## 29. Final review I

## Example 29.1. Find a basis of

 $W = \{ (a+2b+4c+8d, 2a+4b+6c+8d, 3a+6b+9c+12d) \mid (a, b, c, d) \in \mathbb{R}^4 \}.$ 

Implicit in this question is the assumption that W is a linear subspace of  $\mathbb{R}^3$ . Given a matrix A there are three linear spaces one can attach to A, the column space, the row space and the null space.

There are many ways to see how to attach a matrix to W. One way is to realise that W is the image of the linear map

$$f: \mathbb{R}^4 \longrightarrow \mathbb{R}^3$$

given by

$$(a, b, c, d) \longrightarrow (a + 2b + 4c + 8d, 2a + 4b + 6c + 8d, 3a + 6b + 9c + 12d)$$

There is a matrix A associate to f. It is the matrix A such that  $f(\vec{x}) = A\vec{x}$ . A is a  $3 \times 4$  matrix. The columns of A correspond to the images of the four standard basis vectors.

$$\vec{e}_1 = (1, 0, 0, 0), \qquad \vec{e}_2 = (0, 1, 0, 0), \qquad \vec{e}_3 = (0, 0, 1, 0) \qquad \text{and} \qquad \vec{e}_4 = (0, 0, 0, 1)$$

The images are

$$f(1,0,0,0) = (1,2,3), \quad f(0,1,0,0) = (2,4,6), \quad f(\vec{e}_3) = (4,6,9) \text{ and } f(\vec{e}_4) = (8,8,12).$$
  
Therefore

$$A = \begin{pmatrix} 1 & 2 & 4 & 8 \\ 2 & 4 & 6 & 8 \\ 3 & 6 & 9 & 12 \end{pmatrix}.$$

Note that the row space and the null space of A are linear subspaces of  $\mathbb{R}^4$ . The column space of A is a linear subspace of  $\mathbb{R}^3$ . In fact the column space is indeed the image of the linear map f.

Here is another way to see all of this:

$$\begin{pmatrix} a+2b+4c+8d\\ 2a+4b+6c+8d\\ 3a+6b+9c+12d \end{pmatrix} = \begin{pmatrix} a\\ 2a\\ 3a \end{pmatrix} + \begin{pmatrix} 2b\\ 4b\\ 6b \end{pmatrix} + \begin{pmatrix} 4c\\ 6c\\ 9c \end{pmatrix} + \begin{pmatrix} 8d\\ 8d\\ 12d \end{pmatrix}$$
$$= a \begin{pmatrix} 1\\ 2\\ 3 \end{pmatrix} + b \begin{pmatrix} 2\\ 4\\ 6 \end{pmatrix} + c \begin{pmatrix} 4\\ 6\\ 9 \end{pmatrix} + d \begin{pmatrix} 8\\ 8\\ 12 \end{pmatrix}$$
$$= \begin{pmatrix} 1 & 2 & 4 & 8\\ 2 & 4 & 6 & 8\\ 3 & 6 & 9 & 12 \end{pmatrix} \begin{pmatrix} a\\ b\\ c\\ d \end{pmatrix}.$$

Visibily then W is the column space of A. Therefore W is a linear subspace and it does make sense to look for a basis of W.

We apply Gaussian elimination:

$$\begin{pmatrix} 1 & 2 & 4 & 8 \\ 2 & 4 & 6 & 8 \\ 3 & 6 & 9 & 12 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 2 & 4 & 8 \\ 0 & 0 & -2 & -8 \\ 0 & 0 & -3 & -12 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 2 & 4 & 8 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & -3 & -12 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 2 & 4 & 8 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

There are pivots in the first and third rows. Gaussian elimination does not preserve the column space but it does preserve the relations. The first and third columns are a basis at the end of the elimination so the first and third columns of A are a basis of the column space.

The column space is the span of the vectors (1, 2, 3) and (4, 6, 9).

Note that (1, 2, 4, 8) and (0, 0, 1, 4) is basis for the row space. Gaussian elimination preserves the row space.

**Example 29.2.** Given that (a, b, c, d) = (1, 1, 1, 1) is a solution to the linear equations

$$a + 2b + 4c + 8d = 15$$
  
 $2a + 4b + 6c + 8d = 20$   
 $3a + 6b + 9c + 12d = 33$ ,

what is the general solution?

The general solution of the linear equations  $A\vec{x} = \vec{b}$  is the sum of a particular solution plus the general solution of the homogeneous equation  $A\vec{x} = \vec{0}$ .

We know that A is row equivalent to

$$\begin{pmatrix} 1 & 2 & 4 & 8 \\ 0 & 0 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{pmatrix}.$$

We can find the general solution to the homogeneous by back substitution. a and c are basic variables, b and d are free variables. Hence

$$c + 4d = 0$$
 so that  $c = -4d$ 

and

a + 2b - 16d + 8d = 0 so that a = -2b + 8d.

The general solution of the homogeneous is

$$(a, b, c, d) = (-2b + 8d, b, -4d, d) = b(-2, 1, 0, 0) + d(8, 0, -4, 1).$$

The null space has a basis (-2, 1, 0) and (8, -4, 1).

The general solution to the linear equations in (29.2) is

$$(a, b, c, d) = (1, 1, 1, 1) + b(-2, 1, 0) + d(8, -4, 1).$$

**Example 29.3.** If A is a  $3 \times 3$  matrix and det A = 3 what is det 2A?

The answer is

$$2^3 \cdot 3 = 24.$$

There are two ways to see this. The first is algebraic. If you multiply a row by 2 then the determinant gets multiplied by 2. A  $3 \times 3$  matrix has three rows, so that each row is multiplied by 2. Thus the determinant gets multiplied by  $2^3 = 8$ .

The second is geometric. The absolute value of the determinant of A is the volume of a parallelepiped with sides given by the rows of A. If we multiply A by 2 then each side is doubled. Thus the volume goes up by a factor of 8.