

KEY WORDS: CURL, CONSERVATIVE VECTOR FIELD, FORMAL DETERMINANT

## 23.1 Conservative vector fields

Recall that  $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$  is **conservative** if  $f = \nabla F$  for some  $F : \mathbb{R}^n \rightarrow \mathbb{R}$ . A test for conservativity of a given vector field in  $\mathbb{R}^2$  or  $\mathbb{R}^3$  is done using the **curl** of the vector field.

**Definition.**

The curl of a vector field  $(f, g, h)$  in  $\mathbb{R}^3$ , denoted  $\text{curl}(f)$  or  $\nabla \times f$ , is the vector  $(h_y - g_z, f_z - h_x, g_x - f_y)$ .

An easy way to remember the formula for the curl is to write it as a formal determinant:

$$\nabla \times f = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ f & g & h \end{vmatrix}.$$

Here we use the notation  $i = (1, 0, 0)$ ,  $j = (0, 1, 0)$  and  $k = (0, 0, 1)$ , and when we multiply  $\frac{\partial}{\partial x}$  by  $g$  for example, we formally obtain  $g_x$ . As an exercise, verify that this gives the above formula from the definition. We now come to a simple test for a vector field  $f : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  to be conservative. An oriented curve  $\gamma$  in  $\mathbb{R}^3$  is **simple** if it is the image of a one-to-one piecewise  $C^1$  map  $r : [a, b] \rightarrow \mathbb{R}^3$ . It is **closed** if it is one-to-one on  $(a, b]$  and  $r(a) = r(b)$ .

**Test for Conservativity.**

1. A vector field  $f$  is conservative if and only if  $\nabla \times f = 0$ .
2. A vector field  $f$  is conservative if and only if for any two simple oriented curves  $\gamma$  and  $\delta$  with the same endpoints,  $\int_{\gamma} f \cdot dr = \int_{\delta} f \cdot dr$ .
3. A vector field  $f$  is conservative if and only if for any simple oriented closed curve  $\gamma$ ,  $\int_{\gamma} f \cdot dr = 0$ .

**Example 1.** Let  $f(x, y, z) = (yz, xz, xy)$ . We saw that this is conservative since  $f = \nabla F$  where  $F = xyz$ . Now we check it using the test

$$\begin{aligned} \nabla \times f &= \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ yz & xz & xy \end{vmatrix} \\ &= i \left( \frac{\partial xy}{\partial y} - \frac{\partial xz}{\partial z} \right) - j \left( \frac{\partial xy}{\partial x} - \frac{\partial yz}{\partial z} \right) + k \left( \frac{\partial xz}{\partial x} - \frac{\partial yz}{\partial y} \right) \\ &= (x - x, y - y, z - z) = 0. \end{aligned}$$

Therefore  $f$  is conservative.

**Example 2.** Determine  $\int_{\gamma} f \cdot dr$  when  $\gamma$  is the curve  $(t^2, \cos \pi t^2, \log t)$  for  $1 \leq t \leq 2$  and  $f(x, y, z) = (1 + y + yz, x + xz, xy)$ .

**Solution.** The line integral will be impossible to evaluate explicitly unless we can show  $f$  is conservative. Now it is straightforward to check that  $\nabla \times f = 0$  so by the test for conservativity,  $f$  is conservative. This means

$$\int_{\gamma} f \cdot dr = F(4, 1, \log 2) - F(1, -1, 0)$$

if  $f = \nabla F$ . There are two ways to proceed. One is to try to find  $F$ . The other is to use part 2 of the test to replace  $\gamma$  by a much simpler curve joining  $(1, -1, 0)$  to  $(4, 1, \log 2)$ . For example, we could replace  $\gamma$  by  $r(t) = (3t + 1, 2t - 1, t \log 2)$  for  $0 \leq t \leq 1$ . Then  $\frac{dr}{dt} = (3, 2, \log 2)$  and the line integral is

$$\begin{aligned} \int_{\gamma} f \cdot dr &= \int_0^1 f(r(t)) \cdot \frac{dr}{dt} dt \\ &= \int_0^1 [3[2t + (2t - 1)(t \log 2)] + 2[(3t + 1)(1 + t \log 2)] + \log 2(3t + 1)(2t - 1)] dt \\ &= 8 + 4 \log 2. \end{aligned}$$

It is important that this replacement of  $\gamma$  is only possible because  $f$  is conservative (by part 2 of the test). Now let's use the alternative, which is to compute  $F$  such that  $f = \nabla F$ . We need

$$\frac{\partial F}{\partial x} = 1 + y + yz \quad \frac{\partial F}{\partial y} = x + xz \quad \frac{\partial F}{\partial z} = xy.$$

Such equations for unknown  $F$  are called [partial differential equations](#), and generally very difficult to solve. In this situation, however, we can solve them as follows. Since  $F_x = 1 + y + yz$ , we know

$$F(x, y, z) = x + xy + xyz + c(y, z)$$

because when we take derivatives in  $x$  the function  $c(y, z)$  disappears and we get  $1 + y + yz$ . This is like integrating in the usual sense, except that the arbitrary constant of integration is now a function of  $y$  and  $z$ . Since  $F_y = x + xz$  we also have

$$F(x, y, z) = xy + xyz + d(x, z)$$

for some function  $d(x, z)$ . Finally  $F_z = xy$  so

$$F(x, y, z) = xyz + e(x, y)$$

for some function  $e(x, y)$ . We have concluded

$$F(x, y, z) = x + xy + xyz + c(y, z) = xy + xyz + d(x, z) = xyz + e(x, y)$$

from which we get  $c(y, z) = 0$ ,  $d(x, z) = x$  and  $e(x, y) = x + xy$ . Therefore

$$F(x, y, z) = x + xy + xyz.$$

Now the integral is

$$\int_{\gamma} f \cdot dr = F(4, 1, \log 2) - F(1, -1, 0) = 8 + 4 \log 2.$$

## 23.2 Line Integrals of Scalar Fields

A vector field is a function  $f : \mathbb{R}^n \rightarrow \mathbb{R}^n$ . A **scalar field** is a function  $f : \mathbb{R}^n \rightarrow \mathbb{R}$ . We have already defined line integrals of vector fields, and we will now define line integrals for scalar fields. If  $\gamma$  is a curve in  $\mathbb{R}^n$  parametrized by a function  $r(t) : [a, b] \rightarrow \mathbb{R}^n$ , then the line integral of a scalar field  $f$  along  $\gamma$  is defined by

$$\int_{\gamma} f ds = \int_a^b f(r(t)) \left\| \frac{dr}{dt} \right\| dt$$

where

$$\left\| \frac{dr}{dt} \right\| = \sqrt{\left(\frac{dx_1}{dt}\right)^2 + \left(\frac{dx_2}{dt}\right)^2 + \dots + \left(\frac{dx_n}{dt}\right)^2}.$$

The notation  $ds$  refers to the **element of arclength**. When  $f = 1$ , then the line integral of  $f$  along  $\gamma$  is just the length of the curve  $\gamma$ .

**Example 1.** Determine the line integral of the scalar field  $f(x, y) = x^2 + y^2$  over the spiral  $r = \theta$  for  $0 \leq \theta \leq 2\pi$  in polar co-ordinates.

**Solution.** The curve  $\gamma$  given by  $r = \theta$  is parametrized by

$$r(t) = (x(t), y(t)) = (r \cos t, r \sin t) = (t \cos t, t \sin t).$$

So

$$\frac{dr}{dt} = (\cos t - t \sin t, \sin t + t \cos t).$$

Therefore

$$\begin{aligned} \int_{\gamma} f ds &= \int_0^{2\pi} f(t \cos t, t \sin t) \sqrt{\cos^2 t + t^2 \sin^2 t - 2t \cos t \sin t + \sin^2 t + t^2 \cos^2 t + 2t \sin t \cos t} dt \\ &= \int_0^{2\pi} t^2 \sqrt{1 + t^2} dt \\ &= \end{aligned}$$

**Example 2.** Show that the length of  $y = f(x)$  for  $a \leq x \leq b$  is

$$\int_a^b \sqrt{1 + \left(\frac{df}{dx}\right)^2} dx.$$

**Solution.** The line integral representing length of a curve  $\gamma$  given by  $(x(t), y(t))$  is

$$\int_{\gamma} \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2} dt.$$

Now we parametrize  $y = f(x)$  using  $x$  as a parameter: so  $r(x) = (x, f(x))$  is the parametrization. Putting this in the formula, we get the result. Now for example we could find the length of the parabola  $y = \frac{1}{2}x^2$  for  $-1 \leq x \leq 1$ : it is

$$\int_{-1}^1 \sqrt{1 + x^2} dx = \sqrt{2} + \operatorname{arcsinh}(1).$$

## 23.3 Surface Integrals

Just as we have generalized Riemann integrals  $\int_a^b f(x)dx$  to line integrals  $\int_{\gamma} f \cdot dr$ , we can generalize double integrals  $\iint_D f dA$  to integrals over surfaces, which we will refer to as **surface integrals**. We begin with surface integrals of scalar fields. A surface  $\Sigma$  in  $\mathbb{R}^3$  can be written in parametric form using two parameters. Thus  $s(u, v) = (x(u, v), y(u, v), z(u, v))$  would be an example of a parametrized surface in  $\mathbb{R}^3$ , where  $u, v$  are in some set  $D \subseteq \mathbb{R}^2$ . For instance,  $s(u, v) = (\cos u \sin v, \sin u \sin v, \cos v)$  parametrizes the unit sphere in  $\mathbb{R}^3$  if  $0 \leq u < 2\pi$  and  $0 < v < \pi$ .

Given a parametrization  $s(u, v)$  of a given surface, we can define **tangent vectors** to the surface. The tangent vectors are

$$\begin{aligned} T_u &= \left( \frac{\partial x}{\partial u}, \frac{\partial y}{\partial u}, \frac{\partial z}{\partial u} \right) \\ T_v &= \left( \frac{\partial x}{\partial v}, \frac{\partial y}{\partial v}, \frac{\partial z}{\partial v} \right). \end{aligned}$$

These are really important in the definition of surface integrals.

### DarkGreenDefinition.

Let  $f : \mathbb{R}^3 \rightarrow \mathbb{R}$  be a scalar field defined on a surface  $S$  parametrized by  $s(u, v) = (x(u, v), y(u, v), z(u, v))$  for  $(u, v) \in D$  with tangent vectors  $T_u$  and  $T_v$ . Then the surface integral of  $f$  over  $S$  is defined by

$$\iint_S f dS = \iint_D f(s(u, v)) \|T_u \times T_v\| du dv$$

when this integral exists.

Recall that  $T_u \times T_v$  is the vector or cross product of  $T_u$  and  $T_v$ , determined from the formal determinant

$$\begin{vmatrix} i & j & k \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & \frac{\partial z}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & \frac{\partial z}{\partial v} \end{vmatrix}.$$

So this is the vector  $(y_u z_v - z_u y_v, z_u x_v - x_u z_v, x_u y_v - y_u x_v)$ . After computing this, we then take the norm,  $\|T_u \times T_v\|$ , to get

$$\|T_u \times T_v\| = \sqrt{(y_u z_v - z_u y_v)^2 + (z_u x_v - x_u z_v)^2 + (x_u y_v - y_u x_v)^2}.$$

In the case that  $f = 1$ , the integral above represents the **surface area** of the surface  $S$ .

**Example 1.** Suppose that  $S$  is given by  $z = f(x, y)$  for  $(x, y) \in D$ . Find a formula for the surface area of  $S$ .

**Solution.** We parametrize the surface as  $s(x, y) = (x, y, f(x, y))$  for  $(x, y) \in D$ . The tangent vectors are  $T_x = (1, 0, f_x)$  and  $T_y = (0, 1, f_y)$  and so we check that

$$\|T_x \times T_y\| = \sqrt{1 + f_x^2 + f_y^2}.$$

It follows that the surface area is

$$\iint_S 1 dS = \iint_D \sqrt{1 + f_x^2 + f_y^2} dx dy.$$

**Example 2.** Evaluate  $\iint_S z^2 dS$  where  $S$  is the surface of the cube  $[0, 1] \times [0, 1] \times [0, 1]$ .

**Solution.** The surface of the cube consists of six plane pieces. We add up the surface integrals over each of the plane pieces. For the topmost plane piece, we have  $z = 1$  and  $x, y \in [0, 1] \times [0, 1]$ . So we parametrize this surface as  $(x, y, 1)$  for  $(x, y) \in [0, 1] \times [0, 1]$ . Then  $T_x = (1, 0, 0)$  and  $T_y = (0, 1, 0)$  so  $\|T_x \times T_y\| = 1$ . Thus the integral over this piece is

$$\int_0^1 \int_0^1 1 dx dy = 1.$$