(\frac{1}{r}\right) \wedge du$$

$$= \left(\frac{\partial}{\partial u}\left(\frac{1}{r}\right) du + \frac{\partial}{\partial v}\left(\frac{1}{r}\right) dv\right) \wedge du$$

$$= \frac{1}{r^2} du \wedge dr = \theta_1 \wedge \theta_2$$

$$d\theta_2 = d\left(\frac{1}{r} dr\right) = d\left(\frac{1}{r}\right) \wedge dr$$

$$= 0$$

$$\omega_{12} = \theta_1 = \frac{1}{r} du$$

(2) Covariant derivative:

$$\nabla_V E_1 = \omega_{12}(V) E_2$$

$$\nabla_V E_2 = -\omega_{12}(V) E_1$$

$$\alpha(t) = r(\cos t, \sin t) \quad 0 < t < \pi.$$

$$\alpha'(t) = r(-\sin t, \cos t).$$

$$= r(-\sin t V_1 + \cos t V_2)$$

$$= \frac{r}{\sqrt{2}} (-\sin t E_1 + \cos t E_2)$$

$$\alpha''(t) = \nabla_{\alpha'(t)} (\alpha'(t))$$

$$\nabla_{\alpha'} (\alpha') = \frac{r}{r \sin t} (-\sin t E_1 + \cos t E_2)$$

$$= -E_1 + \cot t E_2$$

$$\nabla_{\alpha'} (\alpha') = -\nabla_{\alpha'} E_1 + \frac{d}{dt} (\cot t) E_2$$

$$+ \cot t \nabla_{\alpha'} E_2$$

$$\nabla_{\alpha'} E_1 = \omega_{12}(\alpha'(t)) E_2.$$

$$= \frac{1}{\sqrt{2}} du(\alpha'(t)) E_2.$$

$$= \frac{1}{r \sin t} \cdot (-r \sin t) E_2 = -E_2$$

$$\begin{aligned} \nabla_{\alpha'} E_2 &= -\omega_{12} (\alpha'(t)) E_1 \\ &= \frac{-1}{r} du (\alpha'(t)) E_1 \\ &= E_1 \end{aligned}$$

$$\begin{aligned} \alpha''(t) &= E_2 - \frac{1}{\sin^2 t} E_2 + \cot t E_1 \\ &= -\cot^2 t E_2 + \cot t E_1 \end{aligned}$$

(c)  $\beta(t) = (c, s) t = t(c, s)$   
 $c^2 + s^2 = 1$        $st > 0$

$$\alpha'(t) = (c, s) = c U_1 + s U_2$$

~~acceleration:  $\alpha''(t) =$~~

$$\begin{aligned} &= \frac{c}{2/c} E_1 + \frac{s}{2/s} E_2 \\ &= \frac{c}{ts} E_1 + \frac{s}{ts} E_2 \\ &= \frac{c}{s} \frac{1}{t} E_1 + \frac{1}{t} E_2 \\ &= \frac{1}{t} \left( \frac{c}{s} E_1 + E_2 \right) \end{aligned}$$

$$\begin{aligned} \alpha''(t) &= \nabla_{\alpha'} (\alpha') = -\frac{1}{t^2} \left( \frac{c}{s} E_1 + E_2 \right) \\ &\quad + \frac{1}{t} \nabla_{\alpha'} \left( \frac{c}{s} E_1 + E_2 \right) \end{aligned}$$

$$\begin{aligned}
 \alpha''(t) &= -\frac{1}{t^2} \left( \frac{c}{s} E_1 + E_2 \right) \\
 &\quad + \frac{1}{t} \left( \frac{c}{s} \frac{1}{r} du(\alpha') E_2 - \frac{1}{r} du(\alpha') E_1 \right) \\
 &= -\frac{1}{t^2} \left( \frac{c}{s} E_1 + E_2 \right) \\
 &\quad + \frac{1}{t} \left( \frac{c^2}{ts^2} E_2 - \frac{c}{ts} E_1 \right) \\
 &= -\frac{2c}{t^2 s} E_1 + \frac{1}{t^2} \left( \frac{c^2}{s^2} - 1 \right) E_2.
 \end{aligned}$$

$$(3) \quad \omega_{12} = \theta_1 = \frac{1}{r} du \quad \theta_2 = \frac{1}{r} dv$$

$$d\omega_{12} = d\theta_1 = \theta_1 \wedge \theta_2$$

$$\Rightarrow K = -1$$

$$(4) \quad F: \mathbb{R}^2 \rightarrow \mathbb{R}^3$$

$$(u, v) \mapsto \left( \frac{f(u)}{f(u)} \cos v, \frac{f(u)}{f(u)} \sin v, v \right)$$

image is a helicoid.

(a) pull-back metric: at  $(u_0, v_0) = p$

$$w = (a, b) = a(1, 0) + b(0, 1)$$

$$F_* w = ?$$

$$F_* (1, 0) = \varphi_u = \text{tangent vector to } u\text{-parameter curve}$$

$$= (f'(u) \cos v, f'(u) \sin v, 0)$$

$$F_* (0, 1) = \varphi_v$$

$$= (f(u) (-\sin v), f(u) \cos v, 1)$$

$$F_* w = a \varphi_u + b \varphi_v$$

metric:  $\langle w_1, w_2 \rangle := \langle F_* w_1, F_* w_2 \rangle$

$$= (F_* w_1) \cdot (F_* w_2)$$

$$F_* w_i = a_i \varphi_u + b_i \varphi_v, \quad w_i = (a_i, b_i)$$

$$\langle w_1, w_2 \rangle = (a_1 \varphi_u + b_1 \varphi_v) \cdot (a_2 \varphi_u + b_2 \varphi_v)$$

$$= a_1 a_2 E + (a_1 b_2 + a_2 b_1) F + b_1 b_2 G$$

(b)  $E_1 := \frac{\varphi_u}{\|\varphi_u\|}$  assume  $f' > 0$

$$E_2 := \frac{1}{\left\| \varphi_v - \frac{\varphi_u \cdot \varphi_v}{\varphi_u \cdot \varphi_u} \varphi_u \right\|} \left( \varphi_v - \frac{\varphi_u \cdot \varphi_v}{\varphi_u \cdot \varphi_u} \varphi_u \right)$$

$$E_1 = (\cos v, \sin v, 0)$$

$$E = \varphi_u \cdot \varphi_u = f'^2 \quad F = \varphi_u \cdot \varphi_v = 0$$

$$G = \varphi_v \cdot \varphi_v = f^2 + 1$$

$$E_2 = \frac{1}{\|\varphi_v\|} \varphi_v = \frac{1}{\sqrt{f^2+1}} (-f(u)\sin v, f(u)\cos v, 1)$$

$$\theta_1 = \|\varphi_u\| du = f'(u) du$$

$$\theta_2 = \|\varphi_v\| dv = \sqrt{f^2+1} dv$$

$$d\theta_1 = d(f'(u)) \wedge du = 0$$

$$d\theta_2 = d(\sqrt{f^2+1}) \wedge dv.$$

$$= \frac{f f'}{\sqrt{f^2+1}} du \wedge dv.$$

$$= \frac{f}{f^2+1} \theta_1 \wedge \theta_2$$

$$\Rightarrow \omega_{12} = \frac{f}{f^2+1} \theta_2 = \frac{f}{\sqrt{f^2+1}} dv$$

$$d\omega_{12} = d\left(\frac{f}{\sqrt{f^2+1}}\right) \wedge dv.$$

$$d\omega_{1,2} = \frac{f' \sqrt{f^2+1} - f \frac{f f'}{\sqrt{f^2+1}}}{f^2+1} du \wedge dv$$

$$d\omega_{1,2} = \frac{f'}{(\sqrt{f^2+1})^3} du \wedge dv$$

$$\theta_1 \wedge \theta_2 = f'(u) \sqrt{f^2+1} du \wedge dv$$

$$\Rightarrow K = -\frac{1}{(f^2+1)^2}$$

Back to the Poincaré half plane:

We are going to find the geodesics

$$E = G = \frac{1}{r^2} \quad F = 0$$

$r$ - Clairault

geodesic equations:

$$u'' - \frac{2}{r} u' r' = 0 \quad r'' + \frac{1}{r} u'^2 - \frac{1}{r} r'^2 = 0$$

(1)  $u' = 0$   $u = c$  constant.  
vertical line.  $r$ -parameter curve.

$r$ -parameter curves are geodesics:

This is a  $r$ -Blainault patch.

$$(2) \quad u' \neq 0 \quad \frac{u''}{u'} = 2 \frac{r'}{r}$$

integrate  $\ln u' = 2 \ln r + \text{const.}$

$$\Rightarrow u' = c r^2 \quad c \text{ constant.}$$

unit speed equation:

$$\frac{u'^2 + r'^2}{r^2} = 1$$

$$\Rightarrow c^2 r^4 + r'^2 = r^2$$

$$r'^2 = r^2 - c^2 r^4 = r^2 (1 - c^2 r^2)$$

$$\Rightarrow r' = \pm r \sqrt{1 - c^2 r^2}$$

divide by  $u'$ :  $\frac{r'}{u'} = \frac{r}{u'} \sqrt{1 - c^2 r^2}$

$$= \frac{r}{c r^2} \sqrt{1 - c^2 r^2}$$

$$\frac{c r r'}{\sqrt{1 - c^2 r^2}} = u'$$



integrate:  $cu = -\sqrt{1-c^2v^2} + K.$

$$(cu - K)^2 = 1 - c^2v^2$$

$$\text{or } (cu - K)^2 + c^2v^2 = 1$$

or half circle with center on x-axis.