

Math 155A — Computer Graphics — Winter 2019
Homework #2 — Due Monday, February 4, 9:00pm
Hand in via Gradescope — Use separate pages for each problem 1.-3.

1. Suppose \mathcal{C} is a radius 1, height 2 cylinder centered at the origin, with central axis the y -axis. The top face of \mathcal{C} is the horizontal disk of radius one centered $\langle 0, 1, 0 \rangle$. The bottom face of \mathcal{C} is the horizontal disk of radius one centered $\langle 0, -1, 0 \rangle$. (“Horizontal” means parallel to the xz -plane.)

Let \mathcal{D} a skewed cylinder (also called an oblique cylinder, please “google” it) which has central axis the line where $y = x$ and $z = 0$, and has perpendicular height 4, with the top face of \mathcal{D} the horizontal radius 1 disk centered at $\langle 4, 4, 0 \rangle$ and the bottom face of \mathcal{D} the horizontal radius 1 disk centered at $\langle 0, 0, 0 \rangle$.

- a. Draw a picture of \mathcal{D} .
- b. Give a 4×4 matrix M so that M represents the affine transformation sending \mathcal{C} to \mathcal{D} .
2. Let B be the transformation $\langle x, y, z \rangle \mapsto \langle \frac{1+x}{1-y} - 1, 0, \frac{z}{1-y} \rangle$. Give a 4×4 matrix which represents this transformation over homogeneous coordinates. (When $0 < y < 1$, B give the transformation for a shadow cast from a light at $\langle -1, 1, 0 \rangle$ onto the plane $y = 0$. You do **not** need to use this fact to work the problem!)
3. A light source is placed at $\langle -10, 0, 0 \rangle$ and it casts shadows onto the yz -plane P defined by $x = 0$. The yz -plane is like an infinite wall.

When $\langle x, y, z \rangle$ is a point in \mathbb{R}^3 with $-10 < x \leq 0$, define $A(\langle x, y, z \rangle)$ to be the position of the shadow of the point on the yz -plane. For example, $A(\langle -5, 1, 2 \rangle) = \langle 0, 2, 4 \rangle$, and $A(\langle -8, 1, 2 \rangle) = \langle 0, 5, 10 \rangle$

- a. Working in ordinary coordinates (not homogeneous) give the formula expressing the mapping $A(\langle x, y, z \rangle) = \langle x', y', z' \rangle$. That is, give formulas for x', y', z' in terms of x, y, z .
- b. Give a 4×4 -matrix that represents the transformation A over homogeneous coordinates.