

## Appendix: The Inverse and Implicit Function Theorems.

**Theorem 1.** Suppose that  $f : \mathbf{R}^n \rightarrow \mathbf{R}^n$  is  $C^1$ . Let  $f(x_0) = y_0$  and suppose that

$$(11.2.3) \quad Df(x_0) = \frac{\partial f}{\partial x}(x_0)$$

is invertible. Then for  $y$  close to  $y_0$  there is a unique  $x$  close to  $x_0$  such that

$$(11.2.4) \quad f(x) = y$$

Furthermore  $x = x(y)$  is a  $C^1$  function of  $y$  close to  $y_0$ .

Recall that a function of one variable  $y = f(x)$  is invertible if  $f'(x) \neq 0$ . For a function of several variables we have by Taylor's formula

$$(11.2.5) \quad y - y_0 = f(x) - f(x_0) = (Df)(x_0)(x - x_0) + O(|x - x_0|^2)$$

where the derivative  $Df(x_0) : \mathbf{R}^n \rightarrow \mathbf{R}^n$  is the linear map that best approximates the function close to a point and  $O(|x - x_0|^2)$  means terms that are bounded by a constant times  $|x - x_0|^2$  and hence small when  $|x - x_0|$  is small. Therefore, as a first approximation we must be able to invert the linear map, and we get that  $x - x_0 = (Df(x_0))^{-1}(y - y_0) + O(|y - y_0|^2)$ .

The proof of Theorem 1 uses the contraction mapping theorem. First by a translation replacing  $f(x)$  by  $f(x+x_0) - y_0$  we can reduce to the case when  $x_0 = y_0 = 0$ . Furthermore by multiplying both sides of (11.2.6) by the matrix  $(Df(x_0))^{-1}$  and making a change of variables replacing  $y$  by  $(Df(x_0))^{-1}y$  we may assume that the equation (11.2.4) takes the form

$$(11.2.6) \quad y = x + \phi(x)$$

where  $\phi(x)$  is small;  $\phi(0) = 0$  and  $D\phi(0) = 0$ . We seek a solution in the form

$$(11.2.7) \quad x = y + \psi(y)$$

Then for  $\phi(y)$  we obtain the equation  $\psi(y) = -\phi(y + \psi(y))$ . Consequently, the function  $\psi$  being sought is a fixed point of the mapping  $T$  defined by the formula

$$(11.2.8) \quad (T\psi)(y) = -\phi(y + \psi(y))$$

**Problem 1:** Show that  $T$  is a contraction in some norm for  $y$  sufficiently small and use this to prove Theorem 1. You have to use that since  $\phi$  is continuously differentiable and  $D\phi(0) = 0$  there is a neighborhood  $|y| < \delta$ , such that  $\|D\phi(y)\| < \varepsilon$ .

**Theorem 2.** Suppose that  $F : \mathbf{R}^m \times \mathbf{R}^n \rightarrow \mathbf{R}^n$  is  $C^1$ . Let  $F(x_0, y_0) = c_0$  and suppose that

$$(11.2.9) \quad \frac{\partial F}{\partial y}(x_0, y_0)$$

is invertible. Then for  $x$  close to  $x_0$  there is a unique  $y = g(x)$  close to  $y_0$  such that

$$(11.2.10) \quad F(x, g(x)) = c_0$$

Furthermore  $y = g(x)$  is a  $C^1$  function of  $x$  close to  $y_0$ .

**Problem 2:** Show that Theorem 2 follows from Theorem 1, by considering the mapping  $f(x, y) = (x, F(x, y))$ .

**Problem 3:** Suppose that  $F(x, y, z)$  is a function of 3 variables,  $F(x_0, y_0, z_0) = 0$ , and  $\text{grad} F(x_0, y_0, z_0) \neq 0$ . Use Theorem 2 to deduce that close to  $(x_0, y_0, z_0)$  the equation  $F(x, y, z) = c_0$  is a surface, i.e. show that one of the variables say  $z$  (if  $\partial F/\partial z \neq 0$  can be written as a graph  $z = g(x, y)$  so that  $F(x, y, g(x, y)) = 0$ .