

Lecture 9: Connections.

Let M be a differentiable manifold. Let $\mathcal{D}(M)$ be the (infinitely) differentiable functions on M and let $\mathcal{X}(M)$ denote the set of all differentiable vector fields.

An **affine connection** ∇ on M is a map $\mathcal{X}(M) \times \mathcal{X}(M) \rightarrow \mathcal{X}(M)$ denoted by $\nabla : (X, Y) \rightarrow \nabla_X Y$, satisfying:

$$(i) \nabla_{fX+gY} Z = f\nabla_X Z + g\nabla_Y Z$$

$$(ii) \nabla_X (Y + Z) = \nabla_X Y + \nabla_X Z.$$

$$(iii) \nabla_X (fY) = f\nabla_X Y + X(f)Y$$

for $f, g \in \mathcal{D}(M)$ and $X, Y, Z \in \mathcal{X}(M)$.

$\nabla_X Y$ should be thought of as the directional derivative of Y in the direction of X .

Note that the Lie derivative $\mathcal{L}_X Y = XY - YX$ does not satisfy (i).

Let E_1, \dots, E_n be a local frame for TM (for now we use a coordinate frame $E_i = \partial/\partial x^i$.) Expanding in the frame

$$(1) \quad \nabla_{E_i} E_j = \Gamma_{ij}^k E_k$$

where Γ_{ij}^k are called the Christoffel symbols of the connection with respect to the frame. If we expand $X = X^i E_i$, $Y = Y^j E_j$ we obtain

$$(2) \quad \nabla_X Y = \nabla_{X^i E_i} Y^j E_j = X^i \left((E_i Y^j) E_j + Y^j \nabla_{E_i} E_j \right) = \left(X^i Y^j \Gamma_{ij}^k \right) E_k$$

It follows that $\nabla_X Y$ at $p \in M$ depends only on $X(p)$ and on Y in the direction of X .

Proposition Let M be a differentiable manifold with an affine connection ∇ and let $c : I \rightarrow M$ be a curve. Then there is a unique operator DV/dt acting on vector fields V defined along c , such that

$$(a) D(V + W)/dt = dV/dt + dW/dt$$

$$(b) D(fV)/dt = (df/dt)V + fDV/dt$$

(c) If V is induced by a vector field Y ; $V(t) = Y(c(t))$, then $DV/dt = \nabla_{dc/dt} Y$. DV/dt is called the covariant derivative of V along c .

Proof Suppose that there is an operator satisfying (a), (b), (c) and expand in the frame $V = V^j E_j$ and $dc/dt = dx^i/dt E_i$. We obtain $DE_j/dt = \nabla_{dc/dt} E_j = \nabla_{dx^i/dt E_i} E_j = dx^i/dt E_{ij}^k E_k$. Hence

$$(3) \quad \frac{DV}{dt} = \frac{dV^j}{dt} E_j + V^j \frac{DE_j}{dt} = \left(\frac{dV^k}{dt} + \frac{dx^i}{dt} V^j \Gamma_{ij}^k \right) E_k$$

This shows uniqueness. To show existence we define DV/dt by this expression in any coordinate patch and it follows from the uniqueness already proven that its unique in the intersection of two coordinate patches.

A vector field V along a curve c is called **parallel** if $DV/dt = 0$ along c .

Proposition Let $V_0 \in T_{c(t_0)} M$. Then there is a unique parallel vector field V along c such that $V(t_0) = V_0$. V is called the **parallel transport** of V_0 along c .

Pf $DV/dt = 0$ in the coordinates (3) is a system of ODEs which has a unique solution.

Riemannian Connections.

A connection is said to be **compatible** with the metric $\langle \cdot, \cdot \rangle$ when for any smooth curve c and any pair of parallel vector fields P, Q along c , we have $\langle P, Q \rangle = \text{constant}$.

Proposition A connection is compatible with a metric iff along any curve c :

$$(4) \quad \frac{d}{dt} \langle V, W \rangle = \left\langle \frac{DV}{dt}, W \right\rangle + \left\langle V, \frac{DW}{dt} \right\rangle$$

Pf It is obvious that (3) implies that the connection is compatible with the metric. Choose an orthonormal basis $\{P_1(t_0), \dots, P_n(t_0)\}$ of $T_{c(t_0)}M$. By the previous proposition these can be parallel transported along c to $\{P_1(t), \dots, P_n(t)\}$ and by (4) they are still orthonormal. If we write $V = V^i P_i$, $W = W^j P_j$ we have $DV/dt = dV^i/dt P_i$, $DW/dt = dW^j/dt P_j$ and

$$\left\langle \frac{DV}{dt}, W \right\rangle + \left\langle V, \frac{DW}{dt} \right\rangle = \frac{dV^i}{dt} W^i + V^i \frac{dW^i}{dt} = \frac{d}{dt} \delta_{ij} V^i W^j = \frac{d}{dt} \langle V, W \rangle.$$

Corollary A connection is compatible with the metric if and only if

$$(5) \quad X \langle Y, Z \rangle = \langle \nabla_X Y, Z \rangle + \langle Y, \nabla_X Z \rangle$$

Pf If c is a curve such that $dc/dt = X$ then (5) is equivalent to (4). The proof in the other direction is to expand in the basis in the proof of the previous proposition.