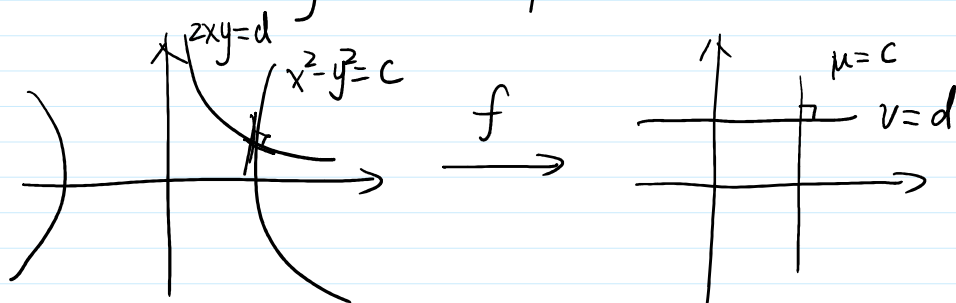


### 3. Analytic functions as mappings. Möbius transformations

We start with some examples:

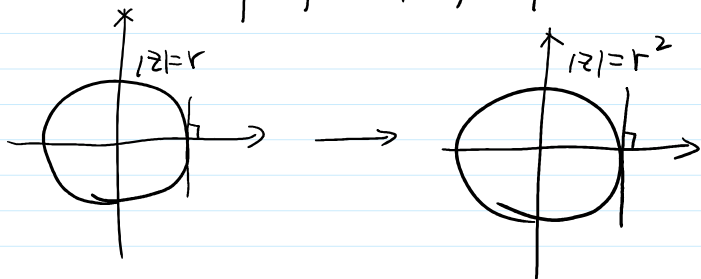
Example: Let  $f(z) = z^2$ . If we write  $z = x + iy$  and  $f(z) = u + iv$ , then the hyperbolas  $x^2 - y^2 = c$  and  $2xy = d$  are mapped by  $f$  into the straight lines  $u = c$ ,  $v = d$ . Note



Example: Let  $f(z) = z^2$ . Then

$f(z)$  maps  $x$ -axis to  $x$ -axis

maps  $\{z : |z| = r\}$  to  $\{z : |z| = r^2\}$ .



Defn: A path is a region  $G \subset \mathbb{C}$  is continuous function  $\gamma : [a, b] \rightarrow G$  for some interval  $[a, b]$  in  $\mathbb{R}$ . If  $\gamma'(t)$  exists for each  $t \in [a, b]$  and  $\gamma' : [a, b] \rightarrow \mathbb{C}$  is continuous then  $\gamma$  is a smooth path. Also  $\gamma$  is piecewise smooth if there is a partition of  $[a, b]$ ,  $a = t_0 < t_1 < \dots < t_n = b$  s.t.  $\gamma$  is smooth on each

piecewise smooth if there is a partition of  $[a, b]$ ,  
 $a = t_0 < t_1 < \dots < t_n = b$  s.t.  $\gamma$  is smooth on each  
subinterval  $[t_{j-1}, t_j]$ ,  $1 \leq j \leq n$ .

Remark: To say that a function  $\gamma: [a, b] \rightarrow \mathbb{C}$  has a derivative  $\gamma'(t)$  for each pt  $t \in [a, b]$  means that

$$\lim_{h \rightarrow 0} \frac{\gamma(t+h) - \gamma(t)}{h} = \gamma'(t).$$

exists for  $a < t < b$  and that the one-side limit exists for  $t = a$  and  $t = b$ , respectively. This is equivalent to saying that  $\operatorname{Re} \gamma$  and  $\operatorname{Im} \gamma$  have a derivative.

Suppose  $\gamma: [a, b] \rightarrow \mathbb{G}$  is a smooth path and that for some  $t_0$  in  $(a, b)$ ,  $\gamma'(t_0) \neq 0$ . Then  $\gamma$  has a tangent line at the pt  $z_0 = \gamma(t_0)$ . This line goes through  $z_0$  in the direction of  $\gamma'(t_0)$ .  
Let  $\gamma_1$  and  $\gamma_2$  be two smooth paths with  $\gamma_1(t_1) = \gamma_2(t_2) = z_0$  and  $\gamma_1'(t_1), \gamma_2'(t_2) \neq 0$ .

Defn: Define the angle between the paths  $\gamma_1$  and  $\gamma_2$  at  $z_0$   
to be  $\arg \gamma_2'(z_0) - \arg \gamma_1'(z_0)$

Suppose  $\gamma$  is a smooth path in  $\mathbb{G}$  and  $f: \mathbb{G} \rightarrow \mathbb{C}$  is analytic.

Then  $\sigma = f \circ \gamma$  is also a smooth path and

$$\sigma'(t) = f'(\gamma(t)) \cdot \gamma'(t)$$

Let  $z_0 = \gamma(t_0)$ , and suppose that  $\gamma'(t_0) \neq 0$  and  $f'(z_0) \neq 0$ ,

then  $\sigma'(t_0) \neq 0$  and

$$\arg \sigma'(t_0) - \arg \gamma'(t_0) = \arg f'(z_0)$$

$$\arg \sigma'(t_0) - \arg \gamma'(t_0) = \arg f'(z_0)$$

Now let  $\gamma_1$  and  $\gamma_2$  be smooth paths with  $\gamma_1(t_1) = \gamma_2(t_2) = z_0$  and  $\gamma_1'(t_1) \neq 0 \neq \gamma_2'(t_2)$ ; let  $\sigma_1 = f \circ \gamma_1$ ,  $\sigma_2 = f \circ \gamma_2$ . Then

$$\arg \sigma_2'(t_2) - \arg \sigma_1'(t_1) = \arg \sigma_2'(t_2) - \arg \sigma_1'(t_1)$$

In this case, we say  $f$  preserves the angle at  $z_0$  between the curves. The above argument yields

**Thm 3.4:** If  $f: G \rightarrow \mathbb{C}$  is analytic then  $f$  preserves angles at each  $z_0$  of  $G$  where  $f'(z_0) \neq 0$ .

A function  $f: G \rightarrow \mathbb{C}$  which has the angle preserving property and also has  $\lim_{z \rightarrow a} \frac{|f(z) - f(a)|}{|z - a|}$

existing is called a conformal map.

**Corollary:** If  $f$  is analytic in  $G$  and  $f'(z) \neq 0$  for  $\forall z \in G$ , then  $f$  is conformal.

The converse of this statement is also true.

**Defn:** A mapping of the form  $S(z) = \frac{az+b}{cz+d}$  is called a linear fractional transformation. If  $a, b, c$  and  $d$  also satisfy  $ad - bc \neq 0$  then  $S(z)$  is called a Möbius transformation.

**Remark:** The set of Möbius maps form a group under composition. Indeed, if  $S = \frac{az+b}{cz+d}$  is a Möbius transformation, then  $S^{-1} = \frac{dz-b}{-c z - a}$  satisfies

$w \mapsto \dots$  inverse, if  $S = \frac{cz+d}{-cz+a}$   
 transformation, then  $S^{-1} = \frac{dz-b}{-cz+a}$  satisfies  
 $S(S^{-1}(z)) = z$ ,  $S^{-1}(S(z)) = z$ , i.e.  $S^{-1}$  is the  
 inverse mapping of  $S$ . If  $S, T$  are both Möbius  
 transformations, then  $S \circ T$  is also. (Exercise)

Unless otherwise stated, the only linear fractional  
 transformations we will consider are Möbius transformations

We will also consider  $S$  as defined on  $\mathbb{C}_\infty$  with  $S(\infty) = \frac{a}{c}$   
 and  $S(-\frac{d}{c}) = \infty$  if  $c \neq 0$ ; Note we have  $S(\infty) = \infty$  when  
 $c = 0$ .

Remark:  $S: \mathbb{C}_\infty \rightarrow \mathbb{C}_\infty$  is one-to-one and onto.

Defn: We call

$S_1(z) = z + a$  a translation

$S_2(z) = az, a > 0$  a dilation

$S_3(z) = e^{i\theta} z$  a rotation

$S_4(z) = \frac{1}{z}$  the inversion

Proposition 3.6: Every Möbius transformation is the composition  
 of translations, dilations and the inversion

pf: ① If  $c = 0$ , then  $S(z) = \frac{a}{d}z + \frac{b}{d}$ . Hence

$$S = S_1 \circ S_2$$

where  $S_1 = \frac{a}{d}z$ ,  $S_2 = z + \frac{b}{d}$

② If  $c \neq 0$ , we put  $S_1(z) = z + \frac{d}{c}$ ,  $S_2(z) = \frac{1}{z}$   
 $(bc - ad)$ ,  $\dots$   $S_3(z) = z + \frac{a}{c}$  Then

(2) If  $c \neq 0$ , we put  $S_1(z) = z + \frac{c}{c}$ ,  $S_2(z) = z$   
 $S_3(z) = \frac{(bc-ad)}{c^2} z$ ,  $S_4(z) = z + \frac{a}{c}$  Then

$$S = S_4 \circ S_3 \circ S_2 \circ S_1.$$

Remark: A Möbius transformation can have at most two fixed pts unless  $S(z) = z$ . Indeed,

$$\frac{az+b}{cz+d} = z \iff$$

$$cz^2 + (d-a)z - b = 0$$

It has at most two solutions if  $c \neq 0$  or  $d-a \neq 0$ .  
 or  $b \neq 0$

Now let  $S$  be a Möbius transformation and let  $a, b, c$  be distinct pts in  $C_{\infty}$  with  $\alpha = S(a)$ ,  $\beta = S(b)$ ,  $\gamma = S(c)$ .

Suppose that  $T$  is another map with this property. Then

$T^{-1} \circ S$  has  $a, b$  and  $c$  as fixed pts and therefore,

$T^{-1} \circ S = I$ , where  $I$  is the identity. That is,  $S = T$ .

Hence, a Möbius map is uniquely determined by its action on any three given pts in  $C_{\infty}$ .

Let  $z_2, z_3, z_4$  be pts in  $C_{\infty}$ . Define  $S: C_{\infty} \rightarrow C_{\infty}$  by

$$S(z) = \left( \frac{z-z_3}{z-z_4} \right) / \left( \frac{z_2-z_3}{z_2-z_4} \right) \text{ if } z_2, z_3, z_4 \in \mathbb{C}$$

$$S(z) = \frac{z-z_3}{z-z_4} \text{ if } z_2 = \infty$$

$$S(z) = \frac{z_2-z_4}{z-z_4} \text{ if } z_3 = \infty$$

$$S(z) = \frac{z-z_3}{z_2-z_3} \text{ if } z_4 = \infty$$

$$S(z) = \frac{z - z_3}{z_2 - z_3} \quad \text{if } z_4 = \infty$$

In any case  $S(z_2) = 1$ ,  $S(z_3) = 0$ ,  $S(z_4) = \infty$  and  $S$  is only transformation having this property.

Defn 3.7: If  $z_1 \in \mathbb{C}_\infty$  then  $(z_1, z_2, z_3, z_4)$ , called the cross ratio of  $z_1, z_2, z_3$  and  $z_4$ , is the image of  $z_1$  under the unique Möbius transformation  $S$  with  $S(z_2) = 1$ ,  $S(z_3) = 0$ ,  $S(z_4) = \infty$ .

Example:  $(z_1, z_2, z_3, z_4) = 1$  and  $(z, 1, 0, \infty) = z$ . Also, if  $M$  is any Möbius map and  $w_2, w_3, w_4$  are the pts s.t.  $Mw_2 = 1$ ,  $Mw_3 = 0$ ,  $Mw_4 = \infty$  then  $Mz = (z, w_2, w_3, w_4)$ .

Proposition 3.8: If  $z_2, z_3, z_4$  are distinct pts and  $T$  is any Möbius transformation then

$$(z_1, z_2, z_3, z_4) = (Tz_1, Tz_2, Tz_3, Tz_4)$$

for any pt  $z_1$ .

Prf: Let  $S(z) = (z, z_2, z_3, z_4)$ , then  $S$  is a Möbius map.

If  $M = ST^{-1}$  then  $M(Tz_2) = 1$ ,  $M(Tz_3) = 0$ ,  $M(Tz_4) = \infty$ , hence,

$ST^{-1}z = (z, Tz_2, Tz_3, Tz_4)$  for all  $z$  in  $\mathbb{C}_\infty$ . In particular, if  $z = Tz_1$ , the desired result follows.

Proposition 3.9: If  $z_2, z_3, z_4$  are distinct pts in  $\mathbb{C}_\infty$  and  $w_2, w_3, w_4$  are also distinct pts of  $\mathbb{C}_\infty$ , then

Proposition 2.1: If  $z_2, z_3, z_4$  are distinct pts of  $\mathbb{C}_\infty$ , then

$w_2, w_3, w_4$  are also distinct pts of  $\mathbb{C}_\infty$ , then there is one and only one Möbius transformation  $S$  s.t.  $Sz_2 = w_2, Sz_3 = w_3, Sz_4 = w_4$ .

Pf: Let  $Tz = (z_1, z_2, z_3, z_4)$ ,  $Mz = (z, w_2, w_3, w_4)$  and  $S = M^{-1}T$ . Clearly  $S$  has the desired property.

If  $R$  is another Möbius map with  $Rz_j = w_j$  for all  $2 \leq j \leq 4$ . Then  $R^{-1} \circ S$  has three fixed pts  $z_2, z_3$ , and  $z_4$ . Hence  $R^{-1} \circ S = I$  or  $S = R$ .

Remark: (1) A circle in  $\mathbb{C}_\infty$  means either a circle in  $\mathbb{C}$  or a line in  $\mathbb{C}$

(2) Hence, three pts in  $\mathbb{C}_\infty$  determines a circle in  $\mathbb{C}_\infty$ .

Proposition 3.10: Let  $z_1, z_2, z_3, z_4$  be four distinct pts in  $\mathbb{C}_\infty$ .

Then  $(z_1, z_2, z_3, z_4) \in \mathbb{R}$  iff all four pts lie on a circle.

Pf: We first prove the following Lemma:

Lemma: Let  $Sz = \frac{az+b}{cz+d}$ . Then

$S^{-1}(\mathbb{R}_\infty)$  is a circle.

Pf: If  $z = x \in \mathbb{R}$  and  $w = S^{-1}(x) \neq \infty$ , then  $x = Sw$  implies  $S(w) = \overline{S(w)}$ . That is,

$x = Sw$  implies  $S(w) = \overline{S(w)}$ . That is,

$$\frac{aw+b}{cw+d} = \frac{\bar{a}\bar{w}+\bar{b}}{\bar{c}\bar{w}+\bar{d}}$$

Cross multiplying  $\Rightarrow$

$$(a\bar{c}-\bar{a}c)|w|^2 + (a\bar{d}-\bar{a}d)w + (b\bar{c}-\bar{b}c)\bar{w} + (b\bar{d}-\bar{b}d) = 0 \quad (1)$$

If  $a\bar{c}-\bar{a}c = 0$ , putting  $\alpha = 2(a\bar{d}-\bar{a}d)$ ,  $\beta = i(b\bar{d}-\bar{b}d) \in \mathbb{R}$ .

and multiplying (1) by  $i$  gives

$$0 = \operatorname{Im}(\alpha w) - \beta = \operatorname{Im}(\alpha w - \beta) \quad (2)$$

This is a line in  $\mathbb{C}$  and thus a circle in  $\mathbb{C}_\infty$

If  $a\bar{c}-\bar{a}c \neq 0$ , then (1)  $\Rightarrow$

$$|w|^2 + \bar{\gamma}w + \gamma\bar{w} - \delta = 0$$

for some  $\gamma \in \mathbb{C}$ ,  $\delta \in \mathbb{R}$ . Hence

$$|w + \gamma| = (|\gamma|^2 + \delta)^{\frac{1}{2}} \quad (3)$$

This is a circle in  $\mathbb{C}_\infty$  as well.

Then we have

Lemma: Let  $S(z) = (z, z_2, z_3, z_4)$ . Then

$S^{-1}(\mathbb{R}_\infty) = \Gamma$ , where  $\Gamma$  is the circle determined by  $z_2, z_3, z_4$ .

Moreover,  $S(\Gamma) = \mathbb{R}_\infty$ .

Pf: By the previous Lemma,  $S^{-1}(\mathbb{R}_\infty)$  is a circle  $\Gamma$  in  $\mathbb{C}_\infty$

On the other hand,  $S(z_2) = 1$ ,  $S(z_3) = 0$ ,  $S(z_4) = \infty$ .

Thus  $z_2, z_3, z_4 \in \Gamma$ . Thus  $\Gamma$  is the circle determined by  $z_2, z_3, z_4$ . On the other hand, as  $S: \mathbb{C}_\infty \rightarrow \mathbb{C}_\infty$  is one-to-one and onto, thus  $S(\Gamma) = \mathbb{R}_\infty$ .



Thm 3.14: A Möbius transformation takes circles in  $\mathbb{C}_\infty$  onto circles in  $\mathbb{C}_\infty$

Pf: Let  $\Gamma$  be any circle in  $\mathbb{C}_\infty$  and let  $S$  be any Möbius transformation. Let  $z_2, z_3, z_4 \in \Gamma$  and put  $w_j = Sz_j$  for  $j=2,3,4$ . Then  $w_2, w_3, w_4$  determine a circle  $\Gamma'$ . We claim that  $S(\Gamma) = \Gamma'$ . In fact, for  $\forall z \in \mathbb{C}_\infty$ , by proposition 3.8,

$$(z, z_2, z_3, z_4) = (Sz, w_2, w_3, w_4) \quad (4)$$

By proposition 3.10, if  $z$  is on  $\Gamma$  then both sides of (4) are real. But this says that  $Sz \in \Gamma'$ .

Let  $T(z) = (z, z_2, z_3, z_4)$  and  $M(w) = (w, w_2, w_3, w_4)$

Then  $Sz = M^{-1} \circ T(z)$ . Hence  $S(\Gamma) = M^{-1}(\mathbb{R}_{\infty})$  is a circle in  $\mathbb{C}_\infty$ ; this circle must be  $\Gamma'$ . Thus  $S(\Gamma) = \Gamma'$ .

Remark: Let  $\Gamma$  and  $\Gamma'$  be two circles in  $\mathbb{C}_\infty$ . Then  $\exists$  a Möbius map  $T$  s.t.  $T(\Gamma) = \Gamma'$ . Indeed, let  $z_2, z_3, z_4 \in \Gamma$ ;  $w_2, w_3, w_4 \in \Gamma'$ . Put  $Rz = (z, z_2, z_3, z_4)$ .  $Sz = (z, w_2, w_3, w_4)$ . Then  $T = S^{-1} \circ R$  maps  $\Gamma$  onto  $\Gamma'$ . This is because  $Tz_j = w_j$ ,  $2 \leq j \leq 4$ . Then it follows from Thm 3.14  $T(\Gamma) = \Gamma'$ . We summarize this as,

proposition 3.16: For any given circles  $\Gamma$  and  $\Gamma'$  in  $\mathbb{C}_\infty$ , there is a Möbius transformation  $T$  s.t.  $T(\Gamma) = \Gamma'$ .

$\Gamma$   $\Gamma'$

there is a Möbius transformation  $T$  s.t.  $T(\Gamma) = \Gamma'$ .

Furthermore we can specify that  $T$  take any three pts on  $\Gamma$  onto any three pts of  $\Gamma'$ . If we do specify  $Tz_j$  for  $j=2,3,4$  (distinct  $z_j$  in  $\Gamma$ ), then  $T$  is unique.

Now we know a Möbius map takes circles to circles, the next question is: what happens to the inside and the outside of the circles? To understand this, we introduce:

Defn: Let  $\Gamma$  be a circle in  $\mathbb{C}_\infty$ . Then the points  $z, z^*$  in  $\mathbb{C}_\infty$  are said to be symmetric with respect to  $\Gamma$  if

$$(z^*, z_2, z_3, z_4) = \overline{(z, z_2, z_3, z_4)} \quad (4)$$

for some distinct pts  $z_2, z_3, z_4 \in \Gamma$ .

Proposition: Let  $\Gamma$  be a circle in  $\mathbb{C}_\infty$ . and  $z, z^* \in \Gamma$ .

Then

$$(z^*, z_2, z_3, z_4) = \overline{(z, z_2, z_3, z_4)} \text{ for some}$$

distinct  $z_2, z_3, z_4 \in \Gamma$ .  $\iff$

$$(z^*, w_2, w_3, w_4) = \overline{(z, w_2, w_3, w_4)} \text{ for}$$

every choice of distinct pts  $w_2, w_3, w_4 \in \Gamma$ .

every choice of distinct pts  $w_2, w_3, w_4 \in \Gamma$ .

Pf: Exercise. (Hint: First consider the case when  $\Gamma = \mathbb{R} \cup \infty$ ).

Remark: By proposition 3.10,  $z$  is symmetric to itself with respect to  $\Gamma$  iff  $z \in \Gamma$ .

Let's investigate what it means for  $z$  and  $z^*$  to be symmetric. We have two cases:

① If  $\Gamma$  is a straight line, by the proposition above, we can choose  $z_2, z_3, z_4$  as any distinct pts on  $\Gamma$ .

We now fix  $z_4 = \infty$ . Then (4) becomes

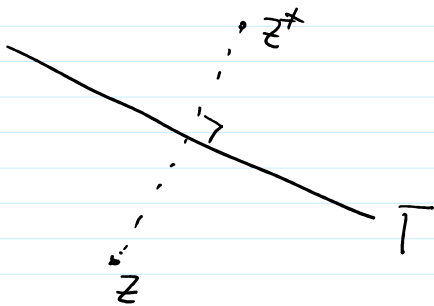
$$\frac{z^* - z_3}{z_2 - z_3} = \frac{\bar{z} - \bar{z}_3}{\bar{z}_2 - \bar{z}_3}$$

$$\Rightarrow |z^* - z_3| = |z - z_3|$$

Since  $z_3$  can be arbitrary pt on  $\Gamma$ , we have  $z$  and  $z^*$  are equidistant from each pt on  $\Gamma$ . Also

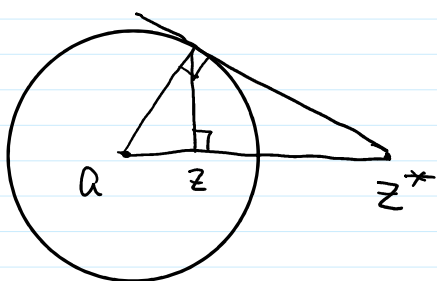
$$\begin{aligned} \operatorname{Im} \frac{z^* - z_3}{z_2 - z_3} &= \operatorname{Im} \frac{\bar{z} - \bar{z}_3}{\bar{z}_2 - \bar{z}_3} \\ &= -\operatorname{Im} \frac{z - z_3}{z_2 - z_3} \end{aligned}$$

Thus  $z$  and  $z^*$  lies in two sides of  $\Gamma$  (unless  $z \in \Gamma$ )



② If  $\Gamma = \{z: |z-a|=R\}$  is a circle, let  $z_2, z_3, z_4$ .

We have in this case:



$$\begin{aligned} (z^*, z_2, z_3, z_4) &= \overline{(z, z_2, z_3, z_4)} \\ &= \overline{(z-a, z_2-a, z_3-a, z_4-a)} \\ &= (\overline{z-a}, \overline{z_2-a}, \overline{z_3-a}, \overline{z_4-a}) \\ &= \left(\overline{z-a}, \frac{R^2}{z_2-a}, \frac{R^2}{z_3-a}, \frac{R^2}{z_4-a}\right) \\ &= \left(\frac{R^2}{\overline{z-a}}, z_2-a, z_3-a, z_4-a\right) \\ &= \left(\frac{R^2}{\overline{z-a}} + a, z_2, z_3, z_4\right) \end{aligned}$$

Hence  $z^* = a + \frac{R^2}{\overline{z-a}}$  or  $(z^*-a)(\overline{z-a}) = R^2 \Rightarrow$

$$\frac{z^*-a}{z-a} = \frac{R^2}{|z-a|^2} > 0.$$

so that  $z^*$  lies on the ray  $\{a+t(z-a) = 0 < t < \infty\}$  from  $a$  through  $z$ .

Symmetry principle 3.19: If a Möbius transformation  $T$  takes a circle  $\Gamma_1$  onto the circle  $\Gamma_2$  then any pair of pts symmetric with respect to  $\Gamma_1$  are mapped by  $T$  onto a pair of pts symmetric with respect to  $\Gamma_2$ .

of pts symmetric with respect to  $\Gamma_2$ .

Pf: Let  $z_2, z_3, z_4 \in \Gamma_1$ ; it follows that if  $z$  and  $z^*$  are symmetric with respect to  $\Gamma_1$ , then by using proposition 3.8

$$\begin{aligned} (Tz^*, Tz_2, Tz_3, Tz_4) &= (z^*, z_2, z_3, z_4) \\ &= \overline{(z, z_2, z_3, z_4)} \\ &= \overline{(Tz, Tz_2, Tz_3, Tz_4)} \end{aligned}$$

Hence  $Tz^*$  and  $Tz$  are symmetric with respect to  $\Gamma_2$ .