

MA equation $\det(\nabla^2 u) = f$.

Monge - 1795
1st book on DG

Monge / Ampère

For linear $Lu = f$ - H^1 is the right space

For MA $C(\bar{\Omega})$ & convex is the weak solution admissible set.

(0) A little introduction:

$(\Omega_1, \underbrace{f(x) dx}_{d\mu_1}) \longrightarrow (\Omega_2, \underbrace{g(y) dy}_{d\mu_2})$
 If \exists map given by ∇u $y = \nabla u(x)$
 $\int \varphi g(y) dy = \int \varphi(\nabla u(x)) g(\nabla u(x)) \det(\nabla^2 u) dx$
 $= \int \varphi(\nabla u(x)) f(x) dx$

Then u satisfies

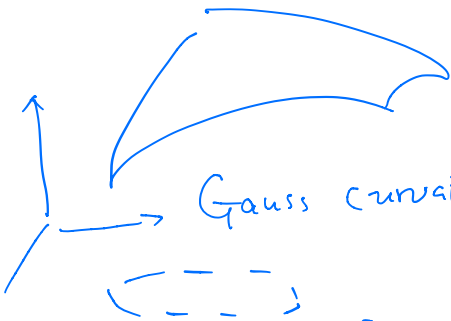
$$\det(\nabla^2 u) = \frac{f(x)}{g(\nabla u(x))}$$

Arises optimal transport problem!

$$x_{n+1} = \varphi(x)$$

Monge: $I(T)$
 $= \int c(x, T(x)) d\mu(x)$
 Minimise T . $T\#u = \nu$
 $\nu(B) = \mu(T^{-1}(B))$

$$\det(D\varphi)$$



Gauss curvature =

$$\frac{\det(D\varphi)}{(\sqrt{1 + |\nabla\varphi|^2})^{\frac{n+2}{2}}}$$

Some calculation using definition

$$\Rightarrow \det(D^2\varphi) = \underbrace{(\sqrt{1 + |\nabla\varphi|^2})^{\frac{n+2}{2}}}_{f(x)} \text{ is the}$$

prescribing Gauss curvature equ.

$$n \det(A) = a_{ij} A^{ij}$$

$$\det(\nabla^2 u) = B^{ij} \partial_{x_i x_j}^2 u$$

We shall introduce two solutions to MA equation
Aleksandrov

① A-solution, Alexandrov — our focus

② V-solution, Viscosity.

$$\frac{u(tx_1 + (1-t)x_2)}{\leq t u(x_1) + (1-t)u(x_2)}$$

Tool one:

Radon measures: Check Folland Ch 7.

- ① Outer regular on Borel
- ② Inner regular on open
- ③ $\mu(K) < +\infty$

— Borel measure + ①, ②, ③
 called Radon

↓ But

Theorem 7.8. X LCH, 2nd countable

$\Rightarrow \forall \mu, \mu(K) < +\infty \Rightarrow \mu$ is Radon

Key: Radon measure is dual to $C_0(X)$.

$$L^p \quad (L^p)^* = L^q \quad 1 < p < +\infty$$

(L^1 — Not the dual of L^∞ , $(L^1)^* = L^\infty$ — for μ σ -finite)

Good dual for L^∞ is Radon measures

$C_0(X)$ \cong Good compactness result!

If $\sup \mu(K) < +\infty, \forall K$ Compact

then $\mu_j \rightarrow \mu$

$$\Leftrightarrow \int f(x) d\mu_j(x) = \int f d\mu$$

$\forall f \in C_c(\mathbb{R}^n)$


① MA-measure for $u \in C(\mathbb{R}^n)$. u is convex.

$M(u)$ is called the MA measure

If $u \in C^2(\mathbb{R}^n)$ Ω convex $\nabla^2 u > 0$

$$M(u)(E) = \int_E \frac{\det(\nabla^2 u)}{J(\nabla u)} dx = |\nabla u(E)|$$

Goal: Theorem: $\Omega \subset \mathbb{R}^n$ strictly convex. open bounded

\forall Borel. measure $\nu(\Omega) < +\infty$. $\hookrightarrow \forall x, y \in \bar{\Omega}$
 $f|_{\Omega}$ continuous $\exists!$ $u \in C(\bar{\Omega})$ Convex
 $\begin{cases} M(u) = \nu \\ u|_{\partial\Omega} = g \end{cases}$ Interior $\bar{x}y \subset \Omega$
 \rightarrow Not strictly \rightarrow 

We need to enlarge the scope of the "solution" concept

by defining $M(u)$ for u continuous — Ampère is a student of Monge
 \uparrow MA-measure

"Uncertainty principle": Existence \times Uniqueness = Const
 difficulty level Perron

The trick is to find the "sweet spot" to balance it.

Tool two: Basics on Convex sets!
 Convex functions P. Lax
Linear Algebra

We build up this a little bit!

Def: Normal map 

$\partial u(x_0) : x_0 \rightarrow S$ — a set $\subset \mathbb{R}^n$

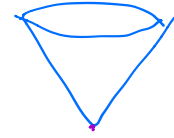
$\{p \mid \forall x \in \Omega, u(x) \geq u(x_0) + \langle p, x - x_0 \rangle\}$
 $l_p(x)$

$l_p(x)$ — called the support linear function.
 P — subdifferential.

Example:

$$u(x) = \frac{h}{R} |x - x_0|$$

$$\Omega = B_R(x_0)$$



$x_1 \neq x_0$

$$\partial u(x_1) = \frac{h}{R} \frac{x_1 - x_0}{|x_1 - x_0|}$$

$\nabla u(x_1)$
 $\partial u(x_1) \neq \emptyset$

$$\begin{aligned} &\in \partial B_{\frac{h}{R}}(0) \\ &|\partial u(B_R(x_0) \setminus \{x_0\})| \\ &= 0 \end{aligned}$$

Lemma. If u is C^1 at x_1 , $\nabla u(x_1) = \nabla u(x_1)$

Pf:

$$u(x) = u(x_1) + \langle \nabla u(x_1), x - x_1 \rangle + o(|x - x_1|)$$

$$\forall u(x_1) + \langle P, x - x_1 \rangle$$

\Rightarrow

$$\langle \nabla u(x_1) - P, x - x_1 \rangle + o(|x - x_1|) \geq 0$$

$$\forall x \in B_\delta(x_1)$$

This forces

$$\nabla u(x_1) = P.$$

otherwise

$$\nabla u(x_1) - P = w \neq 0 \quad \text{let}$$

$$x - x_1 = -\eta \frac{w}{|w|}$$

$$|x - x_1| = \eta$$

$$\Rightarrow \text{LHS} = \langle w, -\eta \frac{w}{|w|} \rangle \neq o(\eta)$$

$$= -|w|\eta + o(\eta) < 0 \quad \text{if } \eta \ll 1.$$

At x_0 . $\forall P \in \overline{B_{\frac{h}{R}}(0)}$

claim $\overline{B_{\frac{h}{R}}(0)} = \partial u(x_0)$

\Rightarrow

$$u(x) = \frac{h}{R} |x - x_0|$$

$$u(x_0) = 0 \quad \underline{\underline{L_P(x) = u(x_0) + \langle P, x - x_0 \rangle}}$$

$$\leq \underline{\underline{|P|}} |x - x_0| \leq \left(\frac{h}{R}\right) |x - x_0| = u(x).$$

$$\overline{B_{\frac{h}{R}}(0)} \subset \partial u(x_0).$$

$$\forall p \quad |p| > \boxed{\frac{h}{R}} \quad \underline{p = |p| w} \quad w \in \mathbb{S}^{n-1}(1)$$

$$\Rightarrow l_p(x) = u(x_0) + \langle p, x - x_0 \rangle$$

$$= u(x_0) + |p| \langle w, x - x_0 \rangle$$

$$\boxed{x - x_0 = (R - \varepsilon)w} \Rightarrow$$

$$l_p(x) = |p|(R - \varepsilon) \quad \text{if } \varepsilon \ll 1$$

$$\Rightarrow \frac{h}{R - \varepsilon} (R - \varepsilon) = h \quad u(x) = \frac{h}{R} |x - x_0|$$

$$\text{But } u(x) \leq h \quad (\Leftrightarrow \varepsilon)$$

$$\text{Hence } \partial u(x_0) = \overline{B_{\frac{h}{R}}(0)}$$

$$\Rightarrow M(u)(E) \doteq |\partial u(E)| \quad \forall E \subset \mathbb{R}^n$$

$$M(u) = \left| B_{\frac{h}{R}}(w) \right| \delta_{x_0} \quad \begin{matrix} \forall E \subset \mathbb{R}^n \\ B_{\frac{h}{R}}(x_0) \\ \cap \Omega \end{matrix}$$

- Monge Ampère measure

$$M(u)(E) := |\partial u(E)| \quad \left. \begin{matrix} \forall E \subset \mathbb{R}^n \\ \text{or } E \subset \Omega \end{matrix} \right\} \text{Borel.}$$

At this point it is simply a function ≥ 0

$$\textcircled{1} \quad M(u)(K) < +\infty$$

Lemma: $\forall K \subset \subset \Omega$, $\partial u(K)$ is compact!

pf: Assume $\{p_k\} \in \partial u(x_k)$ $x_k \in K$

Pick $c > 0$ $K_c \subset \subset \Omega$ $K_c = \{x \mid d(x, K) \leq c\}$

$$\boxed{u(x) \geq u(x_k) + \langle p_k, x - x_k \rangle}$$

$$\text{Let } x = x_k + c \frac{p_k}{|p_k|} \Rightarrow$$

$$\boxed{u(x) \geq u(x_k) + c|p_k|}$$

 \Rightarrow

$$\boxed{|p_k| \leq \frac{1}{c} \left[\max_K u - \min_{K_c} u \right]}$$

$$u(x) \geq u(x_0) + \langle p, x - x_0 \rangle$$

$$x = x_0 + c \frac{p}{|p|}$$

$$\Rightarrow \geq u(x_0) + c|p|$$

$$\Rightarrow |p| \leq \frac{1}{c} \left[\max_{\Omega} u - \min_{\Omega} u \right]$$

$$\left(c \leq d(K, \Omega) \right)$$

$$\forall p \in \partial u(K)$$

Hence $\{x_k\}, \{p_k\}$ are bounded sequence

\exists convergent subsequence $x_k \rightarrow x_0 \in K$
 $p_k \rightarrow p$

$$\rightarrow u(x) \geq u(x_0) + \langle p, x - x_0 \rangle \quad \forall x \in \Omega \Rightarrow p \in \partial u(x_0)$$

$$x_0 \in K \quad \square$$

Corollary: $M(u)(K) < +\infty$.

Next we show $M(u)$ is a measure.

Fact: (Ex 15).

$$\partial u(\Omega \setminus E) = \underbrace{(\partial u(\Omega) \setminus \partial u(E))}_{\partial u(x_0)} \cup \underbrace{(\partial u(\Omega \setminus E) \cap \partial u(E))}_{\partial u(x_0)} \quad (*)$$

Key difference: $\partial u: \Omega \rightarrow \mathcal{S} \subset \mathcal{P}(\mathbb{R}^n)$. Namely ∂u maps a pt into a set!

E.g.

$\partial u(x_0)$ is measurable

\Rightarrow

$$\begin{cases} u(x) \geq u(x_0) + \langle p, x - x_0 \rangle \\ u(x) \geq u(x_0) + \langle p', x - x_0 \rangle \end{cases} \quad \forall t \in [0,1]$$

$$\Rightarrow u(x) \geq u(x_0) + \langle tp + (1-t)p', x - x_0 \rangle \quad \forall t \in [0,1]$$

$\Rightarrow \partial u(x_0)$ is a convex subset!

[It is a m -measurable]

direct checking!

(*) can be proved!

The key to show $M(u)(E)$ is a measure is the Lemma below:

Lemma: $u \in C(\Omega)$

$$S := \{ p \mid \exists x \neq y, p \in \partial u(x) \cap \partial u(y) \}$$

Then $|S| = 0$.

Sard's theorem for continuous functions

pf: use two key ingredients.

① Rademacher's theorem: A Lipschitz function is a.e. differentiable.

② Legendre transform & convex functions are locally Lipschitz.

← Evans-Gariepy



Assuming the above. $\mathcal{G} := \{ S \subset \Omega \mid \partial u(S) \text{ is Lebesgue measurable} \}$

$$(\partial u)(\Omega \setminus E) = \left[\underbrace{\partial u(\Omega) \setminus \partial u(E)}_M \right] \cup \left[\underbrace{\partial u(\Omega \setminus E) \cap \partial u(E)}_{m(\square)=0} \right]$$

$$\Rightarrow |\partial u(\Omega \setminus E)| = |\partial u(\Omega) \setminus \partial u(E)| \Rightarrow \Omega \setminus E \in \mathcal{G} \text{ if } E \in \mathcal{G}$$

provided (1) Ω is $M(u)$ measurable

Since $\Omega = \bigcup_{n=1}^{\infty} K_n$ K_n is $M(u)$ measurable
 $\Rightarrow \partial u(\Omega) = \bigcup_{n=1}^{\infty} \partial u(K_n)$

Same holds for any U open $U \subset \Omega$.

Namely

\mathcal{G} contains all open subsets of Ω

(2) If $E \in \mathcal{G} \Rightarrow \Omega \setminus E \in \mathcal{G}$ [see above]

(3) Moreover, \mathcal{G} is a σ -algebra.

Hence $M(u)$ is a Radon measure. (A Borel measure with $\mu(K) < +\infty$)

by Lemma

$$\text{For (2)} \quad \partial u(\Omega \setminus E) = \underbrace{\left[\underbrace{\partial u(\Omega)}_M \setminus \underbrace{\partial u(E)}_{E \in \mathcal{G}} \right]}_{M \text{-Lebesgue measurable}} \cup \underbrace{\left[\underbrace{\partial u(\Omega \setminus E) \cap \partial u(E)}_{\in M} \right]}_{m(\partial u(\Omega \setminus E) \cap \partial u(E)) = 0}$$

$$\Rightarrow \Omega \setminus E \in \mathcal{G} \in \mathcal{G}$$

$$\text{For (3)} \quad \bigcup_{i=1}^{\infty} \partial u(E_i) \in M = \partial u \left(\bigcup_{i=1}^{\infty} E_i \right) \in \mathcal{G}$$

(4) $M(u)$ is a measure on \mathcal{G}

$$\text{Namely } M(u) \left(\bigcup_{i=1}^{\infty} E_i \right) = \sum_{i=1}^{\infty} M(u)(E_i)$$

(**)

if $E_i \in \mathcal{G}$ & $E_i \cap E_j = \emptyset \quad \forall i \neq j$

Let $H_i = \partial u(E_i)$

LHS = $|\bigcup_{i=1}^{\infty} H_i|$, RHS = $\sum_{i=1}^{\infty} |H_i|$

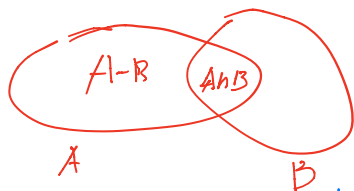
Clearly $|\bigcup_{i=1}^{\infty} \partial u(E_i)| = |\bigcup_{i=1}^{\infty} H_i|$
 $\bigcup_{i=1}^{\infty} H_i = H_1 \cup (H_2 \setminus H_1) \cup (H_3 \setminus (H_1 \cup H_2)) \dots$

$|\bigcup_{i=1}^{\infty} H_i| = |H_1| + |H_2 \setminus H_1| + |H_3 \setminus (H_1 \cup H_2)| + \dots$

By the Lebesgue measure property

Claim: $|H_n| = |H_n \setminus (H_1 \cup H_2 \cup \dots \cup H_{n-1})|$

$H_n = [H_n \setminus (H_1 \cup H_2 \dots \cup H_{n-1})] \cup [H_n \cap (H_1 \cup H_2 \dots \cup H_{n-1})]$



$|\cdot| = 0$ by the Lemma.

$E_i \cap E_j = \emptyset$

$p = \partial u(x) \quad x \in E_n$
 $\Rightarrow \partial u(y) \quad y \in \bigcup_{i=1}^n E_i$

Now we prove the Lemma:

(1) $u(y) \geq u(x) + \langle p_x, y - x \rangle$

$\Rightarrow \underline{u(y) - u(x) \geq -|p_x| |y - x|}$

& similarly $\underline{u(x) - u(y) \geq -|p_y| |x - y|}$

$\Rightarrow |u(x) - u(y)| \leq \max\{|p_x|, |p_y|\} |x - y|$
 if $x, y \in K$

u is Lipschitz

Here convexity is used since

$\partial u(x) \neq \emptyset$

$\Rightarrow u(y) \geq l_p(y), \forall y \in \Omega$

if u is convex

$epi(u) = \{(x, a) \mid a \geq u(x)\}$

$l_p(x) = u(x_0) + \langle p, x - x_0 \rangle \in epi(u)$



(2) Legendre transform:

$$u^*(p) := \sup_{x \in \Omega} \{ \underbrace{\langle p, x \rangle - u(x)}_{L_u(p) \text{ - linear in } p} \} \quad \forall p \in \mathbb{R}^n$$

Hence $-L_u(p)$ is convex in p .

$\Rightarrow u^*(p)$ is always convex.

By Radmacher's Theorem

$\Rightarrow u^*(p)$ is locally Lipschitz

$\Rightarrow \mathcal{N} := \{ p_0 \mid u^*(p) \text{ is not differentiable at } p_0 \}$ is of zero measure!

Lemma follows if we show that

$$S := \{ p \in \mathbb{R}^n \mid p \in \partial u(x) \cap \partial u(y), \quad x \neq y \in \Omega \}$$

$S \subset \mathcal{N}$

$$\forall p \in S \begin{cases} \exists x \in \Omega \text{ s.t. } u(z) \geq u(x) + \langle p, z-x \rangle \\ \exists y \in \Omega \text{ s.t. } u(z') \geq u(y) + \langle p, z'-y \rangle \end{cases} \quad \forall z, z' \in \Omega$$

for some $x \neq y$

$$0 \geq -u(z) + \langle p, z \rangle + u(x) - \langle p, x \rangle$$

$$\Rightarrow \langle p, x \rangle - u(x) \geq \langle p, z \rangle - u(z) \quad \forall z \in \Omega$$

$$\Rightarrow \underline{u^*(p) = \langle p, x \rangle - u(x)}$$

Similarly $\Rightarrow \underline{u^*(p) = \langle p, y \rangle - u(y)}$

IF $p \in \partial u(x)$
 $\Rightarrow u^*(p) = \langle p, x \rangle - u(x)$
 & $x \in \partial u^*(p)$

But

$$u^*(q) = \sup_{z \in \Omega} (\langle q, z \rangle - u(z))$$

$$\geq \langle q, x \rangle - u(x) = \underbrace{u^*(p)}_{p+q} + \langle x, q-p \rangle$$

Similarly $u^*(q) \geq u^*(p) + \langle \eta, q-p \rangle$

Namely $x, y \in \partial u^*(p)$

$\Rightarrow u^*$ can not be differentiable at p , since $x \neq y \in \partial u^*$

Def: A convex continuous function u is called a generalized solution (A-solution)

if $M(u)(E) = \nu(E)$ for $\nu \ll \text{Radon measure}$
 $\Leftrightarrow M(u) = \nu$

Reason: if $u \in C^2(\Omega)$ u is convex & Ω is convex is called Monge-Ampère

claim: $M(u)(E) = \int_E \det(\nabla^2 u) dx$
 Namely $|\partial u(E)| = \int_E \det(\nabla^2 u) dx$

$\forall E$
 $|\partial u(E)| = |\partial u(E|S_0) \cup \partial u(S_0)| = |\partial u(E|S_0)|$

$\partial u(x) = \nabla u(x)$
 & $\nabla u: \Omega \rightarrow \mathbb{R}^n$ C^1 -map

$S_0 := \{x \in \Omega, \det(\nabla^2 u) = 0 \}$
 $(\Leftrightarrow \nabla u \text{ is singular})$

$|\partial u(S_0)| = 0 \Rightarrow M(u)(E) = M(u)(E|S_0) = \int_{E|S_0} \det(\nabla^2 u) dx$

$\int_{E|S_0} \det(\nabla^2 u) dx = \int_E \det(\nabla^2 u) dx$
 ∇u is 1-1 on $\{\nabla^2 u > 0\}$
 $\det(\nabla^2 u) = 0$ on S_0

(II) Uniqueness

We study

① maximum principles

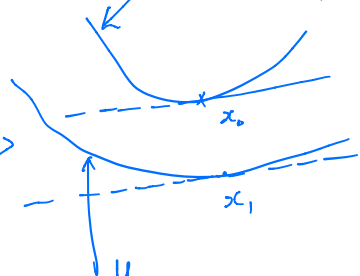
② Comparison principles \Rightarrow the uniqueness

(i) Alexandrov
 (ii) ABP, Alexandrov-Bakelman-Pucci

Comparison (I). If $u-v \equiv 0$ on $\partial\Omega$ $v \geq u$ in Ω Assumption is important!
 Then $\partial v(\Omega) \subset \partial u(\Omega)$
 $\Rightarrow M(v|\Omega) \leq M(u|\Omega)$

Pf. If $p \in \partial v(\Omega)$

$$\Rightarrow \exists x_0 \in \Omega \quad \frac{v(x) \geq v(x_0) + \langle p, x-x_0 \rangle}{\forall x \in \Omega} \quad \downarrow \quad \begin{matrix} v \\ p(x) \\ u \end{matrix}$$



Let $F(x) \doteq \underbrace{v(x_0) + \langle p, x-x_0 \rangle}_{\text{linear}} - \underbrace{u(x)}_u$

Try to maximize it!

$$F(x_0) = v(x_0) - u(x_0) \geq 0$$

$$F|_{\partial\Omega} = v(x_0) + \langle p, x-x_0 \rangle - u(x) \leq 0$$

what is needed is

$$\begin{aligned} -u(x)|_{\partial\Omega} &\leq -v(x)|_{\partial\Omega} \\ \Leftrightarrow u(x)|_{\partial\Omega} &\geq v(x)|_{\partial\Omega} \\ \text{But } u(x) &\leq v(x) \\ \text{in } \Omega & \\ \Rightarrow & \boxed{u(x) = v(x) \text{ on } \partial\Omega} \end{aligned}$$

Hence, either (1) $F(x) \leq 0$ \Rightarrow $\boxed{u(x) \geq v(x_0) + \langle p, x-x_0 \rangle \geq u(x_0) + \langle p, x-x_0 \rangle}$
 $(v(x_0) = u(x_0)) \Rightarrow p \in \partial u(x_0)$

or (2) $\max_{x \in \bar{\Omega}} F(x) > 0$. [This is the case if $v(x_0) > u(x_0)$]

Let $x_1 \in \Omega$ satisfy $F(x_1) = \max_{\bar{\Omega}} F(x)$

$$\Rightarrow \frac{F(x) \leq F(x_1)}{v(x_0) + \langle p, x-x_0 \rangle - u(x) \leq v(x_0) + \langle p, x_1-x_0 \rangle - u(x_1)}$$

$$\Rightarrow \frac{v(x_0) + \langle p, x-x_0 \rangle - u(x)}{(\Rightarrow)} \leq \frac{v(x_0) + \langle p, x_1-x_0 \rangle - u(x_1)}{u(x) \geq u(x_1) + \langle p, x-x_1 \rangle}$$

$$\Rightarrow p \in \partial u(x_1) \Rightarrow p \in \partial u(\Omega). \quad \square$$

Comparison principle (2). $u, v \in C(\bar{\Omega})$ v is convex.

$$|\partial u(E)| \leq |\partial v(E)| \quad \forall E \text{ Borel} \Leftrightarrow M(u) \leq M(v)$$

Then
$$\min_{x \in \bar{\Omega}} (u(x) - v(x)) = \min_{x \in \partial \Omega} (u(x) - v(x)) \quad (*)$$

Linear analogue $\Delta u \leq \Delta v \Leftrightarrow \Delta(u-v) \leq 0$ $u-v$ - Sup-harmonic
 then (*) holds

This proves the uniqueness in the main theorem!
 We worry about the existence later!

Pf. w.l.g. assume $\min_{x \in \partial \Omega} (u(x) - v(x)) = 0$

If $\min_{x \in \bar{\Omega}} (u(x) - v(x)) = -a < 0$ for some $a > 0$
 the interior minimum

let x_0 be the point \checkmark is attained

$$u(x_0) - v(x_0) = -a$$

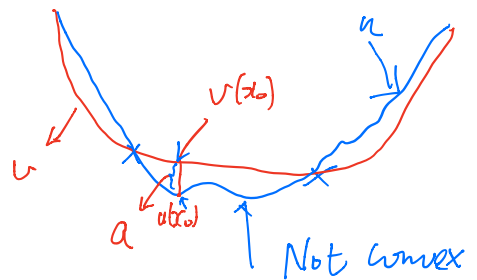
$$u(x_0) = v(x_0) - a$$

We construct

$$w(x) := v(x) + \delta |x - x_0|^2 - \frac{a}{2}$$

$$w(x_0) = v(x_0) - \frac{a}{2} > u(x_0)$$

Hence
$$E := \left\{ \begin{array}{l} w(x) > u(x) \\ \downarrow \\ \text{open} \end{array} \right\} \neq \emptyset$$



δ to be chosen

However: $w|_{\partial\Omega} \leq v(x) + \delta \text{Diam}^2(\bar{\Omega}) - \frac{a}{2}$

$U(x) \geq v(x)$ on $\partial\Omega \rightarrow \leq \underbrace{u(x)|_{\partial\Omega} + \delta D^2 - \frac{a}{2}}_{\leq u(x)|_{\partial\Omega}} \leq u(x) - \frac{a}{4}$

if $\delta D^2 - \frac{a}{2} < -\frac{a}{4}$
 $\delta D^2 < \frac{a}{4}$ — We pick this δ .

$\Rightarrow \partial E \cap \partial\Omega = \emptyset \Rightarrow \bar{E} \subset \Omega$

Now we apply the Comparison (I) to u & w on E

CP(I)

$\Rightarrow |\partial w(E)| \leq |\partial u(E)|$

But this is a contradiction since

$|\partial w(E)| \geq |\partial v(E)| + \frac{(2\delta)^{\frac{1}{n}} |E|}{\dots}$ (2)

Here v is convex is needed! $M(\phi_2)(E) \geq |\partial\phi_1(E)| + |\partial\phi_2(E)|$

$w = v + \delta|x-x_0|^2 - \frac{a}{2}$

[Convexity of $\det^{\frac{1}{n}}$ — Brunn-Minkowski inequality]

Baby version: $\det^{\frac{1}{n}}(A+B) \geq \det^{\frac{1}{n}}(A) + \det^{\frac{1}{n}}(B)$

\downarrow
 $\det(A+B) \geq \det(A) + \det(B)$ A, B symmetric positive definite

Details can be seen on p. 18 of [Gu].