

Sample Midterm Exam

Math 20F
8/22/08

Name: _____
Section: _____

Read all of the following information before starting the exam:

- READ EACH OF THE PROBLEMS OF THE EXAM CAREFULLY!
- Show all work, clearly and in order, if you want to get full credit. I reserve the right to take off points if I cannot see how you arrived at your answer (even if your final answer is correct).
- A single $8\frac{1}{2} \times 11$ sheet of notes (double sided) is allowed. No calculators are permitted.
- Circle or otherwise indicate your final answers.
- Please keep your written answers clear, concise and to the point.
- This test has xxx problems and is worth xxx points. It is your responsibility to make sure that you have all of the pages!
- Turn off cellphones, etc.
- Good luck!

1	
2	
3	
4	
5	
Σ	

1. (0 points)

(a) Let $A = \begin{pmatrix} 1 & 3 & 4 \\ 2 & 5 & 7 \\ 1 & 2 & 2 \end{pmatrix}$, and $\mathbf{b} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$. Solve $A\mathbf{x} = \mathbf{b}$.

Answer: By row reduction:

$$\mathbf{x} = \begin{pmatrix} 3 \\ 2 \\ -2 \end{pmatrix}.$$

(b) Suppose $T\left(\begin{pmatrix} 1 \\ -1 \end{pmatrix}\right) = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$ and $T\left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$. Find the matrix for the linear transformation T .

Answer: Note that the hypothesis imply $T\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 2 \\ 2 \end{pmatrix}$ and $T\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$, so

$$A = \begin{pmatrix} 2 & 0 \\ 2 & -1 \end{pmatrix}.$$

(c) Define linear independence.

Answer: Vectors $\mathbf{v}_1, \dots, \mathbf{v}_n$ are linearly independent if $\alpha_1\mathbf{v}_1 + \dots + \alpha_n\mathbf{v}_n = \mathbf{0}$ implies that $\alpha_i = 0$ for all i . (That is, the only linear combination of $\mathbf{v}_1, \dots, \mathbf{v}_n$ giving the $\mathbf{0}$ vector is the trivial one taking all coefficients to be zero.)

(d) Let $A = \begin{pmatrix} 1 & 2 & -2 \\ 3 & 4 & 0 \\ 2 & 5 & -7 \end{pmatrix}$. Are the columns of A linearly independent?

Answer: Row reducing A we get that

$$A \sim \begin{pmatrix} 1 & 2 & -2 \\ 0 & -2 & 6 \\ 0 & 0 & 0 \end{pmatrix}.$$

Since not every column is a pivot column, the columns are not linearly independent.

2. (0 points)

(a) Let $A = \begin{pmatrix} 1 & 2 & 1 \\ 0 & 3 & 0 \\ 1 & 1 & 1 \end{pmatrix}$. Let $B = \begin{pmatrix} 2 & 3 & 1 \\ 0 & 1 & 1 \\ -1 & 2 & -1 \end{pmatrix}$. Compute A^T, AB and

$B^T - 3A$.

Answer:

$$A^T = \begin{pmatrix} 1 & 0 & 1 \\ 2 & 3 & 1 \\ 1 & 0 & 1 \end{pmatrix}, \quad AB = \begin{pmatrix} 1 & 7 & 2 \\ 0 & 3 & 3 \\ 1 & 6 & 1 \end{pmatrix}, \quad B^T - 3A = \begin{pmatrix} -1 & -9 & -4 \\ 3 & -8 & 2 \\ -2 & -2 & -4 \end{pmatrix}.$$

(b) Let $A = \begin{pmatrix} 1 & -2 & 1 \\ 4 & -7 & 3 \\ -2 & 6 & 0 \end{pmatrix}$. Compute A^{-1} .

Answer:

$$A^{-1} = \frac{1}{4} \begin{pmatrix} -18 & 6 & 1 \\ -6 & 2 & 1 \\ 10 & -2 & 1 \end{pmatrix}.$$

(c) Suppose $A \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$, and $A \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \begin{pmatrix} -1 \\ 0 \end{pmatrix}$. Find A^{-1} .

Answer: Note that the hypothesis imply that $A^{-1} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ -2 \end{pmatrix}$ and $A^{-1} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$, so

$$A^{-1} = \begin{pmatrix} 1 & 1 \\ -2 & 2 \end{pmatrix}.$$

3. (0 points)

(a) Suppose $A = \begin{pmatrix} 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & -2 & 1 \\ 0 & 0 & -3 & 0 & 1 \\ 0 & 1 & 2 & 2 & -1 \\ 3 & 0 & 0 & 0 & 2 \end{pmatrix}$. Compute $\det(A)$.

Answer: Via 2 row exchanges,

$$A \sim A' = \begin{pmatrix} 3 & 0 & 0 & 0 & 2 \\ 0 & 1 & 2 & 2 & -1 \\ 0 & 0 & -3 & 0 & 1 \\ 0 & 0 & 0 & -2 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{pmatrix}$$

Thus $\det(A) = (-1)^2 \det(A')$. Since A' is upper triangular this is easy to compute, and we get $\det(A) = 18$.

(b) Suppose $A = \begin{pmatrix} 1 & -1 \\ 2 & 1 \end{pmatrix}$, and $\mathbf{b} = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$. Use Cramer's rule to solve $A\mathbf{x} = \mathbf{b}$.

Answer: Note that:

$$\det(A_1(\mathbf{b})) = \det \begin{pmatrix} 2 & -1 \\ 2 & 1 \end{pmatrix} = 3$$

$$\det(A_2(\mathbf{b})) = \det \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix} = -3$$

$$\det(A) = 3$$

So Cramer's rule gives $\mathbf{x} = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$.

(c)

Find the area of the *triangle* with vertices $(2, 3)$, $(4, 7)$ and $(8, 4)$ using the methods of this course.

Answer: The triangle is determined by the vectors $(2, 4)$ and $(6, 1)$, so

$$\text{Area} = \frac{1}{2} \left| \det \begin{pmatrix} 2 & 6 \\ 4 & 1 \end{pmatrix} \right| = 11.$$

4. (0 points) For each statement, mark it true or false. If it is false give a (counter)example or brief proof. If it is true give a reason - if the reason is a theorem, state the theorem, otherwise give a brief proof. No credit for answers without a correct reason or example. Unless explicitly noted, there are no condition on the dimensions of matrices A and B .

(a) If $\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\}$ are linearly dependent, then one of the vectors is a multiple of another.

FALSE: Take $\mathbf{v}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$, $\mathbf{v}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ and $\mathbf{v}_3 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$.

(b) If $A\mathbf{x} = \mathbf{b}$ is consistent for all \mathbf{b} , the columns of A span \mathbf{R}^m .

TRUE: If $A\mathbf{x} = \mathbf{b}$ is consistent for all \mathbf{b} , then for any \mathbf{b} , \mathbf{b} can be written as a linear combination of the columns of A (with coefficients given by \mathbf{x} .) This is exactly what it means to span \mathbf{R}^m .

(c) If $AB = AC$, then $B = C$.

FALSE: If A is the zero matrix, A times any matrix B is the zero matrix, so this is certainly false.

(d) If the transformation $T(\mathbf{x}) = A\mathbf{B}\mathbf{x}$ is onto, then the transformation $T'(\mathbf{x}) = A\mathbf{x}$ is onto

TRUE: We need to check that for each \mathbf{b} , there is a \mathbf{y} such that $\mathbf{b} = A\mathbf{y}$. But, we know that for every \mathbf{b} we can write $\mathbf{b} = A\mathbf{B}\mathbf{x}$ for some \mathbf{x} . We simply can take $\mathbf{y} = \mathbf{B}\mathbf{x}$. This checks the definition of onto.

(e) If A and B are $n \times n$, and invertible, then $A + B$ is invertible.

FALSE: If A is invertible, so is $-A$, and $A + (-A)$ is the zero matrix which is not invertible.

(f) If A is row equivalent to B , then $\det(A) = \det(B)$.

FALSE: Though $\det(A)$ is unchanged by row replacement, swapping rows and multiplying a row by a scalar changes the determinant. Example:

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \sim \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}$$

but the determinants are different.

(g) If the columns of A are linearly dependent, then $\text{Col}(A)$ is not a vector space.

FALSE: $\text{Col}(A)$ is the span of the columns of A , and the span of any vectors is a vector space (even if they are linearly dependent).

5. (0 points)

(a) If $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a linear transformation verify that the range of $T = \{\mathbf{v} \in \mathbb{R}^m : T(\mathbf{x}) = \mathbf{v} \text{ for some } \mathbf{x} \in \mathbb{R}^n\}$, is a vector space. (Note the range is not necessarily all of \mathbb{R}^m . \mathbb{R}^m is the co-domain, not the range.)

Answer: It suffices to check that the range is a subspace as it sits inside \mathbb{R}^m . Actually this is what I intended to ask. Let \mathcal{R} denote the range. If $\mathbf{u}, \mathbf{v} \in \mathcal{R}$ then by definition of \mathcal{R} , $\mathbf{u} = T(\mathbf{x})$ and $\mathbf{v} = T(\mathbf{y})$. Note that

$$\mathbf{u} + \mathbf{v} = T(\mathbf{x}) + T(\mathbf{y}) = T(\mathbf{x} + \mathbf{y})$$

so $\mathbf{u} + \mathbf{v} \in \mathcal{R}$.

If $\mathbf{u} = T(\mathbf{x}) \in \mathcal{R}$ then $c\mathbf{u} = cT(\mathbf{x}) = T(c\mathbf{x}) \in \mathcal{R}$. Finally, we need to check $\mathbf{0} \in \mathcal{R}$, but $T(\mathbf{0}) = \mathbf{0}$ so indeed it is. We've checked the three conditions so \mathcal{R} is a subspace of \mathbb{R}^m .

(b) Verify that the derivative operator $\frac{d}{dx}$ is a linear transformation from the vector space of polynomials of degree at most 3 to the vector space of polynomials of degree at most 2. Is this linear transformation 1-1? Onto?

Answer: Here we use elementary properties of the derivative. Recall a linear transformation satisfies: $T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$ and $T(c\mathbf{u}) = cT(\mathbf{u})$. In our case, $T = \frac{d}{dx}$ and our vectors \mathbf{u} and \mathbf{v} are polynomials $f(x)$ and $g(x)$. Note:

$$\frac{d}{dx}(f(x) + g(x)) = \frac{d}{dx}f(x) + \frac{d}{dx}g(x)$$

so the first property holds, and

$$\frac{d}{dx}cf(x) = c\frac{d}{dx}f(x)$$

so the second property also holds, and hence $\frac{d}{dx}$ is a linear transformation. $\frac{d}{dx}1 = \frac{d}{dx}2 = 0$, so $\frac{d}{dx}$ is not 1-1, however $\frac{d}{dx}\int f(x)dx = f(x)$, so $\frac{d}{dx}$ is onto.