

## Lecture 6: Linear Independence, Spanning, Basis and Dimension.

The homogeneous system  $A\mathbf{x} = \mathbf{0}$  can be studied from a different perspective by writing them as vector equations;

$$(1) \quad \begin{bmatrix} 1 & 2 & -3 \\ 3 & 5 & 9 \\ 5 & 9 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Leftrightarrow x_1 \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix} + x_2 \begin{bmatrix} 2 \\ 5 \\ 9 \end{bmatrix} + x_3 \begin{bmatrix} -3 \\ 9 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

A set of vectors  $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$  in  $\mathbf{R}^n$  is said to be **linearly independent** if

$$x_1\mathbf{v}_1 + \dots + x_p\mathbf{v}_p = \mathbf{0}$$

has only the trivial solution  $x_1 = \dots = x_p = 0$ . The set  $\{\mathbf{v}_1, \dots, \mathbf{v}_p\}$  is said to be **linearly dependent** if there are weights  $\lambda_1, \dots, \lambda_p$  not all 0, such that

$$\lambda_1\mathbf{v}_1 + \dots + \lambda_p\mathbf{v}_p = \mathbf{0}.$$

**Ex 1** Determine if  $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix}$ ,  $\mathbf{v}_2 = \begin{bmatrix} 2 \\ 5 \\ 9 \end{bmatrix}$ ,  $\mathbf{v}_3 = \begin{bmatrix} -3 \\ 9 \\ 3 \end{bmatrix}$  are linearly independent?

**Sol** They are linearly dependent if (1) has a nontrivial solution. Augmented:

$$\begin{bmatrix} 1 & 2 & -3 & 0 \\ 3 & 5 & 9 & 0 \\ 5 & 9 & 3 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & -3 & 0 \\ 0 & -1 & 18 & 0 \\ 0 & -1 & 18 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & -3 & 0 \\ 0 & -1 & 18 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 33 & 0 \\ 0 & -1 & 18 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

Since  $x_3$  is free there are nontrivial solutions  $x_1 = -33x_3$ ,  $x_2 = 18x_3$ ,  $x_3$  is free. If we e.g. let  $x_3 = 1$  then  $x_1 = -33$  and  $x_2 = 18$  so we have the linear dependence relation

$$-33 \begin{bmatrix} 1 \\ 3 \\ 5 \end{bmatrix} + 18 \begin{bmatrix} 2 \\ 5 \\ 9 \end{bmatrix} + 1 \begin{bmatrix} -3 \\ 9 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \Leftrightarrow \begin{bmatrix} 1 & 2 & -3 \\ 3 & 5 & 9 \\ 5 & 9 & 3 \end{bmatrix} \begin{bmatrix} -33 \\ 18 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The columns of  $A$  are linearly independent  $\Leftrightarrow A\mathbf{x} = \mathbf{0}$  has only the trivial solution.

**Th**  $n$  vectors  $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  in  $\mathbf{R}^m$  are linearly dependent if  $n > m$ .

**Pf**  $A = [\mathbf{v}_1 \dots \mathbf{v}_n]$  is a  $m \times n$  matrix. If  $n > m$  then the homogeneous system  $A\mathbf{x} = \mathbf{0}$  has more unknowns than equations so there must be free variables. Hence  $A\mathbf{x} = \mathbf{0}$  has a nontrivial solution  $\mathbf{x} \neq \mathbf{0}$  so the columns of  $A$  are linearly dependent.

**Ex 2** With as little work as possible decide if the following sets of vectors are linearly dependent. (a)  $\left\{ \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 9 \\ 6 \\ 4 \end{bmatrix} \right\}$  and (b) the columns of  $\begin{bmatrix} 1 & 2 & 3 & 4 & 5 \\ 6 & 7 & 8 & 9 & 0 \\ 9 & 8 & 7 & 6 & 5 \end{bmatrix}$ .

**Sol** (a) linearly independent since one is not a multiple of the other. (b) linearly dependent since there are more columns than entries in the vectors.

We say that a set of vectors  $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  **span**  $H$  if every  $\mathbf{v} \in H$  can be written as a linear combination of them;  $\mathbf{v} = c_1\mathbf{v}_1 + \dots + c_n\mathbf{v}_n$ .

**Ex 3** Do the vectors in Ex. 2 or Ex. 3 Span  $\mathbf{R}^3$ ?

**Basis.**

Let  $H$  be a subspace of a vector space  $V$ .  $\{\mathbf{b}_1, \dots, \mathbf{b}_n\}$  is called a **basis** for  $H$  if

(i)  $\{\mathbf{b}_1, \dots, \mathbf{b}_n\}$  are linearly independent, and (ii)  $\{\mathbf{b}_1, \dots, \mathbf{b}_n\}$  span  $H$ .

This means that every  $\mathbf{v} \in H$  can be written  $\mathbf{v} = c_1\mathbf{b}_1 + \dots + c_n\mathbf{b}_n$  for a unique choice of constant  $c_1, \dots, c_n$ .

**Ex 4** Show that  $\mathbf{e}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ ,  $\mathbf{e}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$ ,  $\mathbf{e}_3 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$  is a basis for  $\mathbf{R}^3$ , the **standard basis**

**Sol** They span  $\mathbf{R}^3$  since any vector can be written  $\mathbf{x} = x_1\mathbf{e}_1 + x_2\mathbf{e}_2 + x_3\mathbf{e}_3$ .

They are linearly independent since  $x_1\mathbf{e}_1 + x_2\mathbf{e}_2 + x_3\mathbf{e}_3 = \mathbf{x} = \mathbf{0}$  implies  $x_1 = x_2 = x_3 = 0$ .

**Ex 5** Show that  $\mathbf{v}_1 = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$ ,  $\mathbf{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ ,  $\mathbf{v}_3 = \begin{bmatrix} 1 \\ 0 \\ 3 \end{bmatrix}$  is a basis for  $\mathbf{R}^3$ .

**Sol**  $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$  are linearly independent and span  $\mathbf{R}^3$  if and only if the reduced row echelon form of the matrix  $A = [\mathbf{v}_1 \ \mathbf{v}_2 \ \mathbf{v}_3]$  has 3 pivot columns. Row reduction

$$\begin{bmatrix} 1 & 0 & 1 \\ 2 & 1 & 0 \\ 0 & 1 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 1 & 3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -2 \\ 0 & 0 & 5 \end{bmatrix}$$

**Question:** Why lin. indep. if 3 pivots? ( $A\mathbf{x} = \mathbf{0}$ ) Why span if 3 pivots? ( $A\mathbf{x} = \mathbf{b}$ )

**Ex 6** Explain why not basis: (a)  $\left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 7 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ -3 \\ 7 \end{bmatrix} \right\}$ , (b)  $\left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \right\}$ .

**Sol** (a) Linearly dependent since more vectors than rows. (b) Since the matrix with the two vectors as columns does not have a pivot in every row they do not span  $\mathbf{R}^3$ .

**The Spanning Theorem** A basis can be constructed from a spanning set by discarding vectors which are linear combinations of the preceding vectors in the set.

**Ex 7** Find a basis for Col  $A$ , where  $A = [\mathbf{a}_1 \ \mathbf{a}_2 \ \mathbf{a}_3 \ \mathbf{a}_4]$  is given below:

$$[\mathbf{a}_1 \ \mathbf{a}_2 \ \mathbf{a}_3 \ \mathbf{a}_4] = \begin{bmatrix} 1 & 2 & 0 & 4 \\ 2 & 4 & -1 & 3 \\ 3 & 6 & 2 & 22 \\ 4 & 8 & 0 & 16 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 0 & 4 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} = [\mathbf{b}_1 \ \mathbf{b}_2 \ \mathbf{b}_3 \ \mathbf{b}_4]$$

$\mathbf{b}_2 = 2\mathbf{b}_1$  and  $\mathbf{a}_2 = 2\mathbf{a}_1$   
 $\mathbf{b}_4 = 4\mathbf{b}_1 + 5\mathbf{b}_3$ ,  $\mathbf{a}_4 = 4\mathbf{a}_1 + 5\mathbf{a}_3$   
 $\mathbf{b}_1$  and  $\mathbf{b}_3$  are not multiples.  
 $\mathbf{a}_1$  and  $\mathbf{a}_3$  are not multiples.

Elementary row operations do not affect linear dependency relations among the columns, since  $A\mathbf{x} = \mathbf{0} \Leftrightarrow B\mathbf{x} = \mathbf{0}$ . Hence  $\text{Span}\{\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3, \mathbf{a}_4\} = \text{Span}\{\mathbf{a}_1, \mathbf{a}_3\}$ .

**Th** The pivot columns of  $A$  form a basis for Col  $A$ .

To form a basis for Nul  $A$ , use row operations to find the reduced row echelon form  $[A \ \mathbf{0}] \sim [R \ \mathbf{0}]$  and use it to find the general solution of  $A\mathbf{x} = \mathbf{0}$  in parametric form. The vectors found in parametric form is a basis.

To find a basis for Col  $A$ , use row operations to find the reduced row echelon form  $A \sim R$  and use it to find the pivot columns. The pivot columns of  $A$  form a basis.

**Dimension.**

Recall that  $\mathbf{b}_1, \dots, \mathbf{b}_n$  form a **basis** for a vector space  $V$  if

- (i)  $\mathbf{b}_1, \dots, \mathbf{b}_n$  are linearly independent, and (ii)  $\mathbf{b}_1, \dots, \mathbf{b}_n$  span  $V$ .

**Th** If  $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  is a spanning set for  $V$  then any collection of  $p$  vectors  $\{\mathbf{u}_1, \dots, \mathbf{u}_p\}$ , where  $p > n$ , is linearly dependent.

**Pf** Since  $\mathbf{v}_1, \dots, \mathbf{v}_n$  span  $V$  we can write each  $\mathbf{u}_i$  as a linear combination:

$$\mathbf{u}_i = a_{i1}\mathbf{v}_1 + \dots + a_{in}\mathbf{v}_n$$

A linear combination of the  $\mathbf{u}_i$  can be written

$$\begin{aligned} c_1\mathbf{u}_1 + \dots + c_p\mathbf{u}_p &= c_1(a_{11}\mathbf{v}_1 + \dots + a_{1n}\mathbf{v}_n) + \dots + c_p(a_{p1}\mathbf{v}_1 + \dots + a_{pn}\mathbf{v}_n) \\ &= (c_1a_{11} + \dots + c_pa_{p1})\mathbf{v}_1 + \dots + (c_1a_{p1} + \dots + c_pa_{pn})\mathbf{v}_n \end{aligned}$$

Hence  $c_1\mathbf{u}_1 + \dots + c_p\mathbf{u}_p = \mathbf{0}$  if

$$\begin{aligned} c_1a_{11} + \dots + c_pa_{p1} &= 0 \\ &\vdots \\ c_1a_{1n} + \dots + c_pa_{pn} &= 0 \end{aligned}$$

Since  $p > n$  this is a homogenous system for  $c_1, \dots, c_p$  with more unknowns than equations so it has a nontrivial solution. Hence there are constants  $c_1, \dots, c_p$  not all zero such that  $c_1\mathbf{u}_1 + \dots + c_p\mathbf{u}_p = \mathbf{0}$ , i.e.  $\mathbf{u}_1, \dots, \mathbf{u}_p$  are linearly dependent.

**Cor** If  $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  and  $\{\mathbf{u}_1, \dots, \mathbf{u}_m\}$  are bases for  $V$  then  $n = m$ .

The number of elements in a basis for  $V$  is called the **dimension** of  $V$ , written  $\dim V$ .

**Dimensions of the column and null spaces of a matrix.**

**Ex 8** Find  $\dim \text{Col } A$  and  $\dim \text{Nul } A$ , where  $A = \begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 4 & 7 & 8 \end{bmatrix}$ .

**Sol**  $\begin{bmatrix} 1 & 2 & 3 & 4 \\ 2 & 4 & 7 & 8 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 3 & 4 \\ 0 & 0 & 1 & 0 \end{bmatrix}$  so the pivot columns  $\left\{ \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ 7 \end{bmatrix} \right\}$  is a basis for  $\text{Col } A$  and  $\dim \text{Col } A = 2$ .

To find  $\text{Nul } A$  we solve  $A\mathbf{x} = \mathbf{0}$  :

$$\begin{bmatrix} 1 & 2 & 3 & 4 & 0 \\ 2 & 4 & 7 & 8 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 3 & 4 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 0 & 4 & 0 \\ 0 & 0 & 1 & 0 & 0 \end{bmatrix} \Rightarrow \begin{cases} x_1 = -2x_2 - 4x_4 \\ x_3 = 0 \end{cases} \text{ and}$$

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = x_2 \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -4 \\ 0 \\ 0 \\ 1 \end{bmatrix} \text{ so } \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -4 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\} \text{ is a basis for Nul } A \text{ and } \dim \text{Nul } A = 2.$$

$\dim \text{Col } A =$  number of pivot columns of  $A$ ,  $\dim \text{Nul } A =$  number of free variables of  $A$