

**Lecture 5: 2.4 Paths and curves.**

A **path** in  $\mathbb{R}^3$  is a map  $\mathbf{c} : I \rightarrow \mathbb{R}^3$  of an interval  $I = [a, b]$  to  $\mathbb{R}^3$ , i.e. for each  $t \in I$   $\mathbf{c}(t)$  is a vector  $\mathbf{c} = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$ . A path is called a **curve** by some authors, but we define a **curve** to be the image in  $\mathbb{R}^3$  of a path.

The **velocity** of a path is defined to be

$$\mathbf{c}'(t) = \lim_{h \rightarrow 0} \frac{\mathbf{c}(t+h) - \mathbf{c}(t)}{h} = x'(t)\mathbf{i} + y'(t)\mathbf{j} + z'(t)\mathbf{k}.$$

Since the velocity is tangent to the curve, the **tangent line** to the curve at  $t_0$  is given by

$$\mathbf{L}(t) = \mathbf{c}(t_0) + \mathbf{c}'(t_0)t$$

**Example.** Let  $\mathbf{c}(t) = (\cos t, \sin t, t)$ . Find the equation of the tangent line at  $t = \pi/2$ .

**Solution.** We have  $\mathbf{c}'(t) = (-\sin t, \cos t, 1)$ . The equation of the tangent line is

$$\mathbf{L}(t) = \mathbf{c}(\pi/2) + \mathbf{c}'(\pi/2)(t - \pi/2) = (0, 1, \pi/2) + (-1, 0, 1)t$$

or  $x = -t$ ,  $y = 1$  and  $z = \pi/2 + t$ .

**2.5. The Chain Rule.**

The **Chain rule in one variable**: suppose that  $y = g(x)$ , and  $z = f(y)$ , i.e.  $z = h(x) := f(g(x)) = f \circ g(x)$  then

$$\frac{dz}{dx} = \frac{dz}{dy} \frac{dy}{dx} \quad \Leftrightarrow \quad h'(x) = f'(y) g'(x)$$

Why is this true?

$$\Delta z = f(y + \Delta y) - f(y) \approx f'(y)\Delta y$$

which is the same as saying that  $f$  is differentiable. Similarly

$$\Delta y = g(x + \Delta x) - g(x) \approx g'(x)\Delta x$$

and if we combine the two we get

$$\Delta z \approx f'(y) g'(x)\Delta x$$

The **Chain rule in several variables**: Suppose that  $g : \mathbf{R}^n \rightarrow \mathbf{R}^m$  is differentiable at  $\mathbf{x}_0$ , and  $f : \mathbf{R}^m \rightarrow \mathbf{R}^p$  is differentiable at  $\mathbf{y}_0 = f(\mathbf{x}_0)$ . Then  $h = f \circ g : \mathbf{R}^n \rightarrow \mathbf{R}^p$  is differentiable at  $\mathbf{x}_0$ , and

$$Dh(\mathbf{x}_0) = Df(\mathbf{y}_0) Dg(\mathbf{x}_0), \quad \text{where} \quad \mathbf{y}_0 = f(\mathbf{x}_0).$$

The right hand side is the  $p \times n$  matrix equal to the matrix  $Df(\mathbf{y}_0)$  multiplied by the matrix  $Dg(\mathbf{x}_0)$ .

The intuitive argument above actually generalizes to several variables just by replacing  $f'$  by  $Df$  etc. since differentiability of functions in several variables says

$$g(x + \Delta x) - g(x) \sim Dg(x)\Delta x.$$

**Chain rule case 1:  $f \circ \mathbf{c}$  where  $\mathbf{c}$  is a curve in  $\mathbb{R}^3$ .**

If  $h(t) = f(\mathbf{c}(t)) = f(x(t), y(t), z(t))$ , then by the chain rule

$$\frac{\partial(f \circ \mathbf{c})}{\partial t} = Df D\mathbf{c} = \begin{bmatrix} \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{bmatrix} \begin{bmatrix} \frac{dx}{dt} \\ \frac{dy}{dt} \\ \frac{dz}{dt} \end{bmatrix} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt} + \frac{\partial f}{\partial z} \frac{dz}{dt}$$

This can also be expressed with the gradient notation and dot product

$$\frac{df \circ \mathbf{c}}{dt}(t) = \nabla f(\mathbf{c}(t)) \cdot \mathbf{c}'(t)$$

**Example.** If  $z = x^2 + y^2$ ,  $x = \cos t$  and  $y = \sin t$  find  $dz/dt$ .

**Solution 1.**  $\frac{dz}{dt} = \frac{\partial z}{\partial x} \frac{dx}{dt} + \frac{\partial z}{\partial y} \frac{dy}{dt} = 2x(-\sin t) + 2y \cos t = 2 \cos t(-\sin t) + 2 \sin t \cos t = 0$ .

**Solution 2.**  $z = x^2 + y^2 = \cos^2 t + \sin^2 t = 1$ , so  $\frac{dz}{dt} = 0$ .

**Chain rule case 2:**

**Example.** Consider the surface which is given parametrically by the mapping  $(u, v) \rightarrow (x, y, z) = (u \cos v, u \sin v, u)$ , and the change of variables given by  $(p, q) \rightarrow (u, v) = (2p, pq)$ . Compute the partial derivatives  $\partial x/\partial p$ ,  $\partial x/\partial q$ ,  $\partial y/\partial p$ , etc., at the point  $(p, q) = (1, 0)$  by using the chain rule.

**Solution.**  $Dh = DfDg$ ,

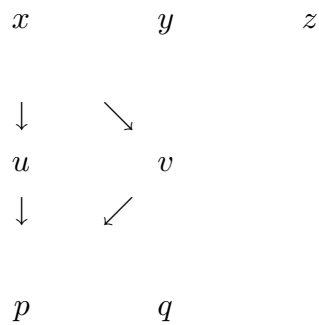
$$\begin{pmatrix} \frac{\partial x}{\partial p} & \frac{\partial x}{\partial q} \\ \frac{\partial y}{\partial p} & \frac{\partial y}{\partial q} \\ \frac{\partial z}{\partial p} & \frac{\partial z}{\partial q} \end{pmatrix} = \begin{pmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} \end{pmatrix} \begin{pmatrix} \frac{\partial u}{\partial p} & \frac{\partial v}{\partial p} \\ \frac{\partial u}{\partial q} & \frac{\partial v}{\partial q} \end{pmatrix} = \begin{pmatrix} \cos v & -u \sin v \\ \sin v & u \cos v \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ q & p \end{pmatrix}$$

(at  $(p, q) = (1, 0)$  we have  $(u, v) = (2, 0)$ )

$$= \begin{pmatrix} 1 & 0 \\ 0 & 2 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 0 \\ 0 & 2 \\ 2 & 0 \end{pmatrix}.$$

Notice by multiplying out the original matrices we have for example

$$\frac{\partial x}{\partial p} = \frac{\partial x}{\partial u} \frac{\partial u}{\partial p} + \frac{\partial x}{\partial v} \frac{\partial v}{\partial p}.$$



To compute  $\frac{\partial x}{\partial p}$ , using the diagram draw the variables  $x, y, z$  on the top line, the variables which they depend on directly ( $u, v$ ) on the next line and the variables which those variables depend directly on ( $p, q$ ) on the next line. Draw all the downward paths which join  $x$  to  $p$ . To each segment of the path, for example the segment between  $x$  and  $v$ , attach the corresponding partial derivative, in this case  $\partial x / \partial v$ . Now multiply together the derivatives for each path and sum over all paths.