

$$\frac{d}{dt} \left(2 \left\langle \frac{DJ}{dt}, J(t) \right\rangle \right) =$$

$$2 \left\langle \frac{D^2 J}{dt^2}, J(t) \right\rangle + 2 \left\langle \frac{DJ}{dt}, \frac{DJ}{dt} \right\rangle$$

evaluate at 0:

$$= 2 \left| \frac{DJ}{dt}(0) \right|^2$$

$$J(t) = d(\exp_q)_{tw}(tw) = \frac{\partial f}{\partial s}(t, 0)$$

$$\frac{DJ}{dt} = \frac{D}{dt} \left(d(\exp_q)_{tw}(tw) \right)$$

$$= \frac{D}{dt} \left(t d(\exp_q)_{tw}(w) \right)$$

$$= d(\exp_q)_{tw}(w) + t \frac{D}{dt} (d(\exp_q)_{tw}(w))$$

evaluate at $t=0$:

$$\frac{DJ}{dt}(0) = d(\exp_q)_0(w) + 0 = w.$$

$$\text{So } \frac{d}{dt} |J(t)|^2 \Big|_{t=0} = 2 |w|^2 = 2.$$

Next: $\frac{d^3}{dt^3} \langle J(t), J(t) \rangle$

$$= \frac{d}{dt} \left(2 \left\langle \frac{D^2 J}{dt^2}, J(t) \right\rangle + 2 \left\langle \frac{DJ}{dt}, \frac{DJ}{dt} \right\rangle \right)$$

$$= 2 \left\langle \frac{D^3 J}{dt^3}, J(t) \right\rangle + 6 \left\langle \frac{D^2 J}{dt^2}, \frac{DJ}{dt} \right\rangle$$

at 0: $= 6 \left\langle \frac{D^2 J}{dt^2}(0), \frac{DJ}{dt}(0) \right\rangle$

Jacobi equation: $\frac{D^2 J}{dt^2} + R(\gamma', J)\gamma' = 0$

evaluate at 0: $\frac{D^2 J}{dt^2}(0) = 0$

so ~~$\frac{d^3}{dt^3} |J(t)|^2$~~ $\frac{d^3}{dt^3} |J(t)|^2 \Big|_{t=0} = 0$

Next and last derivative:

$$\frac{d''}{dt''} |J(t)|^2 = \frac{d}{dt} \left(2 \left\langle \frac{DJ}{dt^3}, J \right\rangle + 6 \left\langle \frac{D^2 J}{dt^2}, \frac{DJ}{dt} \right\rangle \right)$$

$$= 2 \left\langle \frac{D^4 J}{dt^4}, J \right\rangle + 8 \left\langle \frac{D^3 J}{dt^3}, \frac{DJ}{dt} \right\rangle + 6 \left\langle \frac{D^2 J}{dt^2}, \frac{D^2 J}{dt^2} \right\rangle$$

at 0 $= 8 \left\langle \frac{D^3 J}{dt^3}, \frac{DJ}{dt} \right\rangle(0)$

differentiate the Jacobi equation:

$$\frac{D^3 J}{dt^3} + R(\gamma', \frac{DJ}{dt}) \gamma' = 0.$$

so $\frac{D^3 J}{dt^3}(0) \neq -R(\gamma', w) \gamma'$

the coefficient of the Taylor expansion
is : $\frac{8}{4!} \langle -R(v, w)v, w \rangle$
 $= -\frac{1}{3} K(\sigma)$ □.

Remark: γ' & $t\gamma'$ are Jacobi fields

$$\frac{D^2\gamma'}{dt^2} = 0 = R(\gamma', \gamma') \gamma'$$

So we restrict ourselves to Jacobi fields normal to γ .

Example: Manifolds with constant sectional curvature.

Recall: $K(\sigma) = K_0 + \sigma \cdot \begin{matrix} \oplus \\ (3.4) \end{matrix}$

$$(X, Y, Z, T) = K_0 (\langle X, T \rangle \langle Y, Z \rangle - \langle Y, T \rangle \langle X, Z \rangle)$$

$$\text{where } (X, Y, Z, T) = \langle R(X, Y)Z, T \rangle$$

$$\begin{aligned} \text{So } \langle R(\gamma', J)\gamma', T \rangle &= \\ &= -K_0 (\langle \gamma', T \rangle \langle \gamma', J \rangle - \langle J, T \rangle \langle \gamma', \gamma' \rangle) \\ &\quad \forall \text{ vector field } T. \end{aligned}$$

$$S_0 \quad R(\gamma', J)\gamma' = -K_0(\langle \gamma', J \rangle \gamma - \langle \gamma', \gamma' \rangle J)$$

If J is normal to γ , and γ' has length 1, we obtain:

$$R(\gamma', J)\gamma' = + K_0 J$$

and the Jacobi equation becomes

$$\frac{D^2 J}{dt^2} + K_0 J = 0$$

Recall that if $\{e_1(t), \dots, e_n(t)\}$ is an orthonormal frame and if we write $J = \sum_{i=1}^n g_i \cdot e_i$, then the Jacobi equation becomes:

$$+ j \quad g_j''(t) + \sum_{i=1}^n a_{ij} \cdot g_i(t) = 0$$

$$\begin{aligned} \text{where } a_{ij} &= \langle R(\gamma', e_i) \gamma', e_j \rangle \\ &= K_0 (-\langle \gamma', e_j \rangle \langle \gamma', e_i \rangle + \langle \gamma', \gamma' \rangle \langle e_i, e_j \rangle) \\ &= K_0 (\delta_{ij} - \langle \gamma', e_j \rangle \langle \gamma', e_i \rangle) \end{aligned}$$

Choose $e_1 = \gamma'$, then $a_{ij} = K_0 (\delta_{ij} - \delta_{1i} \delta_{1j})$
and $g_1 = 0$

If, for instance $J = g_2 e_2$, then

$$g_2'' + a_{22} g_2' g_2 = 0$$

$$\text{and } a_{22} = k_0$$

$$\text{so } g_2'' + a k_0 g_2' g_2 = 0$$

g_2 = combination of sine and cosine

Proposition : (2.4) $\gamma: [0, a] \rightarrow M$

a geodesic, $\gamma(0) = q$.

J a Jacobi field along γ s.t. $J(0) = 0$.

Denote $\gamma'(0) = v$, $\frac{DJ}{dt}(0) = w$.

Then $J(t) = d(\exp_q)_{tv}(tw)$
 $= \frac{\partial f}{\partial s}(t, 0)$ where

$$f(t, s) = \exp_q\left(\frac{t}{a}v(s)\right)$$

with $v(s)$ a curve in $T_{\alpha s}(T_q M)$

with $v(0) = av$ and $v'(0) = w$.

Proof: Both vector fields satisfy the
Jacobi equation, so they are equal

if and only if they satisfy the same initial conditions.

$$J(0) = 0 \quad \text{and} \quad d(\exp_q)_{t=0}(0) = 0$$

$\frac{D}{dt} J(0) = w$, we saw earlier that

$$\frac{D}{dt} (d(\exp_q)_{t=w}(tw)) = wr.$$

□.

Conjugate points and the critical points of \exp .

A critical point of \exp_q ($q \in M$) is a point where $d(\exp_q)$ fails to be injective $\Leftrightarrow d(\exp_q)$ fails to be injective because

$T_q M$ and M have the same dim.

$d(\exp_q)_{t=0}$ fails to be injective

if $\exists w \in T_w(T_q M)$ s.t.

$$d(\exp_q)_{t=0}(w) = 0.$$

Def: Let $\varphi \in M$ be a point, a point $q \in M$ is a conjugate point along a geodesic γ if

$$\gamma: [0, a] \rightarrow M.$$

$\gamma(0) = p$, $\exists t_0$ s.t. $\gamma(t_0) = q$
and \exists Jacobi field along γ s.t.

$$J(0) = 0 = J(t_0)$$

Note, then $J(t) = d(\exp_p)_{t\gamma}(tw)$

$$\text{where } v = \gamma'(0) \text{ and } w = \frac{dJ}{dt}(0)$$

$$\text{and } J(0) = 0 = d(\exp_p)_{t\gamma}(t_0 w).$$

So $t\gamma$ is a critical point of $d(\exp_p)$ ^{↑ not needed}

Def: The multiplicity of a conjugate point is the number of linearly independent Jacobi fields with the property $J(0) = J(t_0) = 0$.

Note that γ' and $t\gamma'$ are Jacobi fields.
 $\gamma'(0) \neq 0$ but $(t\gamma')(0) = 0$

$$\frac{D}{dt} (t\gamma') = \gamma' + t \frac{D\gamma'}{dt} = \gamma' \text{ never } 0.$$

There are ~~at least~~ n linearly indep. Jacobi fields s.t. $J(0)=0$ one of them is never 0 outside of p , then \exists at most $n-1$ linearly indep. J_i fields that can vanish at $\gamma(t_0)$. So multiplicity $\leq n-1$.