

MATH 170B: PROJECT 2
 “NONLINEAR SYSTEMS & POLYNOMIAL INTERPOLATION”
 WINTER 2013

Nonlinear Systems

1. **SOURCE CODE:**

Write a MATLAB function for **Newton’s method for systems**. Write this function so that it works for a 2×2 system (in other words: you don’t have to write to solve a general $m \times m$ system). Make use of the 2×2 inversion formula to invert the necessary linear system in each Newton iteration. Your function should be written so that it can be called in MATLAB by typing:

- `[x, NumIters] = NewtSys2x2(@F,@J,x0,TOL,MaxIters)`

Here $F(x_1, x_2)$ is the vector-valued function whose root we are trying to approximate and $J(x_1, x_2)$ is its Jacobian matrix. Include your source code with the rest of your assignment.

2. **APPLICATION PROBLEM:**

Let $i = \sqrt{-1}$. Find all five roots of the complex polynomial

$$f(z) = (1 + i)z^5 - 2z^3 + iz^2 - 1$$

to within a tolerance of 10^{-7} using your **Newtons’ method for systems** code. For each root report your initial guess, how many iterations were required for a 10^{-7} error, and your approximate root.

HINT: The roots of $f(z)$ are the points z in the complex plane where $f(z) = 0$. We can write $z = x + iy$ where x is the real part and y is the imaginary part. In this form, both x and y are strictly real numbers.

We can also separate $f(z)$ into a real part and an imaginary part:

$$\begin{aligned} f(z) &= (1 + i)(x + iy)^5 - 2(x + iy)^3 + i(x + iy)^2 - 1 \\ &\cdot \\ &\cdot \\ \implies f(z) &= A(x, y) + iB(x, y). \end{aligned}$$

where

$$A(x, y) = x^5 - 5x^4y - 10x^3y^2 + 10x^2y^3 + 5xy^4 - y^5 - 2x^3 + 6xy^2 - 2xy - 1$$

$$B(x, y) = x^5 + 5x^4y - 10x^3y^2 - 10x^2y^3 + 5xy^4 + y^5 - 6x^2y + 2y^3 + x^2 - y^2.$$

Again, x and y are strictly real numbers and $A(x, y)$ and $B(x, y)$ are strictly real functions.

The roots of $f(z)$ are all the points z such that $f(z) = 0$. Using the above result this is equivalent to saying that the roots of $f(z)$ are all the points (x, y) such that $A(x, y) = B(x, y) = 0$.

Polynomial Interpolation

3. Consider the function

$$f(x) = \sin\left(\frac{\pi}{2}x\right) + \frac{x}{2}.$$

- (a) We would like to construct a polynomial $P(x)$ that interpolates $f(x)$ at the points $x_0 = 0$, $x_1 = 2$, and $x_2 = 3$. Compute all the necessary Lagrange polynomials and use these to construct the interpolating polynomial $P(x)$.
- (b) Compute the error term $R(x)$.
- (c) **Interpolation:** Compute the maximum bound on $R(x)$ if we approximate $f(1)$ by $P(1)$.
- (d) **Extrapolation:** Compute the maximum bound on $R(x)$ if we approximate $f(4)$ by $P(4)$.

4. **SOURCE CODE:**

Let x_0, x_1, \dots, x_n be distinct points with corresponding data values f_0, f_1, \dots, f_n . Let $P(x)$ be the unique polynomial of degree n which interpolates the data (i.e., $P(x_i) = f_i$ for each $i = 0, \dots, n$). Write the following MATLAB routines:

- (a) **F = DivDiff(x,f,n)** – a **function** to compute the divided differences.
- (b) **P = Horners(x,F,xbar)** – a **function** which uses the divided differences to evaluate $P(x)$ at the point $xbar$ using Horner's method.

5. Consider the function

$$f(x) = \frac{1}{1 + 25x^2}.$$

(a) Let x_i be 11 equally spaced points on $[-1, 1]$:

$$x_i = -1 + i/5, \quad \text{where } i = 0, 1, 2, \dots, 10.$$

- i. Use your code from the previous problem to construct the divided differences with these x_i 's.
- ii. Use your Horner's method code to evaluate the interpolating polynomial $P(x)$ at all the points z_k :

```
z = linspace(-1,1,500);
for k=1:500
    P(k) = Horners(x,F,z(k));
end
```

- iii. Make a single MATLAB plot that contains: (z, P) , $(z, f(z))$, and the data points $(x_i, f(x_i))$ for $i = 0, 1, 2, \dots, 10$. Make the $P(z)$ plot a solid line ('b-'), the $f(z)$ a dashed line ('r--'), and the data points stars ('k*').

(b) Now, let x_i be 11 *unequally* spaced points on $[-1, 1]$:

$$x_i = \cos \left[\frac{\pi(i + 0.5)}{11} \right], \quad \text{where } i = 0, 1, 2, \dots, 10.$$

Repeat steps (i), (ii), and (iii) for these unequally spaced data points.

(c) Explain what you observe with these two choices of the x_i 's.