

POSITIVE POLYNOMIALS IN SCALAR AND MATRIX VARIABLES, THE SPECTRAL THEOREM AND OPTIMIZATION

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ABSTRACT. We follow a stream of the history of positive matrices and positive functionals, as applied to algebraic sums of squares decompositions, with emphasis on the interaction between classical moment problems, function theory of one or several complex variables and modern operator theory. The second part of the survey focuses on recently discovered connections between real algebraic geometry and optimization as well as polynomials in matrix variables and some control theory problems. These new applications have prompted a series of recent studies devoted to the structure of positivity and convexity in a free $*$ -algebra, the appropriate setting for analyzing inequalities on polynomials having matrix variables. We sketch some of these developments, add to them and comment on the rapidly growing literature.

1. INTRODUCTION

This is an essay, addressed to non-experts, on the structure of positive polynomials on semi-algebraic sets, various facets of the spectral theorem for Hilbert space operators, inequalities and sharp constraints for elements of a free $*$ -algebra, and some recent applications of all of these to polynomial optimization and engineering. The circle of ideas exposed below is becoming increasingly popular but not known in detail outside the traditional groups of workers in functional analysis or real algebra who have developed parts of it. For instance, it is not yet clear how to teach and facilitate the access of beginners to this beautiful emerging field. The exposition of topics below may provide elementary ingredients for such a course.

The unifying concept behind all the apparently diverging topics mentioned above is the fact that universal positive functions (in appropriate rings) are sums of squares. Indeed, when we prove inequalities we essentially complete squares, and on the other hand when we do spectral analysis we decompose a symmetric or a hermitian form into a weighted (possibly continuous) sum or difference of squares. There are of course technical difficulties on each side, but they do not obscure the common root of algebraic versus analytical positivity.

We will encounter quite a few positivity criteria, expressed in terms of: matrices, kernels, forms, values of functions, parameters of continued fractions, asymptotic expansions and algebraic certificates. Dual to sums of squares and the main positive objects we study are the power moments of positive measures, rapidly decaying at infinity. These moments will be regarded as discrete data given by fixed coordinate frames in the correspondence between an algebra (of polynomials or operators) and its spectrum, with restrictions on its location. Both concepts of real spectrum (in algebraic geometry) and joint spectrum (in operator theory) are naturally connected

in this way to moment problems. From the practitioner's point of view, moments represent observable/computable numerical manifestations of more complicated entities.

It is not a coincidence that the genius of Hilbert presides over all aspects of positivity we will touch. We owe him the origins and basic concepts related to: the spectral theorem, real algebra, algebraic geometry and mathematical logic. As ubiquitous as it is, a Hilbert space will show up unexpectedly and necessarily in the proofs of certain purely algebraic statements. On the other hand our limited survey does not aim at offering a comprehensive picture of Hilbert's much wider legacy.

Not unexpected, or, better later than never, the real algebraist's positivity and the classical analyst's positive definiteness have recently merged into a powerful framework; this is needed and shaped by several applied fields of mathematics. We will bring into our discussion one principal customer: control theory. The dominant development in linear systems engineering in the 1990's was matrix inequalities and many tricks and ad hoc techniques for making complicated matrix expressions into tame ones, indeed into the Linear Matrix Inequalities, LMIs, loved by all who can obtain them. Since matrices do not commute a large portion of the subject could be viewed as manipulation of polynomials and rational functions of non-commuting (free) variables, and so a beginning toward helpful mathematical theory would be a semi-algebraic geometry for free $*$ -algebras, especially its implications for convexity. Such ventures sprung to life within the last five years and this article attempts to introduce, survey and fill in some gaps in this rapidly expanding area of noncommutative semi-algebraic geometry.

The table of contents offers an idea of the topics we touch in the survey and what we left outside. We are well aware that in a limited space while viewing a wide angle, as captives of our background and preferences, we have omitted key aspects. We apologize in advance for all our omissions in this territory, and for inaccuracies when stepping on outer domains; they are all non-intentional and reflect our limitations. Fortunately, the reader will have the choice of expanding and complementing our article with several recent excellent surveys and monographs (mentioned throughout the text and some recapitulated in the last section).

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We dedicate these pages to Tibi Constantinescu, old time friend and colleague, master of all aspects of matrix positivity.

2. THE SPECTRAL THEOREM

The modern proof of the spectral theorem for self-adjoint or unitary operators uses commutative Banach algebra techniques, cf. for instance [D03]. This perspective departs from the older, and more constructive approach imposed by the original study of special classes of integral operators. In this direction, we reproduce below an early idea of F. Riesz [R13] for defining the spectral scale of a self-adjoint operator from a minimal set of simple observations, one of them being the structure of positive polynomials on a real interval.

2.1. Self-adjoint operators. Let H be a separable, complex Hilbert space and let $A \in \mathcal{L}(H)$ be a linear, continuous operator acting on H . We call A *self-adjoint* if $A = A^*$, that is $\langle Ax, x \rangle \in \mathbb{R}$ for all vectors $x \in H$. The continuity assumption implies the existence of bounds

$$(2.1) \quad m\|x\|^2 \leq \langle Ax, x \rangle \leq M\|x\|^2, \quad x \in H.$$

The operator A is called *non-negative*, denoted in short $A \geq 0$, if

$$\langle Ax, x \rangle \geq 0, \quad x \in H.$$

The operator A is *positive* if it is non-negative and $(\langle Ax, x \rangle = 0) \Rightarrow (x = 0)$.

We need a couple of basic observations, see §104 of [RN90]. The real algebraists should enjoy comparing these facts with the axioms of an order in an arbitrary ring.

a). *A bounded monotonic sequence of self-adjoint operators converges (in the strong operator topology) to a self-adjoint operator.*

Indeed, assume $0 \leq A_1 \leq A_2 \leq \dots \leq I$ and take $B = A_{n+k} - A_n$ for some fixed values of $n, k \in \mathbb{N}$. Observe that $0 \leq B \leq I$, so Cauchy-Schwarz' inequality holds for the bilinear form $\langle Bx, y \rangle$. Use this to get: $\langle Bx, Bx \rangle^2 \leq \langle Bx, x \rangle \langle B^2x, Bx \rangle \leq \langle Bx, x \rangle \langle Bx, Bx \rangle$, from which

$$\|Bx\|^2 = \langle Bx, Bx \rangle \leq \langle Bx, x \rangle$$

Thus, for every vector $x \in H$:

$$\|A_{n+k}x - A_nx\|^2 \leq \langle A_{n+k}x, x \rangle - \langle A_nx, x \rangle.$$

Since the sequence $\langle A_n x, x \rangle$ is bounded and monotonic, it has a limit. Hence $\lim_n A_n x$ exists for every $x \in H$, which proves the statement.

b). *Every non-negative operator A admits a unique non-negative square root \sqrt{A} : $(\sqrt{A})^2 = A$.*

For the proof one can normalize A , so that $0 \leq A \leq I$ and use a convergent series decomposition for $\sqrt{x} = \sqrt{1 - (1 - x)}$, in conjunction with the above remark. See for details §104 of [RN90].

Conversely, if $T \in L(H)$, then $T^*T \geq 0$.

c). *Let A, B be two commuting non-negative (linear bounded) operators. Then AB is also non-negative.*

Note that, if $AB = BA$, the above proof implies $\sqrt{BA} = A\sqrt{B}$. For the proof we compute directly

$$\begin{aligned} \langle ABx, x \rangle &= \langle A\sqrt{B}\sqrt{B}x, x \rangle = \\ \langle \sqrt{B}A\sqrt{B}x, x \rangle &= \langle A\sqrt{B}x, \sqrt{B}x \rangle \geq 0. \end{aligned}$$

With the above observations we can enhance the polynomial functional calculus of a self-adjoint operator. Let $\mathbb{C}[t], \mathbb{R}[t]$ denote the algebra of polynomials with complex, respectively real, coefficients in one variable and let $A = A^*$ be a self-adjoint operator with bounds (2.1). The expression $p(A)$ makes sense for every $p \in \mathbb{C}[t]$, and the polynomial functional calculus for A which is the map ϕ

$$p \mapsto p(A)$$

is obviously linear, multiplicative and unital (1 maps to I). Less obvious is the key fact that that ϕ is positivity preserving:

Proposition 2.1. *If the polynomial $p \in \mathbb{R}[t]$ satisfies $p(t) \geq 0$ for all t in $[m, M]$ and the self-adjoint operator A satisfies $mI \leq A \leq MI$, then $p(A) \geq 0$.*

Proof. A decomposition of the real polynomial p into irreducible, real factors yields:

$$p(t) = c \prod_i (t - \alpha_i) \prod_j (\beta_j - t) \prod_k [(t - \gamma_k)^2 + \delta_k^2],$$

with $c > 0$, $\alpha_i \leq m \leq M \leq \beta_j$ and $\gamma_k \in \mathbb{R}, \delta_k \in \mathbb{R}$. According to the observation c) above, we find $p(A) \geq 0$. ■

The proposition immediately implies

Corollary 2.2. *The homomorphism ϕ on $\mathbb{C}[t]$ extends to $C[m, M]$ and beyond. Moreover,*

$$\|p(A)\| \leq \sup_{[m, M]} |p| =: \|p\|_\infty.$$

Proof. The inequality follows because $\sup_{[m, M]} |p| \pm p$ is a polynomial non-negative on $[m, M]$, so $\|p\|_\infty I \geq \pm p(A)$ which gives the required inequality. Thus ϕ is sup norm continuous and extends by continuity to the completion of the polynomials, which is of course the algebra $C[m, M]$ of the continuous functions.

The Spectral Theorem immediately follows.

Theorem 2.3. *If the self adjoint bounded operator A on H has a cyclic vector ξ , then there is a positive Borel measure μ on $[m, M]$ and a unitary operator $U : H \mapsto L^2(\mu)$ identifying H with $L^2(\mu)$ such that*

$$UAU^* = M_x.$$

Here for any g in L^∞ the multiplication operator M_g is defined by $M_g f = gf$ on all $f \in L^2(\mu)$.

The vector ξ cyclic means

$$\text{span} \{A^k \xi : k = 0, 1, 2, \dots\} = \{p(A)\xi : p \text{ a polynomial}\}$$

is dense in H .

Proof Define a linear functional $L : C([m, M]) \mapsto \mathbb{C}$ by

$$L(f) := \langle f(A)\xi, \xi \rangle \quad \text{for all } f \in C([m, M]).$$

The Representation Theorem (see Proposition 3.2 for more detail) for such L says there is a Borel measure μ such that

$$L(f) = \int_{[m, M]} f d\mu;$$

moreover, μ is a positive measure because if $f \geq 0$ on $[m, M]$, then $L(f) \geq 0$. A critical feature is

$$(2.2) \quad \int p\bar{q} d\mu = \langle p(A)\xi, q(A)\xi \rangle$$

which holds, since $= L(p\bar{q}) = \langle p(A)\bar{q}(A)\xi, \xi \rangle$. We have built our representing space (using a formula which haunts the rest of this paper) and now we identify H with this space.

Define U by $Up(A)\xi = p$ which specifies it on a dense set (by the cyclic assumption) provided $Up_1(A)\xi = Up_2(A)\xi$ implies $e(A)\xi := p_1(A)\xi - p_2(A)\xi = 0$; in other words, $0 = \langle e(A)\xi, q(A)\xi \rangle$ for all polynomials q . Thus $0 = \int e\bar{q} d\mu$, so $e = 0$ a.e. wrt μ . Now to properties of U :

- (1) U is isometric. (That is what (2.2) says.) Thus U extends to H and has closed range.
- (2) The range of U is dense since it contains the polynomials.
- (3) $UAp(A)\xi = xp(x) = xUp(A)\xi$ for all polynomials p . By the density imposed by cyclicity for any v in H we have

$$UA v = M_x U v.$$

Note the constrection gives $U\xi = 1$. ■

2.2. A bigger functional calculus and spectral measures. Our next aim is to consider a bounded, increasing sequence p_n of real polynomial functions on the interval $[m, M]$ and define, according to observation a):

$$f(A)x = \lim p_n(A)x, \quad x \in H,$$

where f is a point-wise limit of p_n . A standard argument shows that, if q_n is another sequence of polynomials, monotonically converging on $[m, M]$ to f , then

$$\lim q_n(A)x = \lim p_n(A)x, \quad x \in H.$$

See for details §106 of [RN90]. The new calculus $f \mapsto f(A)$ remains linear and multiplicative.

In particular, we can apply the above definition to the step functions

$$\chi_s(t) = \begin{cases} 1, & t \leq s, \\ 0, & t > s. \end{cases}$$

This yields a monotonic, operator valued function

$$F_A(s) = \chi_s(A),$$

with the additional properties $F_A(s) = F_A(s)^* = F_A(s)^2$ and

$$F_A(s) = \begin{cases} 0, & s < m, \\ I, & s \geq M. \end{cases}$$

With the aid of this *spectral scale* one can interpret the functional calculus as an operator valued Riemann-Stieltjes integral

$$f(A) = \int_m^M f(t) dF_A(t).$$

The *spectral measure* E_A of A is the operator valued measure associated to the monotonic function F_A , that is, after extending the integral to Borel sets σ ,

$$E_A(\sigma) = \int_{\sigma \cap [m, M]} dF_A(t).$$

Thus $E_A(\sigma)$ is a family of mutually commuting orthogonal projections, subject to the multiplicativity constraint

$$E_A(\sigma \cap \tau) = E_A(\sigma)E_A(\tau).$$

As a matter of notation, we have then for every bounded, Borel measurable function f :

$$(2.3) \quad f(A) = \int_m^M f(t)E_A(dt).$$

This is a form of the Spectral Theorem which does not assume cyclicity.

A good exercise for the reader is to identify the above objects in the case of a finite dimensional Hilbert space H and a self-adjoint linear transformation A acting on it. A typical infinite dimensional example will be discussed later in connection with the moment problem.

2.3. Unitary operators. The spectral theorem for a unitary transformation $U \in L(H)$, $U^*U = UU^* = I$, can be derived in a very similar manner.

The needed structure of positive polynomials is contained in the following classical result.

Lemma 2.4 (Riesz-Fejér). *A non-negative trigonometric polynomial is the modulus square of a trigonometric polynomial.*

Proof. Let $p(e^{i\theta}) = \sum_{-d}^d c_j e^{ij\theta}$ and assume that $p(e^{i\theta}) \geq 0$, $\theta \in [0, 2\pi]$. Then necessarily $c_{-j} = \bar{c}_j$. By passing to complex coordinates, the rational function $p(z) = \sum_{-d}^d c_j z^j$ must be identical to $\overline{p(1/\bar{z})}$. That is its zeros and poles are symmetrical (in the sense of Schwarz) with respect to the unit circle.

Write $z^d p(z) = q(z)$, so that q is a polynomial of degree $2d$. One finds, in view of the mentioned symmetry:

$$q(z) = cz^\nu \prod_j (z - \lambda_j)^2 \prod_k (z - \mu_k)(z - 1/\bar{\mu}_k),$$

where $c \neq 0$ is a constant, $|\lambda_j| = 1$ and $0 < |\mu_k| < 1$.

For $z = e^{i\theta}$ we obtain

$$\begin{aligned} p(e^{i\theta}) &= |p(e^{i\theta})| = |q(e^{i\theta})| = \\ &= |c| \prod_j |e^{i\theta} - \lambda_j|^2 \prod_k \frac{|e^{i\theta} - \mu_k|^2}{|\mu_k|^2}. \end{aligned}$$

■

Returning to the unitary operator U we infer, for $p \in \mathbb{C}[z]$,

$$\Re p(e^{i\theta}) \geq 0 \quad \Rightarrow \quad \Re p(U) \geq 0.$$

Indeed, according to the above Lemma, $\Re p(e^{i\theta}) = |q(e^{i\theta})|^2$, whence

$$\Re p(U) = q(U)^* q(U) \geq 0.$$

Then, exactly as in the preceding section one constructs the spectral scale and spectral measure of U .

For an operator T we denote its “real part” and “imaginary part” by $\Re T = (T + T^*)/2$ and $\Im T = (T - T^*)/2i$.

The reader will find other elementary facts (à la Riesz-Fejér’s Lemma) about the decompositions of non-negative polynomials into sums of squares in the second volume of Polya and Szegő’s problem book [PS25]. This particular collection of observations about positive polynomials reflects, from the mathematical analyst point of view, the importance of the subject in the first two decades of the XX-th century.

2.4. Riesz-Herglotz formula. The practitioners of spectral analysis know that the strength and beauty of the spectral theorem lies in the effective dictionary it establishes between matrices, measures and analytic functions. In the particular case of unitary operators, these correspondences also go back to F. Riesz. The classical Riesz-Herglotz formula is incorporated below in a more general statement. To keep the spirit of positivity of the last sections, we are interested below in the *additive* (rather than multiplicative) structure of polynomials (or more general functions) satisfying Riesz-Fejér’s condition:

$$\Re p(z) \geq 0, \quad |z| < 1.$$

We denote by \mathbb{D} the unit disk in the complex plane. Given a set X by a *positive semi-definite kernel* we mean a function $K : X \times X \rightarrow \mathbb{C}$ satisfying

$$\sum_{i,j=1}^N K(x_i, x_j) c_i \bar{c}_j \geq 0,$$

for every finite selection of points $x_1, \dots, x_N \in X$ and complex scalars c_1, \dots, c_N .

Theorem 2.5. *Let $f : \mathbb{D} \rightarrow \mathbb{C}$ be an analytic function. The following statements are equivalent:*

a). $\Re f(z) \geq 0, \quad z \in \mathbb{D},$

b). (*Riesz-Herglotz formula*). *There exists a positive Borel measure μ on $[-\pi, \pi]$ and a real constant C , such that:*

$$f(z) = iC + \int_{-\pi}^{\pi} \frac{e^{it} + z}{e^{it} - z} d\mu(t), \quad z \in \mathbb{D},$$

c). The kernel $K_f : \mathbb{D} \times \mathbb{D} \longrightarrow \mathbb{C}$,

$$K_f(z, w) = \frac{f(z) + \overline{f(w)}}{1 - z\overline{w}}, \quad z, w \in \mathbb{D},$$

is positive semi-definite,

d). There exists a unitary operator $U \in \mathcal{L}(H)$, a vector $\xi \in H$ and a constant $a \in \mathbb{C}$, $\Re a \geq 0$, such that:

$$f(z) = a + z\langle (U - z)^{-1}\xi, \xi \rangle, \quad z \in \mathbb{D}.$$

Proof. We merely sketch the main ideas in the proof. The reader can consult for details the monograph [AM02].

a) \Rightarrow b). Let $r < 1$. As a consequence of Cauchy's formula:

$$f(z) = i\Im f(0) + \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{re^{it} + z}{re^{it} - z} \Re f(re^{it}) dt, \quad |z| < r.$$

Since the positive measures $\frac{1}{2\pi} \Re f(re^{it}) dt$ have constant mass on $[-\pi, \pi]$:

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} \Re f(re^{it}) dt = \Re f(0), \quad r < 1,$$

they form a weak- $*$ relatively compact family (in the space of finite measures). Any weak- $*$ limit will satisfy the identity in b) (hence all limit points coincide).

b) \Rightarrow c). A direct computation yields:

$$(2.4) \quad K_f(z, w) = \int_{-\pi}^{\pi} \frac{2}{(e^{it} - z)(e^{-it} - \overline{w})} d\mu(t), \quad z, w \in \mathbb{D}.$$

Since for a fixed value of t , the integrand is positive semi-definite, and we average over a positive measure, the whole kernel will turn out to be positive semi-definite.

c) \Rightarrow a). Follows by evaluating K_f on the diagonal:

$$2\Re f(z) = (1 - |z|^2)K_f(z, z) \geq 0.$$

b) \Rightarrow d). Let $H = L^2(\mu)$ and $Uf(t) = e^{it}f(t)$. Then U is a unitary operator, and the constant function $\xi = \sqrt{2}$ yields the representation d).

d) \Rightarrow b). In view of the spectral theorem, we can evaluate the spectral measure E_U on the vector ξ and obtain a positive measure μ satisfying:

$$\begin{aligned} f(z) &= a + z\langle (U - z)^{-1}\xi, \xi \rangle = a + z \int_{-\pi}^{\pi} \frac{d\mu(t)}{e^{it} - z} = \\ &= a + \frac{1}{2} \int_{-\pi}^{\pi} \frac{e^{it} + z}{e^{it} - z} d\mu(t) - \frac{1}{2} \int_{-\pi}^{\pi} d\mu(t), \quad z \in \mathbb{D}. \end{aligned}$$

By identifying the constants we obtain, up to the factor 2, conclusion b). \blacksquare

The theorem above has far reaching consequences in quite divergent directions: function theory, operator theory and control theory of linear systems, see for instance [AM02, FF90, M03, RR97]. We confine ourselves to describe only a generic consequence.

First, we recall that, exactly as in the case of finite matrices, a positive semi-definite kernel can be written as a sum of squares. Indeed, if $K : X \times X \rightarrow \mathbb{C}$ is positive semi-definite, one can define a sesqui-linear form on the vector space $\oplus_{x \in X} \mathbb{C}$, with basis $e(x), x \in X$, by

$$\left\| \sum_i c_i e(x_i) \right\|^2 = \sum_{i,j=1}^N K(x_i, x_j) c_i \bar{c}_j.$$

This is a positive semi-definite inner product. The associated separated (i.e. Hausdorff) Hilbert space completion H carries the classes of the vectors $[e(x)] \in H$. They factor K into a sum of squares:

$$K(x, y) = \langle [e(x)], [e(y)] \rangle = \sum_k \langle [e(x)], f_k \rangle \langle f_k, [e(y)] \rangle,$$

where (f_k) is any orthonormal basis of H . For details, see for instance the Appendix to [RN90].

The following result represents the quintessential bounded analytic interpolation theorem.

Theorem 2.6 (Nevanlinna-Pick). *Let $\{a_i \in \mathbb{D}; i \in I\}$ be a set of points in the unit disk, and let $\{c_i \in \mathbb{C}; \Re c_i \geq 0, i \in I\}$ be a collection of points in the right half-plane, indexed over the same set.*

There exists an analytic function f in the unit disk, with $\Re f(z) \geq 0, |z| < 1$, and $f(a_i) = c_i, i \in I$, if and only if the kernel

$$\frac{c_i + \bar{c}_j}{1 - a_i \bar{a}_j}, \quad i, j \in I,$$

is positive semi-definite.

Proof. Point c) in the preceding Theorem shows that the condition is necessary.

A Moebius transform in the range ($f \mapsto g = (f - 1)/(f + 1)$) will change the statement into:

$$g : \mathbb{D} \rightarrow \mathbb{D}, \quad g(a_i) = d_i,$$

if and only if the kernel

$$\frac{1 - d_i \bar{d}_j}{1 - a_i \bar{a}_j}, \quad i, j \in I,$$

is positive semi-definite.

To prove that the condition in the statement is also sufficient, assume that the latter kernel is positive semi-definite. As before, factor it (into a sum of squares):

$$\frac{1 - d_i \bar{d}_j}{1 - a_i \bar{a}_j} = \langle h(i), h(j) \rangle, \quad i, j \in I,$$

where $h : I \rightarrow H$ is a function with values in an auxiliary Hilbert space H .

Then

$$1 + \langle a_i h(i), a_j h(j) \rangle = d_i \bar{d}_j + \langle h(i), h(j) \rangle, \quad i, j \in I.$$

The preceding identity can be interpreted as an equality between scalar products in $\mathbb{C} \oplus H$:

$$\left\langle \begin{pmatrix} 1 \\ a_i h(i) \end{pmatrix}, \begin{pmatrix} 1 \\ a_j h(j) \end{pmatrix} \right\rangle = \left\langle \begin{pmatrix} d_i \\ h(i) \end{pmatrix}, \begin{pmatrix} d_j \\ h(j) \end{pmatrix} \right\rangle, \quad i, j \in I.$$

Let $H_1 \subset \mathbb{C} \oplus H$ be the linear span of the vectors $(1, a_i h(i))^T$, $i \in I$. The map

$$V \begin{pmatrix} 1 \\ a_i h(i) \end{pmatrix} = \begin{pmatrix} d_i \\ h(i) \end{pmatrix}$$

extends then by linearity to an isometric transformation $V : H_1 \rightarrow H$. Since the linear isometry V can be extended (for instance by zero on the orthogonal complement of H_1) to a contractive linear operator $T : \mathbb{C} \oplus H \rightarrow \mathbb{C} \oplus H$, we obtain a block matrix decomposition of T satisfying:

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{pmatrix} 1 \\ a_i h(i) \end{pmatrix} = \begin{pmatrix} d_i \\ h(i) \end{pmatrix}.$$

Since $\|D\| \leq 1$, the operator $I - zD$ is invertible for all $z \in \mathbb{D}$. From the above equations we find, after identifying A with a scalar:

$$h(i) = (I - a_i D)^{-1} C 1, \quad d_i = A + a_i B h(i).$$

We define the analytic function

$$g(z) = A + z B (I - z D)^{-1} C 1, \quad |z| < 1.$$

It satisfies, as requested: $g(a_i) = d_i$, $i \in I$.

By reversing the above reasoning we infer, with $h(z) = (I - z D)^{-1} C 1 \in H$:

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{pmatrix} 1 \\ z h(z) \end{pmatrix} = \begin{pmatrix} g(z) \\ h(z) \end{pmatrix}.$$

Since T is a contraction,

$$\|g(z)\|^2 + \|h(z)\|^2 \leq 1 + \|z h(z)\|^2 \leq 1 + \|h(z)\|^2, \quad |z| < 1,$$

whence

$$|g(z)| \leq 1, \quad |z| < 1.$$

■

The above proof contains the germ of what experts in control theory call “realization theory”. For the present survey it is illustrative as a constructive link between matrices and analytic functions with bounds; it will also be useful as a model to follow in more general, non-commutative settings.

A great deal of research was done in the last two decades on analogs of Riesz-Herglotz type formulas in several complex variables. As expected, when generalizing to \mathbb{C}^n , there are complications and surprises on the road. See for instance [AM02, BT98, CW99, EP02] and in several non-commuting variables [BGM05, K05]. We will return to some of these topics from the perspective of positive polynomials and moment sequences.

2.5. von Neumann’s inequality. We have just seen that the heart of the spectral theorem for self-adjoint or unitary operators was the positivity of the polynomial functional calculus. A surprisingly general inequality, of the same type, applicable to an arbitrary bounded operator, was discovered by von Neumann [vN2].

Theorem 2.7. *Let $T \in \mathcal{L}(H)$, $\|T\| \leq 1$, be a contractive operator. If a polynomial $p \in \mathbb{C}[z]$ satisfies $\Re p(z) \geq 0$, $z \in \mathbb{D}$, then $\Re p(T) \geq 0$.*

Proof. According to Riesz-Herglotz formula we can write

$$p(z) = iC + \int_{-\pi}^{\pi} \frac{e^{it} + z}{e^{it} - z} d\mu(t), \quad |z| < 1,$$

where $C \in \mathbb{R}$ and μ is a positive measure.

Fix $r < 1$, close to 1, and evaluate the above representation at $z = rT$:

$$p(rT) = iC + \int_{-\pi}^{\pi} (e^{it} + rT)(e^{it} - rT)^{-1} d\mu(t).$$

Therefore

$$\begin{aligned} p(rT) + p(rT)^* &= \\ \int_{-\pi}^{\pi} (e^{it} - rT)^{-1} [(e^{it} + rT)(e^{-it} - rT^*) + (e^{it} - rT)(e^{-it} + rT^*)] (e^{-it} - rT^*)^{-1} d\mu(t) &= \\ 2 \int_{-\pi}^{\pi} (e^{it} - rT)^{-1} [I - r^2 TT^*] (e^{-it} - rT^*)^{-1} d\mu(t) &\geq 0. \end{aligned}$$

Letting $r \rightarrow 1$ we find $\Re p(T) \geq 0$. ■

A Moebius transform argument, as in the proof of Nevanlinna-Pick Theorem, yields the equivalent statement (for a contractive linear operator T):

$$(|p(z)| \leq 1, \quad |z| < 1) \Rightarrow \|p(T)\| \leq 1.$$

Von Neumann’s original proof relied on the continued fraction structure of the analytic functions from the disk to the disk. The recursive construction of the continued fraction goes back to Schur [S18] and can be explained

in a few lines.

Schur's algorithm. Let $f : \mathbb{D} \rightarrow \mathbb{D}$ be an analytic function. Then, in view of Schwarz Lemma, there exists an analytic function $f_1 : \mathbb{D} \rightarrow \mathbb{D}$ with the property:

$$\frac{f(z) - f(0)}{1 - \overline{f(0)}f(z)} = zf_1(z),$$

or equivalently, writing $s_0 = f(0)$:

$$f(z) = \frac{s_0 + zf_1(z)}{1 + \overline{s_0}zf_1(z)}.$$

In its turn,

$$f_1(z) = \frac{s_1 + zf_2(z)}{1 + \overline{s_1}zf_2(z)},$$

with an analytic $f_2 : \mathbb{D} \rightarrow \mathbb{D}$, and so on.

This algorithm terminates after finitely many iterations for finite Blaschke products

$$f(z) = \prod_{k=1}^N \frac{z - \lambda_k}{1 - \overline{\lambda_k}z}, \quad |\lambda_k| < 1.$$

Its importance lies in the fact that the finite section of Schur parameters (s_0, s_1, \dots, s_n) depends via universal expressions on the first section (same number) of Taylor coefficients of f at $z = 0$. Thus, the conditions

$$|s_0(c_0)| \leq 1, \quad |s_1(c_0, c_1)| \leq 1, \dots$$

characterize which power series

$$c_0 + c_1z + c_2z^2 + \dots,$$

are associated to analytic functions from the disk to the disk. For details and a variety of applications, see [Constantinescu96, FF90, RR97].

One notable application is to solve the classical Carathéodory-Fejér interpolation problem, a close relative of the Nevanlinna-Pick problem we presented earlier. Here one specifies complex numbers c_0, \dots, c_m and seeks $f : \mathbb{D} \rightarrow \mathbb{D}$ analytic for which

$$\frac{1}{j!} \frac{d^j f}{dz^j}(0) = c_j, \quad j = 0, \dots, m.$$

The Schur Algorithm constructs such a function and in the same time gives a simple criterion when the solution exists. Alternatively, a special type of matrix $(c_{n-m})_{n,m=0}^m$, with zero entries under the diagonal ($c_j = 0$, $j < 0$), called a Toeplitz matrix, based on c_0, \dots, c_m is a contraction if and only if a solution to the Carathéodory-Fejér problem exists. A version of this fact in the right half plane (rather than the disk) is proved in Theorem 3.3.

As another application, we can derive (also following Schur) an effective criterion for deciding whether a polynomial has all roots inside the unit disk.

Let

$$p(z) = c_d z^d + c_{d-1} z^{d-1} + \dots + c_0 \in \mathbb{C}[z],$$

and define

$$p^b(z) = z^d \overline{p(1/\bar{z})} = \bar{c}_0 z^d + \bar{c}_1 z^{d-1} + \dots + \bar{c}_d.$$

It is clear that

$$|p(e^{it})| = |p^b(e^{it})|, \quad t \in [-\pi, \pi],$$

and that the roots of p^b are symmetric with respect to the unit circle to the roots of p . Therefore, p has all roots contained in the open unit disk if and only if $\frac{p}{p^b}$ is an analytic function from the disk to the disk, that is, if and only if the kernel

$$\frac{p^b(z) \overline{p^b(w)} - p(z) \overline{p(w)}}{1 - z\bar{w}}, \quad z, w \in \mathbb{D},$$

is positive definite. As a matter of fact $\frac{p}{p^b}$ is a finite Blaschke product, and Schur's algorithm terminates in this case after finitely many iterations.

In general, regarded as a Hermitian form, evaluated to the variables $Z_i = z^i, 0 \leq i \leq d$, the signature of the above kernel (that is the number of zeros, negative and positive squares in its canonical decomposition) counts how many roots the polynomial p has inside the disk, and on its boundary. For many more details see the beautiful survey [KN81].

3. MOMENT PROBLEMS

In this section we return to Hilbert space and the spectral theorem, by unifying the analysis and algebra concepts we have discussed in the previous sections. This is done in the context of power moment problems, one of the oldest and still lively sources of questions and inspiration in mathematical analysis.

As before, $x = (x_1, \dots, x_g)$ stands for the coordinates in \mathbb{R}^g , and, at the same time, for a tuple of commuting indeterminates. We adopt the multi-index notation $x^\alpha = x_1^{\alpha_1} \dots x_g^{\alpha_g}$, $\alpha \in \mathbb{N}^g$. Let μ be a positive, rapidly decreasing measure on \mathbb{R}^g . The *moments* of μ are the real numbers:

$$a_\alpha = \int x^\alpha d\mu(x), \quad \alpha \in \mathbb{N}^g.$$

For its theoretical importance and wide range of applications, the correspondence

$$\{\mu; \text{positive measure}\} \longrightarrow \{(a_\alpha); \text{moment sequence}\}$$

can be put on an equal level with the Fourier-Laplace, Radon or wavelet transforms. It is the positivity of the original measure which makes the

analysis of this category of moment problems interesting and non-trivial, and appropriate for our discussion. For general aspects and applications of moment problems (not treated below) the reader can consult the monographs [Akh65, BCR98, FF90, ST43] and the excellent survey [F83]. The old article of Marcel Riesz [MR23] remains unsurpassed for the classical aspects of the one variable theory.

Given a multi-sequence of real numbers $(a_\alpha)_{\alpha \in \mathbb{N}^g}$ a linear functional representing the potential integral of polynomials can be defined as:

$$L : \mathbb{R}[x] \longrightarrow \mathbb{R}, \quad L(x^\alpha) = a_\alpha, \quad \alpha \in \mathbb{N}^g,$$

and vice-versa. When necessary we will complexify L to a complex linear functional on $\mathbb{C}[x]$.

If $(a_\alpha)_{\alpha \in \mathbb{N}^g}$ are the moments of a positive measure, then for a polynomial $p \in \mathbb{R}[x]$ we have

$$L(p^2) = \int_{\mathbb{R}^g} p^2 d\mu \geq 0.$$

Moreover, in the above positivity there is more structure: we can define on $\mathbb{C}[x]$ a pre-Hilbert space bracket by:

$$\langle p, q \rangle = L(p\bar{q}), \quad p, q \in \mathbb{C}[x].$$

The inner product is positive semi-definite, hence the Cauchy-Schwarz inequality holds:

$$|\langle p, q \rangle|^2 \leq \|p\|^2 \|q\|^2.$$

Thus, the set of null-vectors $N = \{p \in \mathbb{C}[x]; \|p\| = 0\}$ is a linear subspace, invariant under the multiplication by any polynomial. Let H be the Hilbert space completion of $\mathbb{C}[x]/N$ with respect to the induced Hermitian form. Let $\mathcal{D} = \mathbb{C}[x]/N$ be the image of the polynomial algebra in H . It is a dense linear subspace, carrying the multiplication operators:

$$M_{x_i} : \mathcal{D} \longrightarrow \mathcal{D}, \quad M_{x_i} p = x_i p.$$

Note that these are well defined, symmetric linear operators:

$$\langle M_{x_i} p, q \rangle = L(x_i p \bar{q}) = \langle p, M_{x_i} q \rangle, \quad p, q \in \mathcal{D},$$

and they commute

$$M_{x_i} M_{x_j} = M_{x_j} M_{x_i}.$$

Finally the (constant function) vector $\xi = 1$ is cyclic, in the sense that \mathcal{D} is the linear span of repeated actions of M_{x_1}, \dots, M_{x_g} on ξ :

$$\mathcal{D} = \bigvee_{\alpha \in \mathbb{N}^g} M_{x_1}^{\alpha_1} \dots M_{x_g}^{\alpha_g} \xi.$$

We collect these observations into a single statement.

Proposition 3.1. *There is a bijective correspondence between all linear functionals*

$$L \in \mathbb{R}[x]', \quad L|_{\Sigma^2\mathbb{R}[x]} \geq 0,$$

and the pairs (M, ξ) of g -tuples $M = (M_1, \dots, M_g)$ of commuting, symmetric linear operators with a cyclic vector ξ (acting on a separable Hilbert space). The correspondence is given by the relation

$$L(p) = \langle p(M)\xi, \xi \rangle, \quad p \in \mathbb{R}[x].$$

Above the word commuting has to be taken with caution: implicitly it is understood that we define the span \mathcal{D} as before, and remark that every M_i leaves \mathcal{D} invariant. Then M_i commutes with M_j as endomorphisms of \mathcal{D} .

Having a positive measure μ represent the functional L adds in general new constraints in this dictionary.

Let $\mathcal{P}_+(K)$ be the set of all polynomials which are non-negative on the set $K \subset \mathbb{R}^g$ and note that this is a convex cone.

Proposition 3.2. *A linear functional $L \in \mathbb{R}[x]'$ is representable by a positive measure μ :*

$$L(p) = \int p d\mu, \quad p \in \mathbb{R}[x]$$

if and only if $L|_{\mathcal{P}_+(\mathbb{R}^g)} \geq 0$.

Although this observation (in several variables) is attributed to Haviland, see [Akh65], it is implicitly contained in Marcel Riesz article [MR23]. Again we see exactly *the gap*

$$\Sigma^2\mathbb{R}[x] \subset \mathcal{P}_+(\mathbb{R}^g),$$

which we must understand in order to characterize the moments of positive measures (as already outlined in Minkowski's and Hilbert's early works).

Proof. If the functional L is represented by a positive measure, then it is obviously non-negative on all non-negative polynomials.

To prove the converse, assume that $L|_{\mathcal{P}_+(\mathbb{R}^g)} \geq 0$. Let $C_{pBd}(\mathbb{R}^g)$ be the space of continuous functions f having a polynomial bound at infinity:

$$|f(x)| \leq C(1 + |x|)^N,$$

with the constants $C, N > 0$ depending on f . We will extend L , following M. Riesz [MR23], to a non-negative functional on $C_{pBd}(\mathbb{R}^g)$.

This extension process, parallel and arguably prior to the Hahn-Banach Theorem, works as follows. Assume that

$$\hat{L} : V \longrightarrow \mathbb{R}$$

is a positive extension of L to a vector subspace $V \subset C_{pBd}(\mathbb{R}^g)$. That is:

$$(h \in V, h \geq 0) \Rightarrow (\hat{L}(h) \geq 0).$$

Remark that L is defined on all polynomial functions. Assume V is not the whole space and choose a non-zero function $f \in C_{pBd}(\mathbb{R}^g) \setminus V$. Since f has polynomial growth, there are elements $h_1, h_2 \in V$ satisfying

$$h_1 \leq f \leq h_2.$$

By the positivity of \hat{L} , we see $\hat{L}h_1 \leq \hat{L}f \leq \hat{L}h_2$, that is

$$\sup_{h_1 \leq f} \hat{L}(h_1) \leq \inf_{f \leq h_2} \hat{L}(h_2).$$

Choose any real number c between these limits and define

$$L'(h + \lambda f) = \hat{L}(h) + \lambda c, \quad h \in V, \lambda \in \mathbb{R}.$$

This will be a positive extension of L to the larger space $V \oplus \mathbb{R}f$.

By a standard application of Zorn's Lemma, we find a positive extension of L to the whole space. Finally, F. Riesz Representation Theorem provides a positive measure μ on \mathbb{R}^g , such that $L(p) = \int p d\mu$, $p \in \mathbb{R}[x]$. ■

Next we focus on a few particular contexts (either low dimensions, or special supporting sets for the measure) where the structure of the positive functionals and tuples of operators appearing in our dictionary can be further understood.

3.1. The trigonometric moment problem. We specialize to dimension $n = 2$ and to measures supported on the unit circle (torus) $\mathbb{T} = \{z \in \mathbb{C}; |z| = 1\}$. The group structure of \mathbb{T} identifies our moment problem to the Fourier transform. It is convenient in this case to work with complex coordinates $z = x + iy \in \mathbb{C} = \mathbb{R}^2$, and complex valued polynomials. In general, we denote by $\Sigma_h^2 \mathbb{C}[x]$ the sums of moduli squares (i.e. $|q|^2$) of complex coefficient polynomials.

The ring of regular functions on the torus is

$$A = \mathbb{C}[z, \bar{z}]/(1 - z\bar{z}) = \mathbb{C}[z] \oplus \bar{z}\mathbb{C}[\bar{z}],$$

where $(1 - z\bar{z})$ denotes the ideal generated by $1 - z\bar{z}$. A non-negative linear functional L on $\Sigma_h^2 A$ necessarily satisfies

$$L(\bar{f}) = \overline{L(f)}, \quad f \in A.$$

Hence L is determined by the complex moments $L(z^n)$, $n \geq 0$. The following result gives a satisfactory solution to the trigonometric moment problem on the one dimensional torus.

Theorem 3.3. *Let $(c_n)_{n=-\infty}^{\infty}$ be a sequence of complex numbers subject to the conditions $c_0 \geq 0$, $c_{-n} = \overline{c_n}$, $n \geq 0$. The following assertions are equivalent:*

a). *There exists a unique positive measure μ on \mathbb{T} , such that:*

$$c_n = \int_{\mathbb{T}} z^n d\mu(z), \quad n \geq 0;$$

b). *The Toeplitz matrix $(c_{n-m})_{n,m=0}^{\infty}$ is positive semi-definite;*

c). *There exists an analytic function $F : \mathbb{D} \rightarrow \mathbb{C}$, $\Re F \geq 0$, such that*

$$F(z) = c_0 + 2 \sum_{k=1}^{\infty} c_{-k} z^k, \quad |z| < 1;$$

d). *There exists a unitary operator $U \in L(H)$ and a vector $\xi \in H$ cyclic for the pair (U, U^*) , such that*

$$\langle U^n \xi, \xi \rangle = c_n, \quad n \geq 0.$$

Proof. Let $L : \mathbb{C}[z, \bar{z}]/(1 - z\bar{z}) \rightarrow \mathbb{C}$ be the linear functional defined by

$$L(z^n) = c_n, \quad n \geq 0.$$

Condition b) is equivalent to

$$L(|p|^2) \geq 0, \quad p \in \mathbb{C}[z, \bar{z}]/(1 - z\bar{z}).$$

Indeed, assume that $p(z) = \sum_{j=0}^g \alpha_j z^j$. Then, since $\bar{z}z = 1$,

$$|p(z)|^2 = \sum_{j,k=0}^g \alpha_j \bar{\alpha}_k z^{j-k},$$

whence

$$L(|p|^2) = \sum_{j,k=0}^g \alpha_j \bar{\alpha}_k c_{j-k}.$$

Thus a) \Rightarrow b) trivially. In view of the Riesz-Fejér Lemma, the functional L is non-negative on all non-negative polynomial functions on the torus. Hence, in view of Proposition 3.2 it is represented by a positive measure. The uniqueness is assured by the compactness of \mathbb{T} and Stone-Weierstrass Theorem (trigonometric polynomials are uniformly dense in the space of continuous functions on \mathbb{T}). The rest follows from Theorem 2.5. ■

Notable in the above Theorem is the fact that the main objects are in bijective, and constructive, correspondence established essentially by Riesz-Herglotz formula. Fine properties of the measure μ can be transferred in this way into restrictions imposed on the generating function F or the unitary operator U .

For applications and variations of the above result (for instance a matrix valued analog of it) the reader can consult [AM02, Akh65, FF90, RR97].

3.2. Hamburger's moment problem. The passage from the torus to the real line reveals some unexpected turns, due to the non-compactness of the line. One may argue that the correct analog on the line would be the continuous Fourier transform. Indeed, we only recall that Bochner's Theorem provides an elegant characterization of the Fourier transforms of positive measures.

Instead, we remain consistent and study polynomial functions and positive measures acting on them. Specifically, consider an \mathbb{R} -linear functional

$$L : \mathbb{R}[x] \longrightarrow \mathbb{R}, \quad L|_{\Sigma^2\mathbb{R}[x]} \geq 0.$$

By denoting

$$c_k = L(x^k), \quad k \geq 0,$$

the condition $L|_{\Sigma^2\mathbb{R}[x]}$ is equivalent to the positive semi-definiteness of the Hankel matrix

$$(c_{k+l})_{k,l=0}^{\infty} \geq 0,$$

since

$$0 \leq \sum_{k,l} f_k c_{k+l} f_l = \sum_{k,l} L(f_k x^k x^l f_l) = L\left(\sum_k f_k x^k \sum_l x^l f_l\right) = L(f(x)^2).$$

Next use that every non-negative polynomial on the line is a sum of squares of polynomials, to invoke Proposition 3.2 for the proof of the following classical fact.

Theorem 3.4 (Hamburger). *Let $(c_k)_{k=0}^{\infty}$ be a sequence of real numbers. There exists a rapidly decaying, positive measure μ on the real line, such that*

$$c_k = \int_{-\infty}^{\infty} x^k d\mu(x), \quad k \geq 0,$$

if and only if the matrix $(c_{k+l})_{k,l=0}^{\infty}$ is positive semi-definite.

Now we sketch a second proof of Hamburger Theorem, based on the Hilbert space construction we have outlined in the previous section. Namely, start with the positive semi-definite matrix $(c_{k+l})_{k,l=0}^{\infty}$ and construct a Hilbert space (Hausdorff) completion H of $\mathbb{C}[x]$, satisfying

$$\langle x^k, x^l \rangle = c_{k+l}, \quad k, l \geq 0.$$

Let \mathcal{D} denote as before the image of the algebra of polynomials in H ; the image is dense. The (single) multiplication operator

$$(Mp)(x) = xp(x), \quad p \in \mathcal{D},$$

is symmetric and maps \mathcal{D} into itself. Moreover, M commutes with the complex conjugation symmetry of H :

$$\overline{Mp} = M\bar{p}.$$

By a classical result of von-Neumann [vN1] there exists a self-adjoint (possibly unbounded) operator A which extends M to a larger domain. Since A possesses a spectral measure E_A (exactly as in the bounded case), we obtain:

$$\begin{aligned} c_k &= \langle x^k, 1 \rangle = \langle M^k 1, 1 \rangle = \\ &= \langle A^k 1, 1 \rangle = \int_{-\infty}^{\infty} x^k \langle E_A(dx) 1, 1 \rangle. \end{aligned}$$

The measure $\langle E_A(dx) 1, 1 \rangle$ is positive and has prescribed moments (c_k) . ■

This second proof offers more insight into the uniqueness part of Hamburger's problem. Every self-adjoint extension A of the symmetric operator M produces a solution $\mu(dx) = \langle E_A(dx) 1, 1 \rangle$. The set K of all positive measures with prescribed moments (c_k) is convex and compact in the weak-* topology. The subset of Nevanlinna extremal elements of K are identified with the measures $\langle E_A(dx) 1, 1 \rangle$ associated to the self-adjoint extensions A of M . In particular one proves in this way the following useful uniqueness criterion.

Proposition 3.5. *Let (c_k) be the moment sequence of a positive measure μ on the line. Then a positive measure with the same moments coincides with μ if and only if the subspace*

$$(iI + M)\mathcal{D} \text{ is dense in } H,$$

or equivalently, there exists a sequence of polynomials $p_n \in \mathbb{C}[x]$ satisfying

$$\lim_{n \rightarrow \infty} \int_{-\infty}^{\infty} |(i+x)p_n(x) - 1|^2 d\mu(x) = 0.$$

Note that both conditions are intrinsic in terms of the initial data (c_k) . For the original function theoretic proof see [MR23]. For the operator theoretic proof see for instance [Akh65].

There exists a classical analytic function counterpart of the above objects, exactly as in the previous case (see §2.4, §2.5) of the unit circle. Namely, assuming that

$$c_k = \langle A^k 1, 1 \rangle = \int_{-\infty}^{\infty} x^k d\mu(x), \quad k \geq 0,$$

as before, the analytic function

$$F(z) = \int_{-\infty}^{\infty} \frac{d\mu(x)}{x-z} = \langle (A-z)^{-1} 1, 1 \rangle$$

is well defined in the upper half-plane $\Im z > 0$ and has the asymptotic expansion at infinity (in the sense of Poincaré, uniformly convergent in wedges $0 < \delta < \arg z < \pi - \delta$):

$$F(z) \approx -\frac{c_0}{z} - \frac{c_1}{z^2} - \dots, \quad \Im(z) > 0.$$

One step further, we have a purely algebraic recursion which determines the continued fraction development

$$-\frac{c_0}{z} - \frac{c_1}{z^2} - \dots = -\frac{c_0}{z - \alpha_0 - \frac{\beta_0}{z - \alpha_1 - \frac{\beta_1}{z - \alpha_2 - \frac{\beta_2}{\ddots}}}}, \quad \alpha_k \in \mathbb{R}, \beta_k \geq 0.$$

It was Stieltjes, and then Hamburger, who originally remarked that (c_k) is the moment sequence of a positive measure if and only if the elements β_k in the continued fraction development of the generating (formal) series are non-negative. Moreover, in this case they proved that there exists a unique representing measure if and only if the continued fraction converges in the upper half-plane. For details and a great collection of classical examples see Perron's monograph [Per50]. A well known uniqueness criterion was obtained via this formalism by Carleman [C26]. It states that uniqueness holds if

$$\sum_1^{\infty} \frac{1}{c_{2k}^{1/(2k)}} = \infty.$$

The condition is however not necessary for uniqueness.

The alert reader has seen the great kinship between the continued fraction recursion just elucidated and the recursion called the Schur Algorithm in §2.5. These are essentially the same thing, but one is in the disk setting while the other is in the half plane.

3.2.1. *Moments on the semiaxis* $[0, \infty]$. The above picture applies with minor modifications to Stieltjes problem, that is the power moment problem on the semi-axis $[0, \infty)$.

Example 3.6. We reproduce below an example found by Stieltjes, and refined by Hamburger. See for details [Per50]. Let ρ and δ be positive constants, and denote

$$\alpha = \frac{1}{2 + \delta}, \quad \gamma = \rho^{-\alpha}.$$

Then

$$a_n = (2 + \delta)\rho^{n+1}\Gamma[(2 + \delta)(n + 1)] = \int_0^{\infty} x^n e^{-\gamma x^\alpha} dx, \quad n \geq 0,$$

is a moment sequence on the positive semi-axis. A residue integral argument implies

$$\int_0^\infty x^n \sin(\gamma x^\alpha \tan(\pi\alpha)) e^{-\gamma x^\alpha} dx = 0, \quad n \geq 0.$$

Hence

$$a_n = \int_0^\infty x^n (1 + t \sin(\gamma x^\alpha \tan(\pi\alpha))) e^{-\gamma x^\alpha} dx,$$

for all $n \geq 0$ and $t \in (-1, 1)$. This shows that the moment sequence (a_n) does not uniquely determine μ even knowing its support is $[0, \infty)$. \square

Summing up the above ideas, we have bijective correspondences between the following sets (\mathbb{C}_+ stands for the open upper half plane):

- A). *Rapidly decaying positive measures μ on the real line;*
- B). *Analytic functions $F : \mathbb{C}_+ \rightarrow \overline{\mathbb{C}_+}$, satisfying $\sup_{t>1} |tF(it)| < \infty$;*
- C). *Self-adjoint operators A with a cyclic vector ξ .*

More precisely:

$$F(z) = \langle (A - z)^{-1} \xi, \xi \rangle = \int_{-\infty}^\infty \frac{d\mu(x)}{x - z}, \quad z \in \mathbb{C}_+.$$

The moment sequence $c_k = \int_{-\infty}^\infty x^k d\mu(x)$, $k \geq 0$, appears in the asymptotic expansion of F , at infinity, but it does not determine F , (A, ξ) or μ . For further details about Hamburger and Stieltjes moment problems see Akhiezer's monograph [Akh65].

3.3. Several variables. The moment problem on \mathbb{R}^g , $g > 1$, is considerably more difficult and less understood. Although we have the general correspondence remarked in Proposition 3.1, the gap between a commuting tuple of unbounded symmetric operators and a strongly commuting one (i.e. by definition one possessing a joint spectral measure) is quite wide. A variety of strong commutativity criteria came to rescue; a distinguished one, due to Nelson [N59], is worth mentioning in more detail.

Assume that $L : \mathbb{R}[x_1, \dots, x_g] \rightarrow \mathbb{R}$ is a functional satisfying (the non-negative Hankel form condition) $L|_{\Sigma^2 \mathbb{R}[x]} \geq 0$. We complexify L and associate, as usual by now, the Hilbert space H with inner product:

$$\langle p, q \rangle = L(p\bar{q}), \quad \mathbb{C}[x].$$

The symmetric multipliers M_{x_k} commute on the common dense domain $\mathcal{D} = \mathbb{C}[x] \subset H$. Exactly as in the one variable case, there exists a positive measure μ on \mathbb{R}^g representing L if and only if there are (possibly unbounded)

self-adjoint extensions $M_{x_k} \subset A_k$, $1 \leq k \leq n$, commuting at the level of their resolvents:

$$[(A_k - z)^{-1}, (A_j - z)^{-1}] := (A_k - z)^{-1}(A_j - z)^{-1} - (A_j - z)^{-1}(A_k - z)^{-1} = 0,$$

$$\text{for } \Im z > 0, 1 \leq j, k \leq n.$$

See for details [F83]. Although individually every M_{x_k} admits at least one self-adjoint extension, it is the joint strong commutativity (in the resolvent sense) of the extensions needed to solve the moment problem.

Nelson's theorem gives a sufficient condition in this sense: if $(1 + x_1^2 + \dots + x_g^2)\mathcal{D}$ is dense in H , then the tuple of multipliers $(M_{x_1}, \dots, M_{x_g})$ admits an extension to a strongly commuting tuple of self-adjoint operators. Moreover, this insures the uniqueness of the representing measure μ . For complete proofs and more details see [Berg87, F83].

A tantalizing open question in this area can be phrased as follows:

Open problem. *Let $(c_{\alpha+\beta})_{\alpha, \beta \in \mathbb{N}^g}$ be a positive semi-definite Hankel form. Find effective conditions insuring that (c_α) are the moments of a positive measure.*

Or equivalently, in predual form, find effective criteria (in terms of the coefficients) for a polynomial to be non-negative on \mathbb{R}^g .

We know from Tarski's principle that the positivity of a polynomial is decidable. The term "effective" above means to find exact rational expressions in the coefficients which guarantee the non-negativity of the polynomial.

We do not touch in this discussion a variety of other aspects of the multivariate moment problem such as uniqueness criteria, orthogonal polynomials, cubature formulas and the truncated problem. See for instance [Berg87, Berg91, CF05, GV61, KM70].

3.4. Positivstellensätze on compact, semi-algebraic sets. Now we look at a very popular classes of Positivstellensätze. The hypotheses are more restrictive (by requiring bounded sets) than the general one, but the conclusion gives a simpler certificate of positivity. The techniques of proof are those used in the multivariate moment problem but measures with compact semi-algebraic support allow much more detail.

To state the theorems in this section requires the notions of preorder, $PO(F)$ and of quadratic module which we now give, but the treatment of them in Section ?? on the general Positivstellensatz gives more properties and a different context than done here. Let $F = \{f_1, \dots, f_p\}$ denote a set of

real polynomials. The *preordering* generated by F is

$$PO(F) = \left\{ \sum_{\sigma \in \{0,1\}^r} s_\sigma f_1^{\sigma_1} \dots f_r^{\sigma_r}; s_\sigma \in \Sigma^2 R[x] \right\}.$$

The *quadratic module generated by F* is defined to be:

$$QM(F) = \sum_{f \in F \cup \{1\}} f \Sigma^2 \mathbb{R}[x].$$

We start with a fundamental result of Schmüdgen, proved in 1991 ([S91]), which makes use in an innovative way of Stengle's general Positivstellensatz.

Theorem 3.7 (Schmüdgen). *Let $F = \{f_1, \dots, f_p\}$ be a set of real polynomials in g variables, such that the non-negativity set \mathcal{D}_F is compact in \mathbb{R}^g . Then*

a). A functional $L \in \mathbb{R}[x]'$ is representable by a positive measure supported on K if and only if

$$L|_{PO(F)} \geq 0.$$

b). Every positive polynomial on \mathcal{D}_F belongs to the preorder $PO(F)$.

Due to the compactness of the support, and Stone-Weierstrass Theorem, the representing measure is unique. We will discuss later the proof of b) in a similar context.

We call the quadratic module $QM(F)$ *archimedean* if there exists $C > 0$ such that

$$C - x_1^2 - \dots - x_g^2 \in QM(F).$$

This implies in particular that the semi-algebraic set \mathcal{D}_F is contained in the ball centered at zero, of radius \sqrt{C} . Also, from the convexity theory point of view, this means that the convex cone $QM(F) \subset \mathbb{R}[x]$ contains the constant function 1 in its algebraic interior (see [K69] for the precise definition). If the set \mathcal{D}_F is compact, then one can make the associated quadratic module archimedean by adding to the defining set one more term, of the form $C - x_1^2 - \dots - x_g^2$.

The key to Schmüdgen's Theorem and to a few forthcoming results in this survey is the following specialization of Proposition 3.1.

Lemma 3.8. [P93] *Let F be a finite set of polynomials in $\mathbb{R}[x]$ with associated quadratic module $QM(F)$ having the archimedean property. There exists a bijective correspondence between:*

a). Commutative g -tuples A of bounded self-adjoint operators with cyclic vector ξ and joint spectrum contained in \mathcal{D}_F ;

b). Positive measures μ supported on \mathcal{D}_F ;

c). *Linear functionals* $L \in \mathbb{R}[x]'$ *satisfying* $L|_{QM(F)} \geq 0$.

The correspondence is constructive, given by the relations:

$$L(p) = \langle p(A)\xi, \xi \rangle = \int_{\mathcal{D}_F} pd\mu, \quad p \in \mathbb{R}[x].$$

Proof. Only the implication $c) \Rightarrow a)$ needs an argument. Assume $c)$ holds and construct the Hilbert space H associated to the functional L . Let $M = (M_{x_1}, \dots, M_{x_g})$ denote the tuple of multiplication operators acting on H . Due to the archimedean property,

$$\langle (C - x_1^2 - \dots - x_g^2)p, p \rangle \geq 0, \quad p \in \mathbb{C}[x],$$

whence every M_{x_k} is a bounded self-adjoint operator. Moreover, the condition

$$\langle f_j p, p \rangle \geq 0, \quad p \in \mathbb{C}[x],$$

assures that $f_j(M) \geq 0$, that is, by the spectral mapping theorem, the joint spectrum of M lies on \mathcal{D}_F . Let E_M be the joint spectral measure of M . Then

$$L(p) = \int_{\mathcal{D}_F} p(x) \langle E_M(dx)1, 1 \rangle,$$

and the proof is complete. ■

For terminology and general facts about spectral theory in a commutative Banach algebra see [D03].

With this dictionary between positive linear functionals and tuples of commuting operators with prescribed joint spectrum we can improve Schmüdgen's result.

Theorem 3.9 ([P93]). *Let* F *be a finite set of real polynomials in* g *variables, such that the associated quadratic module* $QM(F)$ *is archimedean.*

Then a polynomial strictly positive on \mathcal{D}_F *belongs to* $QM(F)$.

Proof. Assume by contradiction that p is a positive polynomial on \mathcal{D}_F which does not belong to $QM(F)$. By a refinement of Minkowski separation theorem due to Eidelheit and Kakutani (see [K69]), there exists a linear functional $L \in \mathbb{R}[x]'$ such that $L(1) > 0$ and:

$$L(p) \leq 0 \leq L(q), \quad q \in QM(F).$$

(Essential here is the fact that the constant function 1 is in the algebraic interior of the convex cone $QM(F)$). Then Lemma 3.8 provides a positive measure μ supported on \mathcal{D}_F , with the property:

$$L(p) = \int_{\mathcal{D}_F} pd\mu \leq 0.$$

The measure is non-trivial because

$$L(1) = \mu(\mathcal{D}_F) > 0,$$

and on the other hand $p > 0$ on \mathcal{D}_F , a contradiction. ■

An algebraic proof of the latter theorem is due to Jacobi and Prestel, see [PD01].

4. APPLICATIONS OF SEMI-ALGEBRAIC GEOMETRY

The prospect of applying semi-algebraic geometry to a variety of areas is the cause of excitement in many communities; and we list a few of them here.

4.1. Global optimization of polynomials. An exciting turn in the unfolding of real algebraic geometry are applications to optimization. To be consistent with the non-commutative setting of the subsequent sections we denote below by $x \in \mathbb{R}^g$ a generic point in Euclidean space, and in the same time the g -tuple of indeterminates in the polynomial algebra.

4.1.1. Minimizing a Polynomial on \mathbb{R}^g . A classical question is: given a polynomial $q \in \mathbb{R}[x]$, find

$$\min_{x \in \mathbb{R}^g} q(x)$$

and the minimizer x^{opt} . The goal is to obtain a numerical solution to this problem and it is daunting even in a modest dimension such as $g = 15$. Finding a local optimum is numerically “easy” using the many available variations of gradient descent and Newton’s method. However, polynomials are notorious for having many many local minima.

A naive approach is to grid \mathbb{R}^g , lets say with 64 grid points per dimension (a fairly course grid), and compare values of q on this grid. This requires $64^{15} \sim 10^9 10^7$ function evaluations or something like 10,000 hours to compute. Such prohibitive requirements occur in many high dimensional spaces and go under the heading of the “curse of dimensionality”.

The success of sums of squares and Positivstellensätze methods rides on the heels of semi-definite programming, a subject which effectively goes back a decade and a half ago, and which effectively allows numerical computation of a sum of squares decomposition of a given polynomial q . The cost of the computation is determined by the number of terms of the polynomial q and is less effected by the number g of variables and the degree of q . To be more specific, this approach to optimization consists of starting with a number q^{**} and numerically solve

$$q - q^{**} = s,$$

for $s \in \Sigma^2$. If this is possible, lower q^{**} according to some algorithm and try again. If not, raise q^{**} and try again. Hopefully, one obtains q^{*o} at the transition (between being possible to write $q - q^{**}$ as a sums of squares and not) and obtains

$$q - q^{*o} \in \Sigma^2$$

and conclude that this is an optimum. This method was proposed first by Shor [S87] and subsequently refined by Lasserre [L01] and by Parrilo [ParThesis].

Parrilo and Sturmfels [PS03] reported experiments with a special class of 10,000 polynomials for which the true global minimum could be computed explicitly. They found in all cases that q^{*o} determined by sums of squares optimization equals the true minimum.

Theoretical evidence supporting this direction is the following observation, see [BCR98] §9.

Theorem 4.1. *Given a polynomial $q \in \mathbb{R}[x]$, the following are equivalent:*

- (1) $q \geq 0$ on the cube $[-1, 1]^g$.
- (2) For all $\varepsilon > 0$, there is $s \in \Sigma^2$ such that

$$\|q - s\|_{L^1([-1, 1]^g)} < \varepsilon.$$

A refinement of this result was recently obtained by Lasserre and Netzer [LN06]. Namely, the two authors prove that an additive, small perturbations with a fixed polynomial, produces a sum of squares which is close to the original polynomial in the L^1 norm of the coefficients. We reproduce, without proofs, their main result.

Theorem 4.2. [LN06] *Let $p \in \mathbb{R}[x_1, \dots, x_g]$ be a polynomial of degree d , and let*

$$\Theta_r = 1 + x_1^{2r} + \dots + x_g^{2r},$$

where $r \geq d/2$ is fixed. Define

$$\epsilon_r^* = \min_L \{L(p); L \in \mathbb{R}_{2r}[x_1, \dots, x_g]', L(\Theta_r) \leq 1, L|_{\Sigma}^2 \geq 0\}.$$

Then $\epsilon_r^* \leq 0$ and the minimum is attained. The polynomial

$$p_{\epsilon, r} = p + \epsilon \Theta_r$$

is a sum of squares if and only if $\epsilon \geq -\epsilon_r^*$.

Moreover, if the polynomial p is non-negative on the unit cube $[-1, 1]^g$, then $\lim_{r \rightarrow \infty} \epsilon_r^* = 0$.

Variations of the above theorem, with supports on semi-algebraic sets, relevant examples and an analysis of the degree bounds are contained in the same article [LN06].

For quite a few years by now, Lasserre has emphasized the tantamount importance of such perturbation results for optimization using sums of squares (henceforth abbreviated *SOS*) methods, see [L01], in that it suggests that determining if a given p is nonnegative on a bounded region by computing a sums of squares has a good probability of being effective.

We shall not prove the stated perturbation results, but remark that a free algebra version of them holds, [KS05].

In the opposite pessimistic direction there are the precise computations of Choi-Lam-Reznick (see [R92]) and a recent result due to Bleckermann [Blec04].

As a backup to the above optimization scheme, if a $q - q^{*o} \in \Sigma^2$ fails to be a sum of squares, then one can pick a positive integer m and attempt to solve

$$(1 + |x|^2)^m (q - q^{*o}) \in \Sigma^2.$$

Reznick's Theorem [R95] tells us that for some m this solves the optimization problem exactly. Engineers call using the term with some non zero m "relaxing the problem", but these days they call most modifications of almost anything a "relaxation" .

4.1.2. *Constrained optimization.* Now we give Jean Lasserre's interpretation of Theorem 3.9. Let \mathcal{P} denote a collection of polynomials. The standard constrained optimization problem for polynomials is:

$$\text{minimize } q(x) \text{ subject to } x \in \mathcal{D}_{\mathcal{P}} := \{x \in \mathbb{R}^g; p(x) \geq 0, p \in \mathcal{P}\}.$$

Denote the minimum value of q by q^{opt} . We describe the idea when \mathcal{P} contains but one polynomial p . Assume $\nabla p(x)$ does not vanish for $x \in \partial \mathcal{D}_p$.

The standard first order necessary conditions for $x^{opt} \in \partial \mathcal{D}_{\mathcal{P}}$ to be a local solution to this problem is

$$\nabla q(x^{opt}) = \lambda \nabla p(x^{opt})$$

with $\lambda > 0$. We emphasize, this is a local condition and λ is called the Lagrange multiplier.

Now we turn to analyzing the global optimum. Suppose that q can be expressed in the form:

$$q - q^{**} = s_1 + s_2 p, \quad s_{1,2} \in \Sigma^2,$$

which implies $q(x) \geq q^{**}$ for all $x \in \mathcal{D}_p$. So q^{**} is a lower bound. This is a stronger form of the Positivstellensatz than is always true. Then this optimistic statement can be interpreted as a global optimality condition

when $q^{**} = q^{opt}$. Also it implies the classical Lagrange multiplier linearized condition, as we now see. At the *global* minimum x^{opt} we have

$$0 = q(x^{opt}) - q^{opt} = s_1(x^{opt}) + s_2(x^{opt})p(x^{opt})$$

which implies $0 = s_1(x^{opt})$ and, since s_1 is a sum of squares, we get $\nabla s_1(x^{opt}) = 0$. Also $s_2(x^{opt}) = 0$, $\nabla s_2(x^{opt}) = 0$ whenever $p(x^{opt}) \neq 0$. Calculate

$$\nabla q = \nabla s_1 + p\nabla s_2 + s_2\nabla p.$$

If $p(x^{opt}) = 0$, we get

$$\nabla q(x^{opt}) = s_2(x^{opt})\nabla p(x^{opt})$$

and if $p(x^{opt}) \neq 0$ we get $\nabla q(x^{opt}) = 0$, the classic condition for an optimum in the interior. Set $\lambda = s_2(x^{opt})$ to get $\lambda\nabla p(x^{opt}) = \nabla q(x^{opt})$ the classic Lagrange multiplier condition as a (weak) consequence of the Positivstellensatz.

The reference for this and more general (finitely many p_j in terms of the classical Kuhn-Tucker optimality conditions) is [L01] Proposition 5.1.

Also regarding constrained optimization we mention that, at the technical level, the method of moments has re-entered into polynomial optimization. Quite specifically, Lasserre and followers are relaxing the original problem

$$\min_{x \in \mathcal{D}} q(x)$$

as

$$\min_{\mu} \int_{\mathcal{D}} q d\mu,$$

where the minimum is taken over all probability measures supported on \mathcal{D} . They prove that it is a great advantage to work in the space of moments (as free coordinates), see [HL05, L01, L04].

5. LINEAR MATRIX INEQUALITIES AND COMPUTATION OF SUMS OF SQUARES

Numerical computation of a sum of squares and a Positivstellensatz is based on a revolution which started about 20 years ago in optimization; the rise of interior point methods. We avoid delving into yet another topic but mention the special aspects concerning us. Thanks to the work of Nesterov and Nemirovskii in the early 1990s one can solve Linear Matrix Inequalities (LMIs in short) numerically using interior point optimization methods, called *semi-definite programming*. An LMI is an inequality of the form

$$(5.1) \quad A_0 + A_1x_1 + \cdots + A_gx_g \geq 0$$

where the A_j are symmetric matrices and the numerical goal is to compute $x \in \mathbb{R}^g$ satisfying this. The sizes of matrix unknowns treatable by year

2006 solvers exceed 100×100 ; with special structure dimensions can go much higher. This is remarkable because our LMI above has about $5000g$ unknowns.

5.1. SOS and LMIs. Sum of squares and Positivstellensätze problems convert readily to LMIs and these provide an effective solution for polynomials having modest number of terms. These applications make efficiencies in numerics a high priority. This involves shrewd use of semi-algebraic theory and computational ideas to produce a semi-definite programming package, for a recent paper see [1]; also there is recent work of L. Vandenberghe. Semi-algebraic geometry packages are: SOS tools [PPSP04] and GloptiPoly [HL03].

A lament is that all current computational semi-algebraic geometry projects use a packaged semi-definite solver, none write their own. This limits efficiencies for sum of squares computation.

Special structure leads to great computational improvement as well as elegant mathematics. For example, polynomials which are invariant under a group action, the delight of classical invariant theory, succumb to rapid computation, see [GP04] [CKSprept].

5.2. LMIs and the world. LMIs have a life extending far beyond computational sum of squares and are being found in many areas of science. Later in this paper §?? we shall glimpse at their use in systems engineering, a use preceding sum of squares applications by 10 years. The list of other areas includes statistics, chemistry, quantum computation together with more; all too vast for us to attempt description.

A paradigm mathematical question here is:

Which convex sets \mathcal{C} in \mathbb{R}^g with algebraic boundary can be represented with some monic LMI?

That is,

$$\mathcal{C} = \{x \in \mathbb{R}^g : I + A_1x_1 + \cdots + A_gx_g \geq 0\},$$

where A_j are symmetric matrices. Here we have assumed the normalization $0 \in \mathcal{C}$. This question was raised by Parrilo and Sturmfels [PS03]. The paper [HVprept] gives an obvious necessary condition ¹ on \mathcal{C} for an LMI representation to exist and proves sufficiency when $g = 2$.

¹This is in contrast to the free algebra case where all evidence (like that in this paper) indicates that convexity is the only condition required.

The main issue is that of determinantal representations of a polynomial $p(x)$ on \mathbb{R}^g , namely, given p express it in the form

$$(5.2) \quad p(x) = \det(A_0 + A_1x_1 + \cdots + A_gx_g).$$

That this is possible for some matrices is due to the computer scientist Leslie Valiant [Val79]. That the matrices can be taken real and symmetric is in [HMPrept] as is the fact that a representation of $\det p(X)$ always holds for polynomials in non-commuting (free) variables, as later appear in §6. A symbolic computer algorithm due to N. Slinglend and implemented by J. Shopples runs under the Mathematica package NCAAlgebra.

The open question is which polynomials can we represent monically; that is with $A_0 = I$. Obviously, necessary is the *real zero condition*, namely,

*the polynomial $f(t) := p(tx)$ in one complex variable t
has only real zeroes,*

but what about the converse? When $g = 2$ the real zero condition on p insures that it has a monic representation; this is the core of [HVprept].

What about higher dimensions? Lewis, Parrilo and Ramana [LPR05] showed that this $g = 2$ result (together with a counterexample they concocted) settles a 1958 conjecture of Peter Lax, which leads to the surmise that sorting out the $g > 2$ situation may not happen soon. Leonid Gurvitz pointed out the Valiant connection to functional analysts and evangelizes that monic representations have strong implications for lowering the complexity of certain polynomial computations.

6. NON-COMMUTATIVE ALGEBRAS

A direction in semi-algebraic geometry, recently blossoming still with many avenues to explore, concerns variables which do not commute. As of today versions of the strict Positivstellensätze we saw in §?? are proved for a free $*$ -algebra and for the enveloping algebra of a Lie algebra; here the structure is cleaner or the same as in the classical commutative theory. The verdict so far on noncommutative Nullstellensätze is mixed. In a free algebra it goes through so smoothly that no radical ideal is required. This leaves us short of the remarkable perfection we see in the Stengle -Tarski - Seidenberg commutative landscape. Readers will be overjoyed to hear that the proofs needed above are mostly known to them already: just as in earlier sections, non-negative functionals on the sums of squares cone in a $*$ -algebra can be put in correspondence with tuples of non-commuting operators, and this carries most of the day.

This noncommutative semi-algebraic foundation underlies a rigid structure (at least) for free $*$ -algebras which has recently become visible. A noncommutative polynomial p has second derivative p'' which is again a

polynomial and if p'' is positive, then our forthcoming free $*$ -algebra Positivstellensatz tells us that p'' is a sum of squares. It is a bizarre twist that this and the derivative structure are incompatible, so together imply that a “convex polynomial” in a free $*$ - algebra has degree 2 or less; see §7. The authors suspect that this is a harbinger of a very rigid structure in a free $*$ -algebra for “irreducible varieties” whose curvature is either nearly positive or nearly negative; but this is a tale for another (likely distant) day. Some of the material in this section on higher derivatives and the next is new.

A final topic on semi-algebraic geometry in a free $*$ - algebra is applications to engineering, §???. Arguably the main practical development in systems and control through the 1990’s was the reduction of linear systems problems to Linear Matrix Inequalities, LMIs. For theory and numerics to be highly successful something called “Convex Matrix Inequalities”, henceforth denoted in short CMIs, will do nicely. Most experts would guess that the class of problems treatable with CMIs is much broader than with LMIs. But no, as we soon see, our draconian free $*$ convexity theorems suggest that for systems problems fully characterized by performance criteria based on L^2 and signal flow diagrams (as are most textbook classics), convex matrix inequalities give no greater generality than LMIs.

These systems problems have the key feature that their statement does not depend on the dimension of the systems involved. Thus we summarize our main engineering contention:

Dimension free convex problems are equivalent to an LMI

This and the next sections tells the story we just described but there is a lot it does not do. Our focus in this paper has been on inequalities, where various noncommutative equalities are of course a special and often well developed case. For example, algebraic geometry based on the Weyl algebra and corresponding computer algebra implementations, for example, Gröbner basis generators for the Weyl algebra are in the standard computer algebra packages such as Plural/Singular.

A very different and elegant area is that of rings with a polynomial identity, in short PI rings, e.g. $N \times N$ matrices for fixed N . While most PI research concerns identities, there is one line of work on polynomial inequalities, indeed sums of squares, by Procesi-Schacher [PS76]. A Nullstellensatz for PI rings is discussed in [Amit57].

6.1. Sums of squares in a free $*$ -algebra. Let $\mathbb{R}\langle x, x^* \rangle$ denote the polynomials with real numbers as coefficients in variables $x_1, \dots, x_g, x_1^*, \dots, x_g^*$. These variables do not commute, indeed they are free of constraints other

than $*$ being an anti-linear involution:

$$(fq)^* = q^* f^*, \quad (x_j)^* = x_j^*.$$

Thus $\mathbb{R}\langle x, x^* \rangle$ is called the *real free $*$ -algebra* on generators x, x^* .

Folklore has it that analysis in a free $*$ -algebra gives results like ordinary commutative analysis in one variable. The SoS phenomenon we describe in this section is consistent with this picture, but convexity properties in the next section do not. Convexity in a free algebra is much more rigid.

We invite those who work in a free algebra (or their students) to try NCAAlgebra, the free free- $*$ algebra computer package [HSM05]. Calculations with it had a profound impact on the results in §6 and 7; it is a very powerful tool.

The cone of sums of squares is the convex hull:

$$\Sigma^2 = \text{co}\{f^* f; f \in \mathbb{R}\langle x, x^* \rangle\}.$$

A linear functional $L \in \mathbb{R}\langle x, x^* \rangle'$ satisfying $L|_{\Sigma^2} \geq 0$ produces a positive semidefinite bilinear form

$$\langle f, q \rangle = L(q^* f)$$

on $\mathbb{R}\langle x, x^* \rangle$. We use the same construction introduced in section 3, namely, mod out the null space of $\langle f, f \rangle$ and denote the Hilbert space completion by H , with \mathcal{D} the dense subspace of H generated by $\mathbb{R}\langle x, x^* \rangle$. The separable Hilbert space H carries the multiplication operators $M_j : \mathcal{D} \rightarrow \mathcal{D}$:

$$M_j f = x_j f, \quad f \in \mathcal{D}, \quad 1 \leq j \leq n.$$

One verifies from the definition that each M_j is well defined and

$$\langle M_j f, q \rangle = \langle x_j f, q \rangle = \langle f, x_j^* q \rangle, \quad f, q \in \mathcal{D}.$$

Thus $M_j^* = M_{x_j^*}$. The vector 1 is still $*$ -cyclic, in the sense that the linear span $\bigvee_{p \in \mathbb{R}\langle x, x^* \rangle} p(M, M^*)1$ is dense in H . Thus, *mutatis mutandis*, we have obtained the following result.

Lemma 6.1. *There exists a bijective correspondence between positive linear functionals, namely*

$$L \in \mathbb{R}\langle x, x^* \rangle' \quad \text{and} \quad L|_{\Sigma^2} \geq 0,$$

and g -tuples of unbounded linear operators T with a star cyclic vector ξ , established by the formula

$$L(f) = \langle f(T, T^*)\xi, \xi \rangle, \quad f \in \mathbb{R}\langle x, x^* \rangle.$$

We stress that the above operators do not commute, and might be unbounded. The calculus $f(T, T^*)$ is the non-commutative functional calculus: $x_j(T) = T_j$, $x_j^*(T) = T_j^*$.

An important feature of the above correspondence is that it can be restricted by the degree filtration. Specifically, let $\mathbb{R}\langle x, x^* \rangle_k = \{f; \deg f \leq k\}$, and similarly, for a quadratic form L as in the lemma, let \mathcal{D}_k denote the finite dimensional subspace of H generated by the elements of $\mathbb{R}\langle x, x^* \rangle_k$. Define also

$$\Sigma_k^2 = \Sigma^2 \cap \mathbb{R}\langle x, x^* \rangle_k.$$

Start with a functional $L \in \mathbb{R}\langle x, x^* \rangle'_{2k}$ satisfying $L|_{\Sigma_{2k}^2} \geq 0$. One can still construct a finite dimensional Hilbert space H , as the completion of $\mathbb{R}\langle x, x^* \rangle_k$ with respect to the inner product $\langle f, q \rangle = L(q^*f)$, $f, q \in \mathbb{R}\langle x, x^* \rangle_k$. The multipliers

$$M_j : \mathcal{D}_{k-1} \longrightarrow H, \quad M_j f = x_j f,$$

are well defined and can be extended by zero to the whole H . Let

$$N(k) = \dim \mathbb{R}\langle x, x^* \rangle_k = 1 + (2g) + (2g)^2 + \dots + (2g)^k = \frac{(2g)^{k+1} - 1}{2g - 1}.$$

In short, we have proved the following specialization of the main Lemma.

Lemma 6.2. *Let $L \in \mathbb{R}\langle x, x^* \rangle'_{2k}$ satisfy $L|_{\Sigma_{2k}^2} \geq 0$. There exists a Hilbert space of dimension $N(k)$ and an g -tuple of linear operators M on H , with a distinguished vector $\xi \in H$, such that*

$$(6.1) \quad L(p) = \langle p(M, M^*)\xi, \xi \rangle, \quad p \in \mathbb{R}\langle x, x^* \rangle_{2k-2}.$$

Following the pattern of the preceding section, we will derive now a Nicht-negativstellensatz.

Theorem 6.3 ([H02]). *Let $p \in \mathbb{R}\langle x, x^* \rangle_d$ be a non-commutative polynomial satisfying $p(M, M^*) \geq 0$ for all g -tuples of linear operators M acting on a Hilbert space of dimension at most $N(k)$, $2k \geq d + 2$. Then $p \in \Sigma^2$.*

Proof. The only necessary technical result we need is the closedness of the cone Σ_k^2 in the Euclidean topology of the finite dimensional space $\mathbb{R}\langle x, x^* \rangle_k$. This is done as in the commutative case, using Carathéodory's convex hull theorem. More exactly, every element of Σ_k^2 is a convex combination of at most $\dim \mathbb{R}\langle x, x^* \rangle_k + 1$ elements, and on the other hand there are finitely many positive functionals on Σ_k^2 which separate the points of $\mathbb{R}\langle x, x^* \rangle_k$. See for details [HMP04a].

Assume that $p \notin \Sigma^2$ and let $k \geq (d+2)/2$, so that $p \in \mathbb{R}\langle x, x^* \rangle_{2k-2}$. Once we know that Σ_{2k}^2 is a closed cone, we can invoke Minkowski separation theorem and find a functional $L \in \mathbb{R}\langle x, x^* \rangle'_{2k}$ providing the strict separation:

$$L(p) < 0 \leq L(f), \quad f \in \Sigma_{2k}^2.$$

According to Lemma 6.2 there exists a tuple M of operators acting on a Hilbert space H of dimension $N(k)$ and a vector $\xi \in H$, such that

$$0 \leq \langle p(M, M^*)\xi, \xi \rangle = L(p) < 0,$$

a contradiction. ■

When compared to the commutative framework, this theorem is stronger in the sense that it does not assume a strict positivity of p on a well chosen "spectrum". Variants with supports (for instance for spherical tuples $M : M_1^*M_1 + \dots + M_g^*M_g \leq I$) of the above result are discussed in [HMP04a].

We state below an illustrative and generic result, from [HM04a], for sums of squares decompositions in a free $*$ -algebra.

Theorem 6.4. *Let $p \in \mathbb{R}\langle x, x^* \rangle$ and let $q = \{q_1, \dots, q_k\} \subset \mathbb{R}\langle x, x^* \rangle$ be a set of polynomials, so that the non-commutative quadratic module*

$$QM(q) = \text{co}\{f^*q_k f; f \in \mathbb{R}\langle x, x^* \rangle, 0 \leq i \leq k\}, \quad q_0 = 1,$$

*contains $1 - x_1^*x_1 - \dots - x_g^*x_g$. If for all tuples of linear bounded Hilbert space operators $X = (X_1, \dots, X_g)$ subject to the conditions*

$$q_i(X, X^*) \geq 0, \quad 1 \leq i \leq k,$$

we have

$$p(X, X^*) > 0,$$

then $p \in QM(q)$.

Notice that the above theorem covers relations of the form $r(X, X^*) = 0$, the latter being assured by $\pm r \in QM(q)$. For instance we can assume that we evaluate only on commuting tuples of operators, in which situation all commutators $[x_i, x_j]$ are included among the (possibly other) generators of $QM(q)$.

Some interpretation is needed in degenerate cases, such as those where no bounded operators satisfy the relations $q_i(X, X^*) \geq 0$, for example, if some of q_i are the defining relations for the Weyl algebra; in this case, we would say $p(X, X^*) > 0$, since there are no X . Indeed $p \in QM(q)$ as the theorem says.

Proof Assume that p does not belong to the convex cone $QM(q)$. Since the latter is archimedean, by the same Minkovski principle there exists a linear functional $L \in \mathbb{R}\langle x, x^* \rangle'$, such that

$$L(p) \leq 0 \leq L(f), \quad f \in QM(q).$$

Define the Hilbert space H associated to L , and remark that the left multipliers M_{x_i} on $\mathbb{R}\langle x, x^* \rangle$ give rise to linear bounded operators (denoted by

the same symbols) on H . Then

$$q_i(M, M^*) \geq 0, \quad 1 \leq i \leq k,$$

by construction, and

$$\langle p(M, M^*)1, 1 \rangle = L(p) \leq 0,$$

a contradiction.

The above statement allows a variety of specialization to quotient algebras. Specifically, if I denotes a bilateral ideal of $\mathbb{R}\langle x, x^* \rangle$, then one can replace the quadratic module in the statement with $QM(q) + I$, and separate the latter convex cone from the potential positive element on the set of tuples of matrices X satisfying simultaneously

$$q_i(X, X^*) \geq 0, \quad 0 \leq i \leq k, \quad f(X) = 0, \quad f \in I.$$

For instance, the next simple observation can also be deduced from the preceding theorem.

Corollary 6.5. *Let J be the bilateral ideal of $\mathbb{R}\langle x, x^* \rangle$ generated by the commutator polynomial $[x_1 + x_1^*, x_2 + x_2^*] - 1$. Then $J + QM(1 - x_1^*x_1 - \dots - x_g^*x_g) = \mathbb{R}\langle x, x^* \rangle$.*

Proof Assume by contradiction that $J + QM(1 - x_1^*x_1 - \dots - x_g^*x_g) \neq \mathbb{R}\langle x, x^* \rangle$. By our basic separation lemma, there exists a linear functional $L \in \mathbb{R}\langle x, x^* \rangle'$ with the properties:

$$L_{J+QM(1-x_1^*x_1-\dots-x_g^*x_g)} \geq 0, \quad \text{and} \quad L(1) > 0.$$

Then the GNS construction will produce a tuple of linear bounded operators X , acting on the associated non-zero Hilbert space H , satisfying $X_1^*X_1 + \dots + X_g^*X_g \leq I$ and

$$[X_1^* + X_1, X_2^* + X_2] = I.$$

The latter equation is however impossible, because the left hand side is anti-symmetric while the right hand side is symmetric and non-zero.

■

Similarly, we can derive following the same scheme the next result.

Corollary 6.6. *Assume, in the condition of the above Theorem, that $p(X, X^*) > 0$ for all COMMUTING tuples X of matrices subject to the positivity constraints $q_i(X, X^*) \geq 0, 0 \leq i \leq k$. Then*

$$p \in QM(q) + I,$$

where I is the bilateral ideal generated by all commutators $[x_i, x_j], [x_i, x_j]^*$, $1 \leq i, j \leq g$.

With similar techniques (well chosen, separating, *-representations of the free algebra) one can prove a series of Nullstellensätze. We state for information one of them, see for an early version [HMP04b].

Theorem 6.7. *Let $p_1(x), \dots, p_m(x) \in \mathbb{R}\langle x \rangle$ be polynomials not depending on the x_j^* variables and let $q(x, x^*) \in \mathbb{R}\langle x, x^* \rangle$. Assume that for every g tuple X of linear operators acting on a finite dimensional Hilbert space H , and every vector $v \in H$, we have:*

$$(p_j(X)v = 0, 1 \leq j \leq m) \implies (q(X, X^*)v = 0).$$

Then q belongs to the left ideal $\mathbb{R}\langle x, x^ \rangle p_1 + \dots + \mathbb{R}\langle x, x^* \rangle p_m$.*

Again, this proposition is stronger than its commutative counterpart. For instance there is no need of taking higher powers of q , or of adding a sum of squares to q .

We refer the reader to [HMP06] for the proof of Proposition 6.7. However, we say a few words about the intuition behind it. We are assuming

$$p_j(X)v = 0, \forall j \implies q(X, X^*)v = 0.$$

On a very large vector space if X is determined on a small number of vectors, then X^* is not heavily constrained; it is almost like being able to take X^* to be a completely independent tuple Y . If it were independent, we would have

$$p_j(X)v = 0, \forall j \implies q(X, Y)v = 0.$$

Now, in the free algebra $\mathbb{R}\langle x, y \rangle$, it is much simpler to prove that this implies $q \in \sum_j^m \mathbb{R}\langle x, y \rangle p_j$, as required. We isolate this fact in a separate lemma.

Lemma 6.8. *Fix a finite collection p_1, \dots, p_m of polynomials in non-commuting variables $\{x_1, \dots, x_g\}$ and let q be a given polynomial in $\{x_1, \dots, x_g\}$. Let d denote the maximum of the $\deg(q)$ and $\{\deg(p_j) : 1 \leq j \leq m\}$.*

There exists a real Hilbert space \mathcal{H} of dimension $\sum_{j=0}^d g^j$, such that, if

$$q(X)v = 0$$

whenever $X = (X_1, \dots, X_g)$ is a tuple of operators on \mathcal{H} , $v \in \mathcal{H}$, and

$$p_j(X)v = 0 \text{ for all } j,$$

then q is in the left ideal generated by p_1, \dots, p_m .

Proof (of Lemma). We sketch a proof based on an idea of G. Bergman, see [HM04a].

Let \mathcal{I} be the left ideal generated by p_1, \dots, p_m in $F = \mathbb{R}\langle x_1, \dots, x_g \rangle$. Define \mathcal{V} to be the vector space F/\mathcal{I} and denote by $[f]$ the equivalence class of $f \in F$ in the quotient F/\mathcal{I} .

Define X_j on the vector space F/\mathcal{I} by $X_j[f] = [x_j f]$ for $f \in F$, so that $x_j \mapsto X_j$ implements a quotient of the left regular representation of the free algebra F .

If $\mathcal{V} := F/\mathcal{I}$ is finite dimensional, then the linear operators $X = (X_1, \dots, X_g)$ acting on it can be viewed as a tuple of matrices and we have, for $f \in F$,

$$f(X)[1] = [f].$$

In particular, $p_j(X)[1] = 0$ for all j . If we do not worry about the dimension counts, by assumption, $0 = q(X)[1]$, so $0 = [q]$ and therefore $q \in \mathcal{I}$. Minus the precise statement about the dimension of \mathcal{H} this establishes the result when F/\mathcal{I} is finite dimensional.

Now we treat the general case where we do not assume finite dimensionality of the quotient. Let \mathcal{V} and \mathcal{W} denote the vector spaces

$$\mathcal{V} := \{[f] : f \in F, \deg(f) \leq d\},$$

$$\mathcal{W} := \{[f] : f \in F, \deg(f) \leq d-1\}.$$

Note that the dimension of \mathcal{V} is at most $\sum_{j=0}^d g^j$. We define X_j on \mathcal{W} to be multiplication by x_j . It maps \mathcal{W} into \mathcal{V} . Any linear extension of X_j to the whole \mathcal{V} will satisfy: if f has degree at most d , then $f(X)[1] = [f]$. The proof now proceeds just as in the part 1 of the proof above. ■

With this observation we can return and finish the proof of Theorem 6.7. Since X^* is dependent on X , an operator extension with properties stated in the lemma below gives just enough structure to make the above free algebra Nullstellensatz apply; and we prevail.

Lemma 6.9. *Let $x = \{x_1, \dots, x_m\}$, $y = \{y_1, \dots, y_m\}$ be free, non-commuting variables. Let H be a finite dimensional Hilbert space, and let X, Y be two m -tuples of linear operators acting on H . Fix a degree $d \geq 1$.*

Then there exists a larger Hilbert space $K \supset H$, an m -tuple of linear transformations \tilde{X} acting on K , such that

$$\tilde{X}_j|_H = X_j, \quad 1 \leq j \leq g,$$

and for every polynomial $q \in \mathbb{R}\langle x, x^ \rangle$ of degree at most d and vector $v \in H$,*

$$q(\tilde{X}, \tilde{X}^*)v = 0 \Rightarrow q(X, Y)v = 0.$$

For the matrical construction in the proof see [HMP06].

We end this subsection with an example, see [HM04a].

Example 6.10. Let $p = (x^*x + xx^*)^2$ and $q = x + x^*$ where x is a single variable. Then, for every matrix X and vector v (belonging to the space

where X acts), $p(X)v = 0$ implies $q(X)v = 0$; however, there does not exist a positive integer m and $r, r_j \in \mathbb{R}\langle x, x^* \rangle$, so that

$$(6.2) \quad q^{2m} + \sum r_j^* r_j = pr + r^* p.$$

Moreover, we can modify the example to add the condition $p(X)$ is positive semi-definite implies $q(X)$ is positive semi-definite and still not obtain this representation. \square

Proof Since $A := XX^* + X^*X$ is self-adjoint, $A^2v = 0$ if and only if $Av = 0$. It now follows that if $p(X)v = 0$, then $Xv = 0 = X^*v$ and therefore $q(X)v = 0$.

For $\lambda \in \mathbb{R}$, let

$$X = X(\lambda) = \begin{pmatrix} 0 & \lambda & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

viewed as an operator on \mathbb{R}^3 and let $v = e_1$, where $\{e_1, e_2, e_3\}$ is the standard basis for \mathbb{R}^3 .

We begin by calculating the first component of even powers of the matrix $q(X)$. Let $Q = q(X)^2$ and verify,

$$(6.3) \quad Q = \begin{pmatrix} \lambda^2 & 0 & \lambda \\ 0 & 1 + \lambda^2 & 0 \\ \lambda & 0 & 1 \end{pmatrix}.$$

For each positive integer m there exist a polynomial q_m so that

$$(6.4) \quad Q^m e_1 = \begin{pmatrix} \lambda^2(1 + \lambda q_m(\lambda)) \\ 0 \\ \lambda(1 + \lambda q_m(\lambda)) \end{pmatrix}$$

which we now establish by an induction argument. In the case $m = 1$, from equation (6.3), it is evident that $q_1 = 0$. Now suppose equation (6.4) holds for m . Then, a computation of $QQ^m e_1$ shows that equation (6.4) holds for $m + 1$ with $q_{m+1} = \lambda(q_m + \lambda + \lambda q_m)$. Thus, for any m ,

$$(6.5) \quad \lim_{\lambda \rightarrow 0} \frac{1}{\lambda^2} \langle Q^m e_1, e_1 \rangle = \lim_{\lambda \rightarrow 0} (1 + \lambda q_m(\lambda)) = 1.$$

Now we look at p and get

$$p(X) = \begin{pmatrix} \lambda^4 & 0 & 0 \\ 0 & (1 + \lambda^2)^2 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

Thus

$$\lim_{\lambda \rightarrow 0} \frac{1}{\lambda^2} (\langle r(X)^* p(X) e_1, e_1 \rangle + \langle p(X) r(X) e_1, e_1 \rangle) = 0.$$

If the representation of equation (6.2) holds, then apply $\langle \cdot, e_1, e_1 \rangle$ to both sides and take λ to 0. We just saw that the right side is 0, so the left side is 0, which because

$$\langle \sum r_j(X)^* r_j(X) e_1, e_1 \rangle \geq 0$$

forces

$$\lim_{\lambda \rightarrow 0} \frac{1}{\lambda^2} \langle Q^m e_1, e_1 \rangle \leq 0$$

a contradiction to equation (6.5). Hence the representation of equation (6.2) does not hold.

The last sentence claimed in the example is true when we use the same polynomial p and replace q with q^2 . ■

There are more Positivstellensätze in a free *-algebra which fill in more of the picture. The techniques proving them are not vastly beyond what we illustrated here. For example, Klep-Schweighofer [KS05] do an analog of Stengle's Theorem ??(a), while Theorem 3.9 is faithfully made free in [HM04a]. In spite of the above results we are still far from having a full understanding (à la Stengle's Theorem) of the Null- and Positiv-stellensätze phenomena in the free algebra.

6.2. The Weyl algebra. Weyl's algebra, that is the enveloping algebra of the Heisenberg group is interesting because, by a deep result of Stone-von Neumann, it has a single irreducible representation; and that is infinite dimensional. Thus, to check on the spectrum the positivity of an element, one has to do it at a single point. The details were revealed by Schmüdgen in a very recent article [S05]. We reproduce from his work the main result.

Fix a positive integer g and consider the unital *-algebra $W(g)$ generated by $2g$ self-adjoint elements $p_1, \dots, p_g, q_1, \dots, q_g$, subject to the commutation relations:

$$[p_k, q_j] = -\delta_{kj}(i \cdot 1), \quad [p_k, p_j] = [q_j, q_k] = 0, \quad 1 \leq j, k \leq g.$$

The unique irreducible representation Φ of this algebra is given by the partial differential operators

$$\Phi(p_k)f = -i \frac{\partial f}{\partial x_k}, \quad \Phi(q_k)f = x_k f,$$

acting on Schwartz space $\mathcal{S}(\mathbb{R}^g)$. Via this representation, the elements of $W(g)$ are identified with linear partial differential operators with polynomial coefficients (in g variables). These operators can be regarded as densely defined, closed graph operators from $\mathcal{S}(\mathbb{R}^g)$ to $L^2(\mathbb{R}^g)$. The set

$$W(g)_+ = \{f \in W(g); \langle \Phi(f)\xi, \xi \rangle \geq 0, \xi \in \mathcal{S}(\mathbb{R}^g)\}$$

consists of all symmetric, non-negative elements, with respect to the representation Φ .

Define

$$a_k = \frac{q_k + ip_k}{\sqrt{2}}, \quad a_{-k} = \frac{q_k - ip_k}{\sqrt{2}},$$

so that $a_k^* = a_{-k}$. Fix a positive number α which is not an integer, and let

$$N = a_1^* a_1 + \dots + a_g^* a_g;$$

denote by \mathcal{N} the set of all finite products of elements $N + (\alpha + n)1$, with $n \in \mathbb{Z}$.

The algebra $W(g)$ carries a natural degree, defined on generators as

$$\deg(a_k) = \deg(a_{-k}) = 1.$$

Every element $f \in W(g)$ can be decomposed into homogeneous parts f_s of degree s :

$$f = f_m + f_{m-1} + \dots + f_0.$$

We can regard f_k as a homogeneous polynomial of degree k , in the variables $a_{\pm 1}, \dots, a_{\pm g}$. The principal symbol of f is the polynomial $f_m(z_1, \dots, z_g, \bar{z}_1, \dots, \bar{z}_g)$, where a_j was substituted by z_k and a_{-k} by \bar{z}_k .

Theorem 6.11. [S05] *Let $f \in W(g)$ be a self-adjoint element of even degree $2m$, and let $P(z, \bar{z})$ be its principal symbol. If*

- a). There exists $\varepsilon > 0$ such that $f - \varepsilon \cdot 1 \in W(g)_+$,*
- b). $P(z, \bar{z}) > 0$ for $z \neq 0$,*

then, if m is even there exists $b \in \mathcal{N}$ such that $bfb \in \Sigma^2 W(g)$; if m is odd, there exists $b \in \mathcal{N}$ such that $\sum_{j=1}^g b a_j f a_{-j} b \in \Sigma^2 W(g)$.

For examples and details see [S05].

Already mentioned and annotated was our serious omission of any description of the Nullstellensatz in a Weyl Algebra.

6.3. Sums of squares modulo cyclic equivalence. A still open, important conjecture in the classification theory of von Neumann algebras was recently reduced by F. Radulescu to an asymptotic Positivstellensatz in the free algebra. We reproduce from his preprint [Radul04] the main result. We do not explain below the standard terminology related to von Neumann algebras, see for instance [Tak02].

The following conjecture was proposed thirty years ago in [Connes76]:

Every type II_1 factor can be embedded into an ultraproduct of the hyperfinite factor.

There are presently quite a few reformulations or reductions of this conjecture. The one of interest for this survey can be formulated as follows.

Let $F = \mathbb{C}\langle x_1, \dots, x_g \rangle$ be the free algebra with anti-linear involution $x_j^* = x_j$, $1 \leq j \leq g$. We complete F to the algebra of convergent series

$$\hat{F} = \left\{ \sum_w a_w w; \sum_w |a_w| r^{|w|} < \infty, \forall r > 0 \right\},$$

where w runs over all words in F and $a_w \in \mathbb{C}$. The resulting Fréchet space \hat{F} carries a natural weak topology denoted $\sigma(\hat{F}, \hat{F}^*)$.

A trace τ in a von-Neumann algebra M is a linear functional which has by definition the cyclic invariant property $\tau(a_1 \dots a_n) = \tau(a_2 a_3 \dots a_n a_1)$. Two series $f_1, f_2 \in \hat{F}$ are called *cyclically equivalent* if $f_1 - f_2$ is the weak limit of a linear combination of elements $w - w'$, where $w \in F$ is a word and w' is a cyclic permutation of it.

The following asymptotic Positivstellensatz holds.

Theorem 6.12. [Radul04] *Let $f \in \hat{F}$ be a symmetric series with the property that for every separable, type II_1 von Neumann algebra (M, τ) and every g -tuple of self-adjoint elements X of M we have $\tau(f(X)) \geq 0$. Then f is cyclically equivalent to a weak limit of sums of squares s_n , $s_n \in \Sigma^2 F$.*

It is not known whether one can replace the test II_1 algebras by finite dimensional algebras, but an answer to this query would solve Connes conjecture.

Corollary 6.13. *Connes embedding conjecture holds if and only if for every symmetric element $f \in \hat{F}$ the following assertion holds:*

f is cyclically equivalent to a weak limit of sums of squares s_n , $s_n \in \Sigma^2 F$, if and only if for any positive integer d and g -tuple of self-adjoint $d \times d$ matrices X one has $\text{trace} f(X) \geq 0$.

The proofs of Radulescu's theorem and the corollary follow the same pattern we are by now familiar with: a convex separation argument followed by a GNS construction. See for details [Radul04], and for a last minute refinement [KS06].

7. CONVEXITY IN A FREE ALGEBRA

Convexity of functions, domains and their close relative, positive curvature of varieties, are very natural notions in a $*$ -free algebra. A shocking thing happens: these convex functions are so rare as to be almost trivial. This section illustrates a simple case, that of convex polynomials, and we see how in a free algebra the Nichtnegativtellsätze have extremely strong consequences for inequalities on derivatives. The phenomenon has direct

qualitative consequences for systems engineering as we see in §???. The results of this section can be read independently of all but a few definitions in §6, and the proofs require only a light reading of it.

This time $\mathbb{R}\langle x \rangle$ denotes the free $*$ -algebra in indeterminates $x = (x_1, \dots, x_g)$, over the real field. There is an involution $x_j^* = x_j$ which reverses the order of multiplication $(fp)^* = p^*f^*$. In this exposition we take symmetric variables $x_j = x_j^*$, but in the literature we are summarizing typically x_j can be taken either free or symmetric with no change in the conclusion, for example, the results also hold for symmetric polynomials in $\mathbb{R}\langle x, x^* \rangle$.

A symmetric polynomial $p, p^* = p$, is *matrix convex* if for each positive integer n , each pair of tuples $X = (X_1, \dots, X_g)$ and $Y = (Y_1, \dots, Y_g)$ of symmetric $n \times n$ matrices, and each $0 \leq t \leq 1$,

$$(7.1) \quad p(tX + (1-t)Y) \leq tp(X) + (1-t)p(Y).$$

Even in one-variable, convexity in the noncommutative setting differs from convexity in the commuting case because here Y need not commute with X . For example, to see that the polynomial $p = x^4$ is not matrix convex, let

$$X = \begin{pmatrix} 4 & 2 \\ 2 & 2 \end{pmatrix} \text{ and } Y = \begin{pmatrix} 2 & 0 \\ 0 & 0 \end{pmatrix}$$

and compute

$$\frac{1}{2}X^4 + \frac{1}{2}Y^4 - \left(\frac{1}{2}X + \frac{1}{2}Y\right)^4 = \begin{pmatrix} 164 & 120 \\ 120 & 84 \end{pmatrix}$$

which is not positive semi-definite. On the other hand, to verify that x^2 is a matrix convex polynomial, observe that

$$\begin{aligned} tX^2 + (1-t)Y^2 & - (tX + (1-t)Y)^2 \\ & = t(1-t)(X^2 - XY - YX + Y^2) = t(1-t)(X - Y)^2 \geq 0. \end{aligned}$$

Theorem 7.1. [HM04b] *Every convex symmetric polynomial in the free algebra $\mathbb{R}\langle x \rangle$ or $\mathbb{R}\langle x, x^* \rangle$ has degree two or less.*

As we shall see convexity of p is equivalent to its “second directional derivative” being a positive polynomial. As a matter of fact, the phenomenon has nothing to do with order two derivatives and the extension of this to polynomials with k^{th} derivative nonnegative is given later in Theorem 7.4.

Yet stronger about convexity is the next local implies global theorem.

Let \mathcal{P} denote a collection of symmetric polynomials in non-commutative variables $x = \{x_1, \dots, x_g\}$. Define the matrix nonnegativity domain $\mathcal{D}_{\mathcal{P}}$ associated to \mathcal{P} to be the set of tuples $X = (X_1, \dots, X_g)$ of finite dimensional *real* matrices of all sizes, except 0 dimensions, making $p(X_1, \dots, X_g)$ a positive semi-definite matrix.

Theorem 7.2. [HM04b] *Suppose there is a set \mathcal{P} of symmetric polynomials, whose matrix nonnegativity domain $\mathcal{D}_{\mathcal{P}}$ contains open sets in all large enough dimensions. Then every symmetric polynomial p in $\mathbb{R}\langle x \rangle$ or in $\mathbb{R}\langle x, x^* \rangle$ which is matrix convex on $\mathcal{D}_{\mathcal{P}}$ has degree two or less.*

The first convexity theorem follows from Theorem 6.3, and we outline below the main ideas in its proof. The proof of the more general, order k derivative, is similar and we will return to it later in this section. The proof of Theorem 7.2 requires different machinery (like that behind representation (??)) and is not presented here.

At this point we describe a bit of history. In the beginning was Karl Löwner who studied a class of real analytic functions in one real variable called matrix monotone, which we shall not define here. Löwner gave integral representations and these have developed beautifully over the years. The impact on our story comes a few years later when Löwner's student Klaus [K36] introduced matrix convex functions f in one variable. Such a function f on $[0, \infty] \subset \mathbb{R}$ can be represented as $f(t) = tg(t)$ with g matrix monotone, so the representations for g produce representations for f . Modern references are [OSTprept], [U02]. Frank Hansen has extensive deep work on matrix convex and monotone functions whose definition in several variables is different than the one we use here, see [HanT06]; for a recent reference see [Han97].

For a polynomial $p \in \mathbb{R}\langle x \rangle$ define the *directional derivative*:

$$p'(x)[h] = \frac{d}{dt}p(x + th)|_{t=0}.$$

It is a linear form in h . Similarly, the k^{th} derivative

$$p^{(k)}(x)[h] = \frac{d^k}{dt^k}p(x + th)|_{t=0}$$

is homogeneous of degree k in h .

More formally, we regard the directional derivative $p'(x)[h] \in \mathbb{R}\langle x, h \rangle$ as a polynomial in $2g$ free symmetric (i.e. invariant under $*$) variables $(x_1, \dots, x_g, h_1, \dots, h_g)$; In the case of a word $w = x_{j_1}x_{j_2} \cdots x_{j_n}$ the derivative is:

$$w'[h] = h_{j_1}x_{j_2} \cdots x_{j_n} + x_{j_1}h_{j_2}x_{j_3} \cdots x_{j_n} + \dots + x_{j_1} \cdots x_{j_{n-1}}h_{j_n}$$

and for a polynomial $p = \sum p_w w$ the derivative is

$$p'(x)[h] = \sum p_w w'[h].$$

If p is symmetric, then so is p' .

For g -tuples of symmetric matrices of a fixed size X, H , observe that the evaluation formula

$$p'(X)[H] = \lim_{t \rightarrow 0} \frac{p(X + tH) - p(X)}{t}$$

holds. Alternately, with $q(t) = p(X + tH)$, we find.

$$p'(X)[H] = q'(0).$$

Likewise for a polynomial $p \in \mathbb{R}\langle x \rangle$, the *Hessian* $p''(x)[h]$ of $p(x)$ can be thought of as the formal second directional derivative of p in the “direction” h . Equivalently, the Hessian of $p(x)$ can also be defined as the part of the polynomial

$$r(x)[h] := p(x + h) - p(x)$$

in the free algebra in the symmetric variables that is homogeneous of degree two in h .

If $p'' \neq 0$, that is, if degree $p \geq 2$, then the degree of $p''(x)[h]$ as a polynomial in the $2g$ variables $x_1, \dots, x_g, h_1, \dots, h_g$ is equal to the degree of $p(x)$ as a polynomial in x_1, \dots, x_g .

Likewise for k^{th} derivatives.

Example 7.3. 1. $p(x) = x_2x_1x_2$

$$p'(x)[h] = \frac{d}{dt}[(x_2 + th_2)(x_1 + th_1)(x_2 + h_2)]|_{t=0} = h_2x_1x_2 + x_2h_1x_2 + x_2x_1h_2.$$

2. One variable $p(x) = x^4$. Then

$$p'(x)[h] = hxxx + xhxx + xxhx + xxhx$$

Note each term is linear in h and h replaces each occurrence of x once and only once:

$$p''(x)[h] =$$

$$hhxx + hhxx + hxhx + hxhx +$$

$$hxhx + xhxx + xhxx + xhxx +$$

$$hxhx + hxhx + xxhh + xxhh,$$

which yields

$$p''(x)[h] = 2hhxx + 2hxhx + 2hxhx + 2xhxx + 2xhxx + 2xhxx.$$

Note each term is degree two in h and h replaces each pair of x 's exactly once. Likewise

$$p^{(3)}(x)[h] = 6(hhxx + hhxx + hxhx + xhxx)$$

and $p^{(4)}(x)[h] = 24hhhh$ and $p^{(5)}(x)[h] = 0$.

$$3. \quad p = x_1^2 x_2$$

$$p''(x)[h] = h_1^2 x_2 + h_1 x_1 h_2 + x_1 h_1 h_2.$$

□

The definition of a convex polynomial can be easily adapted to domains. Then one remarks without difficulty that, in exact analogy with the commutative case, a polynomial p is convex (in a domain) if and only if the Hessian evaluated at the respective points is non-negative definite. Because of this Theorem 7.1 is an immediate consequence of the next theorem restricted to $k = 2$.

Theorem 7.4. *Every symmetric polynomial p in the free algebra $\mathbb{R}\langle x \rangle$ or $\mathbb{R}\langle x, x^* \rangle$ whose k^{th} derivative is a matrix positive polynomial has degree k or less.*

Proof (when the variables x_j are symmetric).

Assume $p^{(k)}(x)[h]$ is a matrix positive polynomial, so that, in view of Theorem 6.3 we can write it as a sum of squares:

$$p^{(k)}(x)[h] = \sum f_j^* f_j;$$

here each $f_j(x, h)$ is a polynomial in the free algebra $\mathbb{R}\langle x, h \rangle$.

If $p^{(k)}(x)[h]$ is identically equal to zero, then the statement follows. Assume the contrary, so that $p^{(k)}(x)[h]$ is homogeneous of degree k in h , and there are tuples of matrices X, H and a vector ξ in the underlying finite dimensional Hilbert space, so that

$$\langle p^{(k)}(X)[H]\xi, \xi \rangle > 0.$$

By multiplying H by a real scalar t we find

$$t^k \langle p^{(k)}(X)[H]\xi, \xi \rangle = \langle p^{(k)}(X)[tH]\xi, \xi \rangle > 0,$$

whence $k = 2\mu$ is an even integer.

Since in a sum of squares the highest degree terms cannot cancel, the degree of each f_j is at most ν in x and μ in h , where 2ν is the degree of $p^{(k)}$ in x .

Since $p^{(k)}$ is a directional derivative, it must have a highest degree term of the form $h_{i_1} \cdots h_{i_k} m(x)$ where the monomial $m(x)$ has degree equal to degree $p^{(k)} - k$; also h_{i_j} is allowed to equal h_{i_ℓ} . Thus some product, denote it $f_J^* f_J$, must contain such a term. (Note the the order of the h 's vs. the x 's matters.) This forces f_J to have the form

$$f_J = c_1(h_{i_{\mu+1}} \cdots h_{i_k})m(x) + c_2(h_{i_1} \cdots h_{i_\mu}) + \dots,$$

the c_j being scalars.

To finish the proof use that $f_J^* f_J$ contains

$$c^2 m(x)^*(h_{i_{\mu+1}} \cdots h_{i_k})^*(h_{i_{\mu+1}} \cdots h_{i_k})m(x)$$

and this can not be cancelled out, so

$$\deg p^{(k)} = k + 2(\deg p^{(k)} - k) = 2 \deg p^{(k)} - k.$$

Solve this to find $\deg p^{(k)} = k$. Thus p has degree k . ■

We use a previous example in order to illustrate this proof when $k = 2$.

Example 7.5. Example $p = x^4$ is not matrix convex; here $x = x^*$.

Calculate that

$$p''(x)[h] = 2h h x x + 2h x h x + 2h x x h + 2x h h x + 2x h x h + 2x x h h.$$

Up to positive constants some polynomial $f_J^* f_J$ contains a term $h h x x$, so $f_J = h x x + h + \dots$

So $f_J^* f_J$ contains $x x h h x x$. This is a highest order perfect square so can be cancelled out. Thus it appears in p'' , which as a consequence has degree 6. This a contradiction. □

We call the readers attention to work which goes beyond what we have done in several directions. One [HMVprept] concerns a noncommutative rational function r and characterizes those which are convex near 0. It is an extremely small and rigidly behaved class, for example, r is convex on the entire component of the "domain of r " which contains 0. This rigidity is in analogy to convex polynomials on some "open set" having degree 2 or less and this implying they are convex everywhere. Another direction is the classification of noncommutative polynomials whose Hessian $p''(x)[h]$ at most k "negative noncommutative eigenvalues" In [DHMprept] it is shown that this implies

$$\deg p \leq 2k + 2.$$

Of course the special case we studied in this section is exactly that of polynomials with $k = 0$.

8. A GUIDE TO LITERATURE

While classical semi-algebraic geometry has developed over the last century through an outpouring of seemingly countless papers, the thrust toward a noncommutative semi-algebraic geometry is sufficiently new that we have attempted to reference the majority of papers directly on the subject here in this survey. This non-discriminating approach is not entirely good news for the student, so in this section we provide some guidance to the more readable references.

The Functional Analysis book by Riesz and Nagy [RN90] is a class in itself. For a historical perspective on the evolution of the spectral theorem the reader can go directly to Hilbert's book [Hilb1953] or the German Encyclopedia article by Hellinger and Toeplitz [HT53]. Reading von Neumann in original [vN1] is still very rewarding.

The many facets of matrix positivity, as applied to function theory and systems theory, are well exposed in the books by Agler-McCarthy [AM02], Foias-Frazho [FF90] and Rosenblum-Rovnyak [RR97]. The monograph of Constantinescu [Constantinescu96] is entirely devoted to the Schur algorithm.

For the classical moment problem Akhiezer's text [Akh65] remains the basic reference, although having a look at Marcel Riesz original articles [MR23], Carleman's quasi-analytic functions [C26], or at the continued fractions monograph of Perron [Per50] might bring new insights. Good surveys of the multivariate moment problems are Berg [Berg87] and Fuglede [F83]. Reznick's memoir [R92] exploits in a novel and optimal way the duality between moments and positive polynomials.

For real algebraic geometry, including the logical aspects of the theory, we refer to the well circulated texts [BCR98, J89, M00] and the recent monograph by Prestel and Delzell [PD01]; the latter offers an elegant and full access to a wide selection of aspects of positive polynomials. For new results in algorithmic real (commutative) algebra see [BPR03]; all recent articles of Lasserre contain generous recapitulations and reviews of past articles devoted to applications of sums of squares and moments to optimization. Scheiderer's very informative survey [S03] is centered on sums of squares decompositions. Parrilo's thesis [ParThesis] is a wonderful exposition of many new areas of application which he discovered.

An account of one of the most systematic and elegant ways for producing LMIs for engineering problems is the subject of the book [SIG97]. The condensed version we heartily recommend is their 15 page paper [SI95].

Software:

Common semi-definite programming packages are [Sturm99] *SeDuMi* and *LMI Toolbox* [GNLC95].

Semi-algebraic geometry packages are *SOS tools* [PPSP04] and *GloptiPoly* [HL03].

For symbolic computation in a free $*$ - algebra see *NCAAlgebra* and *NCGB* (which requires Mathematica) [HSM05].

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