Lower Complexity Bounds in Justification Logic

Samuel R. Buss\textsuperscript{a,1}, Roman Kuznets\textsuperscript{b,2,∗}

\textsuperscript{a}Department of Mathematics, University of California, San Diego
La Jolla, CA 92093-0112, USA

\textsuperscript{b}Institut für Informatik und angewandte Mathematik, Universität Bern
Neubrückstrasse 10, 3012 Bern, Switzerland

Abstract

Justification Logic studies epistemic and provability phenomena by introducing justifications/proofs into the language in the form of justification terms. Pure justification logics serve as counterparts of traditional modal epistemic logics, and hybrid logics combine epistemic modalities with justification terms. The computational complexity of pure justification logics is typically lower than that of the corresponding modal logics. Moreover, the so-called reflected fragments, which still contain complete information about the respective justification logics, are known to be in NP for a wide range of justification logics, pure and hybrid alike. This paper shows that, under reasonable additional restrictions, these reflected fragments are NP-complete, thereby proving a matching lower bound. The proof method is then extended to provide a uniform proof that the corresponding full pure justification logics are \(\Pi^p_2\)-hard, reproving and generalizing an earlier result by Milnikel.

1. Introduction

Justification Logic is an emerging field that studies provability, knowledge, and belief via explicit proofs or justifications that are part of the language. A justification logic is essentially a refined analogue of a modal epistemic logic. Whereas the latter uses \(\square F\) to indicate that \(F\) is known to be true, a justification logic uses \(t:F\) instead, where \(t\) is a term that describes a ‘justification’ or proof of \(F\). This construction enables justification logics to reason about both formulas and proofs at the same time, avoiding the need to treat provability at the metalevel.

Because Justification Logic can reason directly about explicit proofs, it provides more concrete and constructive analogues of modal epistemic logics. For example, the modal distribution axiom \(\square(F \rightarrow G) \rightarrow (\square F \rightarrow \square G)\) is replaced in Justification...
Logic by the axiom \(s : (F \rightarrow G) \rightarrow (t : F \rightarrow (s \cdot t) : G)\). The latter replaces the distribution axiom with a computationally explicit construction. Justification logics are very promising for structural proof theory and have already proved to be fruitful in finding new approaches to common knowledge ([4, 12]), the Logical Omniscience Problem ([7, 8]), and self-referentiality of proofs ([22]). For further discussion on the various applications of Justification Logic, see [6].

The goal of the present paper\(^3\) is to provide a uniform method of proving lower bounds for the Derivability Problems in various justification logics and their reflected fragments by reduction from problems similar to the Vertex Cover Problem. We begin by reviewing some definitions of justification logics.

The historically first justification logic, the Logic of Proofs LP, was introduced by Sergei Artemov [2] to provide a provability semantics for the modal logic S4 (see also [3]). The language of LP

\[
F ::= p \mid \bot \mid (F \rightarrow F) \mid t : F, \\
t ::= x \mid c \mid (t \cdot t) \mid (t + t) \mid !t
\]

contains an additional operator \(t : F\), read ‘term \(t\) serves as a justification/proof of formula \(F\).’ Here \(p\) stands for a sentence letter, \(x\) for a justification variable, and \(c\) for a justification constant. Formulas of the form \(t : F\) are called justification assertions.

Statements \(t : F\) can be seen as refinements of modal statements \(\Box F\) because the latter say that \(F\) is known, whereas the former additionally provide a rationale for such knowledge. This relationship is demonstrated through the recursively defined operation of forgetful projection that maps justification formulas to modal formulas:

\[(t : F) \rightarrow = \Box (F)\]

and commutes with Boolean connectives:

\[(F \rightarrow G) \rightarrow = F \rightarrow G\]

where \(p\) \(\rightarrow = p\) and \(\bot\) \(\rightarrow = \bot\).

### Axioms and rules of LP:

- **A1.** A complete axiomatization of classical propositional logic by finitely many axiom schemes; rule modus ponens;

- **A2.** Application Axiom \(s : (F \rightarrow G) \rightarrow (t : F \rightarrow (s \cdot t) : G)\);

- **A3.** Monotonicity Axiom \(s : F \rightarrow (s + t) : F, \quad t : F \rightarrow (s + t) : F\);

- **A4.** Factivity Axiom \(t : F \rightarrow F\);

- **A5.** Positive Introspection Axiom \(t : F \rightarrow !t : F\);

- **R4.** Axiom Internalization Rule \(c : A\), where \(A\) is an axiom of LP and \(c\) is a justification constant.

LP is the exact counterpart of S4 (note the similarity of their axioms): namely, let \(X^\circ = \{F^\circ \mid F \in X\}\) for a set \(X\) of justification formulas and let LP be identified with the set of its theorems, then

\[^3\text{An earlier version of this paper appeared in the proceedings of LFCS 2009 ([13]).}\]
Table 1: Axioms for Justification Logics

<table>
<thead>
<tr>
<th>Justification axiom scheme</th>
<th>Present in logics</th>
</tr>
</thead>
<tbody>
<tr>
<td>A4. $t : F \rightarrow F$</td>
<td>JT, LP</td>
</tr>
<tr>
<td>A5. $t : F \rightarrow ! t : ! F$</td>
<td>J4, JD4, LP</td>
</tr>
<tr>
<td>A7. $t : \bot \rightarrow \bot$</td>
<td>JD, JD4</td>
</tr>
</tbody>
</table>

Theorem 1 (Realization Theorem, [2, 3]). $\text{LP}^o = \text{S4}$.

Other epistemic modal logics have their own justification counterparts in the same sense. Counterparts of the modal logics $K$, $D$, $T$, $K4$, and $D4$ were developed by Vladimir Brezhnev in [11]. These justification logics, named $\text{J}$, $\text{JD}$, $\text{JT}$, $\text{J4}$, and $\text{JD4}$ respectively, are all subsystems of $\text{LP}$ and share the $\text{A1}–\text{A3}$ portion of its axiom system. The remaining two axiom schemes are included dependent on whether or not their forgetful projections are axioms of the respective modal logic. In addition, $\text{JD}$ and $\text{JD4}$ require a new axiom scheme:

$$A7. \text{Consistency} \quad t : \bot \rightarrow \bot,$$

whose forgetful projection is the modal Seriality Axiom. Complete details can be found in Table 1.

Finally, the rule R4 for $\text{J4}$ and $\text{JD4}$ is written the same way as for $\text{LP}$, but of course it now applies to the axioms of $\text{J4}$, respectively $\text{JD4}$. The logics without the Positive Introspection Axiom $A5$ still require some restricted form of positive introspection for constants which is embedded into the Axiom Internalization Rule:

$$R4$. Axiom Internalization Rule

$$\frac{\ldots ![c] \ldots ![c]! c : c : A}{n}$$

where $A$ is an axiom of the logic, $c$ is a justification constant, and $n \geq 0$ is an integer.

This form of the Axiom Internalization Rule is used for $\text{J}$, $\text{JD}$, and $\text{JT}$.

Theorem 2 (Realization Theorem, [11]).

$$\text{J}^o = \text{K}, \quad \text{JD}^o = \text{D}, \quad \text{JT}^o = \text{T},$$

$$\text{J4}^o = \text{K4}, \quad \text{JD4}^o = \text{D4}.$$

All these justification logics are pure in the sense that only terms are present in the language, but not modalities. In [4], Artemov studied hybrid justification logics $\text{T}_o\text{LP}$,

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4The apparent break in the numbering of axioms is due to the Negative Introspection Axiom $A6$ that remains outside the scope of this paper. The numbering of rules follows [5].

5The term “hybrid justification logic” is used here differently from [16], where it is a hybrid of hybrid logic and a justification logic, whereas in our case it is a hybrid of a modal logic and a justification logic.
S4_nLP, and S5_nLP. These combine terms with modalities for several agents (a single-agent variant S4_1LP was originally developed by Artemov jointly with Elena Nogina, see [9]).

**Axioms and rules of** T_nLP, S4_nLP, and S5_nLP:

Let ML ∈ {T, S4, S5}.

1. Axioms and rules of the multimodal logic ML_n.

2. Axioms and rules of the justification logic LP.

3. **Connection axiom.** For each i = 1, . . . , n, t : F → □_i F.

The Axiom Internalization Rule R4 in 2. is extended to apply to all axioms of ML_nLP.

For some applications (e.g., to avoid Logical Omniscience [7] or to study self-referentiality [22]) the use of constants needs to be restricted; this is achieved using *constant specifications*. A constant specification CS for a justification logic JL is a set of instances of the rule R4 for this logic:

CS ⊆ {c : A | A is an axiom of JL, c is a justification constant}.

Given a constant specification CS for JL, the logic JL_CS is the result of replacing the Axiom Internalization Rule in JL (R4 or R4') by its relativized version, respectively by:

R4_CS.  
\[
\frac{c : A \in CS}{c : A},
\]

R4'_CS.  
\[
\frac{c : A \in CS}{\circ \cdots \circ c : \cdots : ! c : c : A}, \quad \text{where } n \geq 0 \text{ is an integer.}
\]

The Realization Theorem holds for a pure justification logic JL with a constant specification CS, i.e., (JL_CS)^o = ML = JL^o, iff CS is axiomatically appropriate:

**Definition 3.** A constant specification CS for a logic JL is called:

- *axiomatically appropriate*\(^6\) if every axiom of JL is justified by at least one constant;

- *schematic*\(^7\) if each constant justifies several (maybe 0) axiom schemes and only them;

- *schematically injective*\(^8\) if it is schematic and each constant justifies no more than one axiom scheme.

The following is the fundamental property of justification logics, closely related to the Realization Theorem:

**Lemma 4 (Constructive Necessitation. [2, 4, 5]).** Let CS be an axiomatically appropriate constant specification for a justification logic JL. For any theorem F of JL_CS, there exists a + -free ground\(^9\) justification term s such that JL_CS ⊢ s : F.

\(^6\)The term is due to Melvin Fitting.

\(^7\)The term is due to Robert Milnikel although the idea goes back to Alexey Mkrtychev.

\(^8\)The term is due to Milnikel.

\(^9\)A justification term is called ground if it contains no occurrences of justification variables.
Whereas it is well known that the Derivability Problems for the modal logics K, D, T, K4, D4, and S4 are PSPACE-complete ([23]), it was shown that

**Theorem 5** ([19, 21, 1]). Let JL ∈ {J, JD, JT, J4, JD4, LP} and CS be an axiomatically appropriate and schematic constant specification for JL. Then the Derivability Problem for JLCS is in Π².

In particular, LP itself is in Π².

**Remark 6.** The restriction on the constant specification being axiomatically appropriate in the preceding theorem is not necessary for J, JT, J4, and LP.

Robert Milnikel proved some matching lower bounds, namely:

**Theorem 7** ([24]).

1. LP_CS is Π²-hard provided CS is axiomatically appropriate and schematically injective;
2. J4-CS is Π²-hard provided CS is axiomatically appropriate and schematic.

The so-called reflected fragment rLP of the Logic of Proofs was studied by Nikolai Krupski in [18].

**Definition 8.** For any justification logic JL_CS with a constant specification CS, the reflected fragment of the logic consists of all provable justification assertions:

\[ rJL_CS = \{ t : F | JL_CS \vdash t : F \} \]

We will write \( rJL_CS \vdash t : F \) to mean \( t : F \in rJL_CS \). At the end of this section, we will present an axiomatization for several reflected fragments via \( * \)-calculi, which would make the use of \( \vdash \) more natural.

A reflected fragment bears complete information about the underlying logic as the following theorem shows:

**Theorem 9** ([18, 21]). Let JL ∈ {J, JD, JT, J4, JD4, LP, TnLP, S4nLP, SSnLP} and CS be an axiomatically appropriate constant specification for JL. Then

\[ JL_CS \vdash F \iff (\exists t) rJL_CS \vdash t : F \]  

(The requirement of axiomatic appropriateness is necessary only for the \( \Rightarrow \)-direction.)

The \( \Rightarrow \)-direction constitutes the Constructive Necessitation Property (Lemma 4). The \( \iff \)-direction easily follows from the Factivity Axiom A4 for all logics but J, JD, J4, and JD4 that do not have Factivity. For these four logics, the statement can be proved semantically using F-models (see [15] for their description) or syntactically by transforming a derivation of \( t : F \) in the respective \( * \)-calculus into a derivation of \( F \) in the underlying justification logic (the details of this transformation can be found in [21, proof of Lemma 3.4.10]).

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10In all complexity results, we always assume CS to be polynomial-time decidable.
Table 2: ★-Calculi

<table>
<thead>
<tr>
<th>Calculus</th>
<th>Axioms and rules</th>
<th>Used for</th>
</tr>
</thead>
<tbody>
<tr>
<td>★CS</td>
<td>★CS', ★A2, ★A3</td>
<td>rJCS, rJDCS, rJTCS</td>
</tr>
<tr>
<td>★LCS</td>
<td>★CS, ★A2, ★A3, ★A5</td>
<td>rJ4CS, rJD4CS, rLP_{CS}, rTnLP_{CS}, rS4nLP_{CS}, rSSnLP_{CS}</td>
</tr>
</tbody>
</table>

**Theorem 10** ([18, 21]). Let JL ∈ {J, JD, JT, J4, JD4, LP, TnLP, S4nLP, S5nLP} and CS be a schematic constant specification for JL. The Derivability Problem for rJL_{CS}, the reflected fragment of JL_{CS}, is in NP.

To prove Theorem 10 for rLP_{CS}, N. Krupski developed an axiomatization for rLP_{CS} that we will call the ★CS-calculus.

**Axioms and rules of the ★CS-calculus:**

- **★CS. Axioms:** for any c:A ∈ CS, c:A;
- **★A2. Application Rule**
  \[ \frac{s: (F \rightarrow G) \quad t: F}{s \cdot t: G} \]
- **★A3. Sum Rule**
  \[ \frac{s: F \quad t: F}{s + t: F} \]
- **★A5. Positive Introspection Rule**
  \[ \frac{t: F}{!t: t': F} \]

In [21], this calculus was shown to also axiomatize the logics rJ4CS, rJD4CS, rTnLP_{CS}, rS4nLP_{CS}, and rSSnLP_{CS}. In particular, the three logics LP_{CS}, J4_{CS}, and JD4_{CS} all use the ★LCS-calculus to axiomatize their reflected fragments. The reflected fragments rJCS, rJDCS, and rJTCS of the three theories which do not have positive introspection are all axiomatized by the ★CS-calculus which is obtained by omitting the rule ★A5 from the ★LCS-calculus while simultaneously extending the set of axioms to include:

- **★CS’. Axioms:** for any c:A ∈ CS and any integer \( n \geq 0 \), \[ ! ! \cdots ! ! c : ! ! c : ! c : ! c : ! c : ! c : ! c : c : A. \]

Note that axioms ★CS are instances of ★CS’ with \( n = 0 \). Therefore, ★CS can be used both in the ★CS- and the ★LCS-calculi.

We collectively call the ★CS- and the ★LCS-calculi the ★-calculi, which are summarized in Table 2. As can be seen from the preceding discussion and the summarizing table, there are only two calculi that axiomatize the reflected fragments of various pure and hybrid justification logics. More precisely, the rules of the ★-calculus for a given justification logic J_{CS} depend solely on whether JL enjoys full positive introspection while the axioms of this ★-calculus are read from CS and thus indirectly depend on the axioms of JL.

In Theorem 37 below, we will show that the same rules can be used in the setting where there are non-logical axioms in addition to the ★CS or ★CS’ axioms.
The first main result of the present paper, Theorem 33, is a lower bound on the complexity of reflected fragments that matches the upper bound of Theorem 10; namely, we show that the Derivability Problems for many reflected fragments are NP-complete. The proof is by a many-one polynomial-time reduction from a known NP-complete problem, the Vertex Cover Problem. As in Milnikel’s lower bound for $\text{LP}_{\text{CS}}$, we have to impose an additional restriction that GS be axiomatically appropriate and schematically injective. The reduction method is then extended to establish a lower bound on the complexity of full pure justification logics that also matches the upper bound of Theorem 5; this gives a reproof of the $\Pi^p_2$-hardness results of [24] and extends the results to additional justification logics.

The paper is structured as follows. Section 2 defines a coding of graphs by propositional formulas and shows how the existence of a vertex cover can be described in terms of these formulas. Section 3 develops justification terms that encode several standard methods of propositional reasoning. Although the formulas that describe the existence of a vertex cover depend on the cover itself rather than only on its size, Sect. 4 shows how to eliminate this dependency by using the terms from Sect. 3 to encode particular derivations of the formulas from Sect. 2. Section 5 finishes the proof of the polynomial-time reduction. This reduction is used in Sect. 6 to establish a criterion for NP-hardness of reflected fragments and to apply it to a wide range of them. Section 7 lays the groundwork for proving lower bounds for full pure justification logics, which is done in Sect. 8 by generalizing the Vertex Cover Problem to a $\Pi^p_2$-complete version. Finally, Sect. 9 explores the restrictions on the constant specification necessary for the proved lower bounds.

2. Graph Coding and Preliminaries

A graph $G = \langle V, E \rangle$ has a finite set $V$ of vertices and a finite set $E$ of undirected edges. We assume w.l.o.g. that $V = \{1, \ldots, N\}$ for some $N$ and represent an edge $e$ between vertices $k$ and $l$ as the set $e = \{k, l\}$ with its endpoints denoted by $v_1(e) < v_2(e)$. A vertex cover for $G$ is a set $C$ of vertices such that each edge $e \in E$ has at least one endpoint in $C$. The Vertex Cover (VC) Problem is the problem of determining whether a given graph $G$ has a vertex cover of a size $\leq L$ for a given integer $L \geq 0$. The Vertex Cover Problem is one of the classic NP-complete problems.

We define below formulas $F_V$, $F_C$, and $F_G$ that will help build a many-one reduction from VC to the reflected fragments of justification logics. These formulas will include large conjunctions. To avoid the dependence of derivations on a vertex cover, we will use balanced conjunctions (see [10]):

**Definition 11.** Each formula is a balanced conjunction of depth 0. If $A$ and $B$ are both balanced conjunctions of depth $k$, then $A \land B$ is a balanced conjunction of depth $k + 1$.

Clearly, a balanced conjunction of depth $k$ is also a balanced conjunction of depth $l$ for any $0 \leq l \leq k$. Thus, we are mainly interested in how deeply a given formula is conjunctively balanced. Unless stated otherwise, for any conjunction $C_1 \land \cdots \land C_{2^k}$ of $2^k$ formulas, we assume that the omitted parentheses are such that the resulting balanced conjunction has the maximal possible depth, i.e., depth $\geq k$. 

We also need to refer to $C_i$'s that form a conjunction $C_1 \land \cdots \land C_{2^k}$. The following inductive definition of depth $k$ conjuncts, or simply $k$-conjuncts, generalizes the definition of conjuncts in an ordinary conjunction:

**Definition 12.** Each formula is a 0-conjunct of itself. If $C \land D$ is a $k$-conjunct of a formula $F$, then $C$ and $D$ are both $(k + 1)$-conjuncts of $F$.

For instance, the conjuncts of an ordinary conjunction are its 1-conjuncts; all $C_i$'s in $C_1 \land \cdots \land C_{2^k}$ are its $k$-conjuncts. More generally, any balanced conjunction of depth $k$ has exactly $2^k$ occurrences of $k$-conjuncts (with possibly several occurrences of the same formula).

To make a full use of balanced conjunctions, it is convenient to restrict attention to instances of the Vertex Cover Problem for graphs in which both the number of vertices and the number of edges are powers of 2. These are called binary exponential graphs. It is also helpful to only consider vertex covers whose size is a power of 2; these we call binary exponential vertex covers. Fortunately, the version of the Vertex Cover Problem restricted to binary exponential graphs and their binary exponential vertex covers is also NP-complete:

**Theorem 13.** The Binary Vertex Cover (BVC) Problem of determining whether a given binary exponential graph $G$ has a vertex cover of size $\leq 2^l$ for a given integer $l \geq 0$ is NP-complete.

**Proof.** Since each instance of BVC is also an instance of the standard VC problem, and since VC is NP-complete, it suffices to construct a polynomial-time many-one reduction from VC to BVC. Suppose we are given an instance of VC; namely, we are given a graph $G_0$ and an integer $L$ and wish to determine if $G_0$ has a vertex cover of size $\leq L$. We give a polynomial-time procedure that constructs a binary exponential graph $G$ and a value $l$ so that $G_0$ has a vertex cover of size $\leq L$ iff $G$ has a vertex cover of size $\leq 2^l$. The graph $G$ is constructed in three stages; each stage causes only a constant factor increase in the size of the graph.

**Stage 1. Increasing the size of vertex covers.** Choose an integer $0 \leq L' < L$ such that $L + L' = 2^l - 1$ for some integer $l \geq 0$. A graph $G' = \langle V', E' \rangle$ is obtained from $G_0$ by adding $2L'$ new vertices broken into $L'$ disjoint pairs with the vertices in each pair joined by a new edge ($L'$ new edges overall). The graph $G_0$ has a vertex cover of size $\leq L$ iff the graph $G'$ has a vertex cover of size $\leq 2^l - 1$.

**Stage 2. Increasing the number of edges.** Choose an integer $0 < M'' \leq |E'|$ such that $|E'| + M'' = 2^m$ for some integer $m \geq 0$. A graph $G'' = \langle V'', E'' \rangle$ is obtained by adding $M'' + 1$ new vertices to $G'$ with one of these vertices joined to all $M''$ others ($M''$ new edges overall). The graph $G'$ has a vertex cover of size $\leq 2^l - 1$ iff the graph $G''$ has a vertex cover of size $\leq 2^l$.

**Stage 3. Increasing the number of vertices.** Choose an integer $0 \leq N''' < |V''|$ such that $|V''| + N''' = 2^k$ for some integer $k \geq 0$. A graph $G = G'''$ is obtained by adding $N'''$ isolated vertices to $G''$. The graph $G''$ has a vertex cover of size $\leq 2^l$ iff the graph $G'''$ has a vertex cover of size $\leq 2^l$.

It is clear from the construction that $G$ is a binary exponential graph such that $G_0$ has a vertex cover of size $\leq L$ iff $G$ has a vertex cover of size $\leq 2^l$. □
Definition 14. Let $G = \langle V, E \rangle$ be a binary exponential graph with $E = \{e_1, \ldots, e_{2^n}\}$. We define the following formulas:

a. For each edge $e_i = \{i_1, i_2\} \in E$, where $i_1 < i_2$, $F_e = p_{i_1} \lor p_{i_2} = p_{v(e)} \lor p_{v(e')}$. 

b. Let $C = \{i_1, i_2, \ldots, i_{2^n}\} \subseteq V$ be a possible binary exponential vertex cover for $G$, where $i_1 < i_2 < \cdots < i_{2^n}$. Define $F_C = p_{i_1} \land \cdots \land p_{i_{2^n}}$.

c. $F_G = F_{e_1} \land \cdots \land F_{e_{2^n}}$.

The proof of the following properties is an easy exercise ($\vdash$ denotes derivability in classical propositional logic):

Lemma 15. For any binary exponential graph $G = \langle V, E \rangle$ and any binary exponential set $C \subseteq V$,

1. $\vdash F_V \to F_G$ ;
2. $\vdash F_V \to F_C$ ;
3. $\vdash F_C \to F_G$ iff $C$ is a vertex cover for $G$.

Our goal is to reduce BVC to derivability in a given reflected fragment. To this end, we consider a particular derivation of $F_V \to F_G$ that proceeds by first proving $F_V \to F_C$, then attempting to prove $F_C \to F_G$, succeeding in the attempt iff $C$ is a vertex cover, and finally applying hypothetical syllogism (HS) to infer $F_V \to F_G$. We further encode this derivation as a justification term $t$ so that $\text{rJL}_{CS} \vdash t : (F_V \to F_G)$ iff $C$ is a vertex cover. In BVC we need to determine whether there exists a vertex cover of (at most) a given size rather than whether a given set of vertices is a vertex cover. Thus, $t : (F_V \to F_G)$ should not depend on $C$ but may (and should) depend on the size of $C$. Since $C$ has already been “syllogized away” from the formula $F_V \to F_G$, it remains to make sure that the term $t$ only depends on the size of $C$. Although any derivations of $F_V \to F_C$ and of $F_C \to F_G$ necessarily explicitly depend on $C$, the terms encoding them, and therefore $t$, can be made independent of $C$. This is the main reason why we use balanced conjunctions: this way all $k$-conjuncts are interchangeable.

Instead of giving a proof for one particular type of reflected fragments and explaining how to adjust it to other cases as in [13], we will now formulate conditions under which a reflected fragment fits our construction. These conditions have the following form: for certain individual axiom schemes or their sets there must exist a term that justifies exactly the axioms from this scheme or this set of schemes respectively.

Definition 16. A reflected fragment $\text{rJL}_{CS}$ is called fitting if it has ground terms $c_1, c_2, c_{A_1A_2}, c_A$, and $c_{V1,V2}$ with the following properties:

\[
\begin{align*}
\text{rJL}_{CS} \vdash c_1 \colon F & \iff F \equiv (X \to (Y \to X)), \\
\text{rJL}_{CS} \vdash c_2 \colon F & \iff F \equiv ((X \to (Y \to Z)) \to ((X \to Y) \to (X \to Z))), \\
\text{rJL}_{CS} \vdash c_{A_1A_2} \colon F & \iff F \equiv (X_1 \land X_2 \to X_i), \quad \text{where } i = 1 \text{ or } i = 2, \\
\text{rJL}_{CS} \vdash c_A \colon F & \iff F \equiv (X \to (Y \to X \land Y)), \\
\text{rJL}_{CS} \vdash c_{V1,V2} \colon F & \iff F \equiv (X_i \to X_1 \lor X_2), \quad \text{where } i = 1 \text{ or } i = 2,
\end{align*}
\]

where $X, Y, Z, X_1,$ and $X_2$ are arbitrary formulas.
Most natural schematically injective constant specifications for justification logics yield fitting reflected fragments. Note that terms $c_1$, $c_2$, and $c_\lambda$ should justify exactly one commonly used propositional axiom scheme each. In fact, if these axiom schemes are part of A1 for a particular justification logic $JL$ and if $CS$ is schematically injective, these terms may have an especially simple form: they can be constants justifying their respective axiom schemes. The two terms $c_{\lambda, A_2}$ and $c_{v_1, v_2}$ should justify two commonly used axiom schemes each. In general, they can be modeled by the sums of terms corresponding to those axiom schemes. That is to say, $c_{\lambda, A_2}$ can be defined to be $c_{\lambda_1} + c_{\lambda_2}$, where $c_{\lambda_1}$ justifies exactly the scheme $X_1 \land X_2 \rightarrow X_i$. Similarly, $c_{v_1, v_2}$ can generally be set equal to $c_{v_1} + c_{v_2}$ for appropriate terms $c_{v_1}$ and $c_{v_2}$.

We shall prove the NP-hardness of fitting reflected fragments by giving a reduction from BVC to derivability in the reflected fragment. Therefore, our complexity lower bounds hold for any fitting reflected logic, and they do not depend on the particular propositional axiomatization chosen, or the particular form of the five terms from (1). In fact, as will be shown, it is not even important that the operation $+$ be present.

3. Justification Terms Encoding Propositional Reasoning

Throughout the section, we assume that a reflected fragment $rJL_{CS}$ is fitting. All $*$-derivations in this and the next two sections can be performed in either of the $*$-calculi. In each case, the choice of the $*$-calculus is made based on the underlying reflected fragment according to Table 2.

The size of terms is defined in a standard way: $|c| = |x| = 1$ for any constant $c$ and any variable $x$, $|(t \cdot s)| = |t| + |s| + 1, |\!\!t| = |t| + 1$.

Note that all the terms from (1) have size $O(1)$ because there are only five of them.

**Lemma 17** (Encoding the Hypothetical Syllogism Rule). The operation

\[
syl(t, s) = (c_2 \cdot (c_1 \cdot s)) \cdot t
\]

with $|syl(t, s)| = |t| + |s| + O(1)$ encodes the Hypothetical Syllogism Rule, i.e.,

\[
rJL_{CS} \vdash syl(t, s) : H \quad \iff \quad H = A \rightarrow C \text{ such that for some } B \quad rJL_{CS} \vdash t : (A \rightarrow B) \quad \text{and} \quad rJL_{CS} \vdash s : (B \rightarrow C).
\]

**Proof.** ($\iff$). Here are the key elements of a derivation of $t : (A \rightarrow B), s : (B \rightarrow C) \vdash syl(t, s) : (A \rightarrow C)$ (parts of the derivation following from the “fit” of the reflected fragment are omitted):

\[
\begin{align*}
c_1 & : ((B \rightarrow C) \rightarrow (A \rightarrow (B \rightarrow C))) \quad \text{(fit)} \\
s & : (B \rightarrow C) \quad \text{(Hyp)} \\
c_1 \cdot s & : (A \rightarrow (B \rightarrow C)) \quad \text{(*A2)} \\
c_2 & : ((A \rightarrow (B \rightarrow C)) \rightarrow ((A \rightarrow B) \rightarrow (A \rightarrow C))) \quad \text{(fit)} \\
c_2 \cdot (c_1 \cdot s) & : ((A \rightarrow B) \rightarrow (A \rightarrow C)) \quad \text{(*A2)} \\
t & : (A \rightarrow B) \quad \text{(Hyp)} \\
(c_2 \cdot (c_1 \cdot s)) \cdot t & : (A \rightarrow C) \quad \text{(*A2)}
\end{align*}
\]

($\Rightarrow$). Consider an arbitrary derivation of $syl(t, s) : H$ in the $*$-calculus. It can easily be seen that any such derivation must have the same key elements as the one used for
the \(\iff\)-direction above: the only difference can be in the choice of formulas for the terms \(c_1, c_2, s,\) and \(t.\) Since the reflected fragment is fitting, we know which formulas can be proved by \(c_1\) and \(c_2.\) Thus, we can shape this as a unification problem: find formulas \(X_1, Y_1, X_2, Y_2, Z_2, X_4,\) and \(X_5\) such that \(\text{rJL}_{\text{CS}} \vdash s : X_s,\) \(\text{rJL}_{\text{CS}} \vdash t : X_r,\) and the following is a \(*\)-calculus derivation of \(s : X_s, t : X_r \vdash \text{syl}(t, s) : H\) modulo derivability of statements from (1):

1. \(c_1 : (X_1 \to (Y_1 \to X_1))\) (fit)
2. \(s : X_s\) (Hyp)
3. \(c_1 \cdot s : (Y_1 \to X_1)\) (*A2)
4. \(c_2 : (((X_2 \to (Y_2 \to Z_2)) \to ((X_2 \to Y_2) \to (X_2 \to Z_2)))\) (fit)
5. \(c_2 \cdot (c_1 \cdot s) : ((X_2 \to Y_2) \to (X_2 \to Z_2))\) (*A2)
6. \(t : X_t\) (Hyp)
7. \((c_2 \cdot (c_1 \cdot s)) \cdot t : H\) (*A2)

To make the applications of the rule \(*\text{A2}\) work in lines 3, 5, and 7, the unification variables have to satisfy the following equations:

\[
\begin{align*}
X_1 &= X_s & \text{from 3.} \\
X_2 &= (Y_2 \to Z_2) &= Y_1 \to X_1 & \text{from 5.} \\
X_2 &= Y_2 &= X_t & \text{from 7.} \\
X_2 &= Z_2 &= H & \text{from 7.}
\end{align*}
\]

By (2) and (3), \(X_s = X_1 = Y_2 \to Z_2.\) This equation combined with (4) and (5) shows that \(H\) is indeed an implication that follows by HS from \(X_t\) and \(X_s,\) justified by \(t\) and \(s\) respectively.

**Lemma 18 (Stripping \(k\) conjunctions).** For any integer \(k \geq 0\) there exists a term \(t_k\) of size \(O(k)\) that encodes the operation of stripping \(k\) conjunctions, i.e.,

\[
\text{rJL}_{\text{CS}} \vdash t_k : D \iff \text{D = } H \to C, \text{ where } C \text{ is a k-conjunct of } H.
\]

**Proof.** We prove by induction on \(k\) that the conditions are satisfied for

\[
t_0 = (c_2 \cdot c_1) \cdot c_1 , \\
t_{k+1} = \text{syl}(c_{A1,A2,t_k}).
\]

Since \(|t_{0+1}| = |t_k| + |c_{A1,A2}| + O(1) = |t_k| + O(1),\) it is clear that \(|t_k| = |t_0| + kO(1) = O(k).\)

**Base case;** \(k = 0.\) (\(\iff\)). If \(C\) is a 0-conjunct of \(H,\) then \(H = C,\) and it is easy to see that \(t_0\) corresponds to the standard derivation of the tautology \(C \to C\) from propositional axioms (cf. combinator \(\text{skk}\)).

(\(\implies\)). Any \(*\)-derivation of \(t_0 : D\) must have the following key elements:

1. \(c_2 : ((X_2 \to (Y_2 \to Z_2)) \to ((X_2 \to Y_2) \to (X_2 \to Z_2)))\) (fit)
2. \(c_1 : (X_1 \to (Y_1 \to X_1))\) (fit)
3. \(c_2 \cdot c_1 : ((X_2 \to Y_2) \to (X_2 \to Z_2))\) (*A2)
4. \(c_1 : (X_3 \to (Y_3 \to X_3))\) (fit)
5. \((c_2 \cdot c_1) \cdot c_1 : D\) (*A2)

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For \( A_2 \) from line 5 to be valid, it is necessary that \( D = X_2 \rightarrow Z_2 \). It follows from \( A_2 \) in line 3 that \( X_2 \rightarrow (Y_2 \rightarrow Z_2) = X_1 \rightarrow (Y_1 \rightarrow X_1) \), in which case \( X_2 = X_1 = Z_2 \). Therefore, \( D = X_2 \rightarrow X_2 \), which is an implication from a formula to its 0-conjunct.

**Induction step.** (\( \Leftarrow \)). Let \( H \) be a formula with a \((k + 1)\)-conjunct \( C \). Then \( H \) must be of the form \( H_1 \land H_2 \) with \( C \) being a \( k \)-conjunct of \( H_i \) for some \( i = 1, 2 \). By the induction hypothesis, \( \mathcal{L}_{CS} \vdash t_k : (H_i \rightarrow C) \) for this \( i \). For both \( i = 1 \) and \( i = 2 \) \( \mathcal{L}_{CS} \vdash (c_{A_1,A_2}) : (H \rightarrow H_i) \). Then, by Lemma 17, \( \mathcal{L}_{CS} \vdash t_{k+1} : (H \rightarrow C) \).

(\( \Rightarrow \)). By the induction hypothesis, \( t_k \) justifies only implications from a formula to one of its \( k \)-conjuncts. Since \( \mathcal{L}_{CS} \) is fitting, \( c_{A_1,A_2} \) justifies only implications from a formula to one of its 1-conjuncts. By Lemma 17, \( t_{k+1} \) justifies only hypothetical syllogisms obtained from the latter and the former, but a \( k \)-conjunct of a 1-conjunct of a formula is its \((k + 1)\)-conjunct.

\[ \square \]

**Lemma 19.** For any term \( s \) and any integer \( l \geq 0 \) there exists a term \( \text{conj}(s,l) \) of size \( O(|s|2^l) \) with the following property:

\[ \mathcal{L}_{CS} \vdash \text{conj}(s,l) : D \iff D = B \rightarrow C_1 \land \cdots \land C_{2^l} \text{ such that } \mathcal{L}_{CS} \vdash s : (B \rightarrow C_i) \text{ for all } i = 1, \ldots, 2^l. \]

**Proof.** We prove by induction on \( l \) that the conditions are satisfied for

\[ \text{conj}(s,0) = \text{syll}(s,t_0), \]

\[ \text{conj}(s,l+1) = (c_2 \cdot \text{syll}(%(s,l),c_\lambda)) \cdot \text{conj}(s,l). \]

It is not hard to see that \(|\text{conj}(s,l)| = 2^l(|s| + K + L) = L\), where \( K \) and \( L \) are constants such that \(|\text{conj}(s,0)| = |s| + K \) and \(|\text{conj}(s,l+1)| = 2|\text{conj}(s,l)| + L\).

**Base case, \( l = 0 \).** (\( \Leftarrow \)). For any formula \( C \), \( \mathcal{L}_{CS} \vdash t_0 : (C \rightarrow C) \) by Lemma 18. Then, by Lemma 17, \( \mathcal{L}_{CS} \vdash s : (B \rightarrow C) \) implies \( \mathcal{L}_{CS} \vdash \text{syll}(s,t_0) : (B \rightarrow C) \).

(\( \Rightarrow \)). By Lemma 17, \( \text{syll}(s,t_0) \) justifies only implications \( B \rightarrow C \) for which there exists a formula \( A \) such that \( \mathcal{L}_{CS} \vdash s : (B \rightarrow A) \) and \( \mathcal{L}_{CS} \vdash t_0 : (A \rightarrow C) \). By Lemma 18, the latter implies \( A = C \). Therefore, \( \mathcal{L}_{CS} \vdash s : (B \rightarrow C) \).

**Induction step.** (\( \Rightarrow \)). Let \( H = C_1 \land \cdots \land C_{2^l} \) with \( \mathcal{L}_{CS} \vdash s : (B \rightarrow C_i) \) for all its \((l + 1)\)-conjuncts \( C_i \). Then \( H = H_1 \land H_2 \), where \( C_1, C_2, \ldots, C_{2^l} \) are \( l \)-conjuncts of \( H_1 \) and \( C_{2^l+1}, C_{2^l+2}, \ldots, C_{2^{l+1}} \) are \( l \)-conjuncts of \( H_2 \). By the induction hypothesis,

\[ \mathcal{L}_{CS} \vdash \text{conj}(s,l) : (B \rightarrow H_1), \]

\[ \mathcal{L}_{CS} \vdash \text{conj}(s,l) : (B \rightarrow H_2). \]

In addition, \( \mathcal{L}_{CS} \vdash c_\lambda : (H_1 \rightarrow (H_2 \rightarrow H_1 \land H_2)) \); in other words,

\[ \mathcal{L}_{CS} \vdash c_\lambda : (H_1 \rightarrow (H_2 \rightarrow H)). \]

From (8) and (6) by Lemma 17, for \( s' = \text{syll}(\text{conj}(s,l),c_\lambda) \) we have

\[ \mathcal{L}_{CS} \vdash s' : (B \rightarrow (H_2 \rightarrow H)). \]

\[ ^{11} \text{Note that, in general, } \text{conj}(s,0) = s \text{ does not satisfy the } \Rightarrow \text{-direction.} \]
Then, from (7) and \( r_{\mathcal{L}_{CS}} \vdash c_2::((B \rightarrow (H_2 \rightarrow H)) \rightarrow ((B \rightarrow H_2) \rightarrow (B \rightarrow H))) \):

\[
\begin{align*}
\mathcal{L}_{CS} \vdash c_2 \cdot s'::((B \rightarrow H_2) \rightarrow (B \rightarrow H)) & \quad \text{and, finally,} \\
\mathcal{L}_{CS} \vdash (c_2 \cdot s') \cdot \text{conj}(s, l)::(B \rightarrow H)
\end{align*}
\]

It remains to note that \( \text{conj}(s, l + 1) = (c_2 \cdot s') \cdot \text{conj}(s, l) \).

(\( \Rightarrow \)). By Lemma 17, the rule

\[
\frac{t:(A \rightarrow B) \quad s:(B \rightarrow C)}{syl(t, s):(A \rightarrow C)} \quad (\text{Syl})
\]

is admissible in both \(*\)-calculi. So any \(*\)-derivation of \( \text{conj}(s, l + 1): D \) must contain the following key elements (we have already incorporated the induction hypothesis about \( \text{conj}(s, l) \) as well as Lemma 17):

1. \( \text{conj}(s, l)::(B \rightarrow C_1 \land C_2 \land \cdots \land C_{2^l}) \) (IH)
2. \( c_1::(X \rightarrow (Y \rightarrow X \land Y)) \) (fit)
3. \( s'::(B \rightarrow (Y \rightarrow X \land Y)) \) (Syl)
4. \( c_2::((X_2 \rightarrow (Y_2 \rightarrow Z_2)) \rightarrow ((X_2 \rightarrow Y_2) \rightarrow (X_2 \rightarrow Z_2))) \) (fit)
5. \( c_2 \cdot s'::((X_2 \rightarrow Y_2) \rightarrow (X_2 \rightarrow Z_2)) \) (*A2)
6. \( \text{conj}(s, l)::(B' \rightarrow C_{2^{l+1}} \land C_{2^{l+2}} \land \cdots \land C_{2^{l+1}}) \) (IH)
7. \( (c_2 \cdot s') \cdot \text{conj}(s, l)::D \) (*A2)

where \( r_{\mathcal{L}_{CS}} + s::(B \rightarrow C_i) \) and \( r_{\mathcal{L}_{CS}} + s::(B' \rightarrow C_{2^i}) \) for \( i = 1, \ldots, 2^l \). Let us collect all unification equations necessary for this to be a valid fragment of a \(*\)-derivation:

\[
\begin{align*}
C_1 \land C_2 \land \cdots \land C_{2^l} &= X_\lambda & \text{from 3.} \\
B \rightarrow (Y \rightarrow X \land Y) &= X_2 \rightarrow (Y_2 \rightarrow Z_2) & \text{from 5.} \\
B' \rightarrow C_{2^{l+1}} \land C_{2^{l+2}} \land \cdots \land C_{2^{l+1}} &= X_2 \rightarrow Y_2 & \text{from 7.} \\
X_2 \rightarrow Z_2 &= D & \text{from 7.}
\end{align*}
\]

By (10) and (11), \( B = X_2 = B' \). Thus, \( r_{\mathcal{L}_{CS}} + s::(B \rightarrow C_i) \) for \( i = 1, \ldots, 2^{l+1} \). Also

\[
Y_\lambda = Y_2 = C_{2^{l+1}} \land C_{2^{l+2}} \land \cdots \land C_{2^{l+1}},
\]

again by (10) and (11). So, by (9) and (10),

\[
Z_2 = X_\land \land Y_\lambda = (C_1 \land C_2 \land \cdots \land C_{2^l}) \land (C_{2^{l+1}} \land C_{2^{l+2}} \land \cdots \land C_{2^{l+1}}).
\]

By (12), \( D \) is indeed an implication from \( B \) to this balanced conjunction for all of whose \((l + 1)\)-conjuncts the term \( s \) justifies their entailment from \( B \).

\[
\square
\]

In the following, a 1-disjunct is defined analogously to a 1-conjunct.

**Lemma 20.** For the term \( \text{disj} = c_{v_1\lor v_2} \) of size \( O(1) \),

\[
r_{\mathcal{L}_{CS}} + \text{disj}::D \iff D = B \rightarrow H, \text{ where } B \text{ is a 1-disjunct of } H.
\]

**Proof.** Easily follows from the fact that the reflected fragment is fitting. \[ \square \]
4. Reduction from Vertex Cover, Part I

We now use the justification terms from the previous section to build a polynomial-time many-one reduction from BVC to a fitting reflected fragment \( r\mathcal{L}_{CS} \).

**Lemma 21.** Let a term of size \( O(k^2) \) be defined by

\[ t_{k-l} = \text{conj}(t_k, l) . \]

For any binary exponential graph \( G = (V, E) \) with \( |V| = 2^k \) and any set \( C \subseteq V \) of size \( 2^l \),

\[ r\mathcal{L}_{CS} \vdash t_{k-l} : (F_V \rightarrow F_C) . \]

**Proof.** \( |\text{conj}(t_k, l)| = O(2^{k^2}) = O(k^2) \).

All \( l \)-conjuncts \( p_i \) of \( F_C \), where \( i \in C \), must be \( k \)-conjuncts of \( F_V \). Thus, for any of them by Lemma 18, \( r\mathcal{L}_{CS} \vdash t_k : (F_V \rightarrow p_i) \). Now, by Lemma 19, we have \( r\mathcal{L}_{CS} \vdash \text{conj}(t_k, l) : (F_V \rightarrow F_C) \). \( \square \)

**Lemma 22.** Let a term of size \( O(l) \) be defined by

\[ t_{l\text{-edge}} = \text{syl}(t_l, \text{disj}) . \]

For any binary exponential graph \( G = (V, E) \), any set \( C \subseteq V \) of size \( 2^l \), and any edge \( e \in E \),

\[ r\mathcal{L}_{CS} \vdash t_{l\text{-edge}} : (F_C \rightarrow F_e) \iff \text{e is covered by C}. \]

**Proof.** \( |\text{syl}(t_l, \text{disj})| = |t_l| + |\text{disj}| + O(1) = O(l) + O(1) = O(l) \).

(\( \Leftarrow \)). If \( i \in e \cap C \) is the vertex in \( C \) that covers \( e \), then \( p_i \) is a 1-disjunct of \( F_e \), so \( r\mathcal{L}_{CS} \vdash \text{disj} : (p_i \rightarrow F_e) \) by Lemma 20. But \( p_i \) is also an \( l \)-conjunct of \( F_C \), so, by Lemma 18, \( r\mathcal{L}_{CS} \vdash t_k : (F_C \rightarrow p_i) \). Finally, \( r\mathcal{L}_{CS} \vdash \text{syl}(t_l, \text{disj}) : (F_C \rightarrow F_e) \) by Lemma 17.

(\( \Rightarrow \)). If \( C \) does not cover \( e \), it is easy to see that \( F_C \rightarrow F_e \) is not valid propositionally. All justification logics are conservative over classical propositional logic, therefore \( \mathcal{L}_{CS} \nvDash F_C \rightarrow F_e \). By Theorem 9, \( r\mathcal{L}_{CS} \nvDash s : (F_C \rightarrow F_e) \) for any term \( s \). \( \square \)

**Lemma 23.** Let a term of size \( O(2^m) \) be defined by

\[ s_{l\text{-edge}} = \text{conj}(t_{l\text{-edge}}, m) . \]

For any binary exponential graph \( G = (V, E) \) with \( |E| = 2^m \) and any set \( C \subseteq V \) of size \( 2^l \),

\[ r\mathcal{L}_{CS} \vdash s_{l\text{-edge}} : (F_C \rightarrow F_G) \iff \text{C is a vertex cover for G}. \]

**Proof.** \( |\text{conj}(t_{l\text{-edge}}, m)| = O(2^{l\text{-edge}}2^m) = O(2^{2^m}) \).

(\( \Leftarrow \)). If \( C \) is a vertex cover, then \( r\mathcal{L}_{CS} \vdash t_{l\text{-edge}} : (F_C \rightarrow F_C) \) for all \( e \in E \), by Lemma 22. All \( m \)-conjuncts of \( F_G \) are \( F_e \)'s with \( e \in E \). Hence, by Lemma 19, we have \( r\mathcal{L}_{CS} \vdash \text{conj}(t_{l\text{-edge}}, m) : (F_C \rightarrow F_G) \).

(\( \Rightarrow \)). If \( C \) is not a vertex cover, by Lemma 15.3, formula \( F_C \rightarrow F_G \) is not valid propositionally. The same argument as in the previous lemma shows that for any term \( s \)

\[ r\mathcal{L}_{CS} \nvDash s : (F_C \rightarrow F_G) . \]

\( \square \)
Lemma 17. A vertex cover of size 2

Proof. By Lemma 21, \( \text{rJL}_{\text{CS}} \vdash t_{k-l-m} : (F_V \rightarrow F_G) \).

Note that the term \( t_{k-l-m} \) depends only on size 2 of a vertex cover and on how many vertices and edges \( G \) has.

5. Reduction from Vertex Cover, Part II

To finish the polynomial-time reduction from BVC to any fitting reflected fragment \( \text{rJL}_{\text{CS}} \) it now remains to prove the other direction:

\[ \text{rJL}_{\text{CS}} \vdash t_{k-l-m} : (F_V \rightarrow F_G) \iff G \text{ has a vertex cover of size } \leq 2^l. \]

Lemma 25 (Converse to Lemma 21).

\[ \text{rJL}_{\text{CS}} \vdash t_{k-l} : H \implies H = B \rightarrow D, \text{ where } D \text{ is a balanced conjunction of depth } \geq 1 \text{ whose all } l\text{-conjuncts are } k\text{-conjuncts of } B. \]

Proof. By definition, \( t_{k-l} = \text{conj}(t_k, l) \), so by Lemma 19, it justifies only implications \( B \rightarrow C_1 \land \cdots \land C_{2^l} \) with \( \text{rJL}_{\text{CS}} \vdash t_k : (B \rightarrow C_i) \) for \( i = 1, \ldots, 2^l \). By Lemma 18, the term \( t_k \) justifies only implications from a formula to its \( k\text{-conjuncts}. \)

Lemma 26 (Converse to Lemma 22).

\[ \text{rJL}_{\text{CS}} \vdash t_{l\text{-edge}} : H \implies H = B \rightarrow D_1 \lor D_2, \text{ where either } D_1 \text{ or } D_2 \text{ is an } l\text{-conjunct of } B. \]

Proof. By definition, \( t_{l\text{-edge}} = \text{syl}(t_l, \text{disj}) \). By Lemma 17, \( H \) can only be an implication \( B \rightarrow D \) such that \( \text{rJL}_{\text{CS}} \vdash t_l : (B \rightarrow C) \) and \( \text{rJL}_{\text{CS}} \vdash \text{disj} : (C \rightarrow D) \) for some formula \( C \). By Lemma 20, the latter statement implies that \( D = D_1 \lor D_2 \) with \( C = D_i \) for some \( i = 1, 2 \). By Lemma 18, \( D_i \) is an \( l\text{-conjunct of } B. \)

Lemma 27 (Converse to Lemma 23).

\[ \text{rJL}_{\text{CS}} \vdash s_{l-m} : H \implies H = B \rightarrow (C_1 \lor D_1) \land \cdots \land (C_{2^m} \lor D_{2^m}), \text{ where either } C_i \text{ or } D_i \text{ is an } l\text{-conjunct of } B \text{ for each } i = 1, \ldots, 2^m. \]
Proof. By definition, \( s_{l,m} = \text{conj}(t_{l,\text{edge}}, m) \). By Lemma 19, \( H \) must be an implication from some formula \( B \) to a balanced conjunction of depth \( \geq m \) such that, for all its \( m \)-conjuncts \( F \), \( rJL_{CS} \vdash t_{l,\text{edge}} : (B \to F) \). By Lemma 26, each of these \( m \)-conjuncts must be a disjunction with one of its 1-disjuncts being an \( l \)-conjunct of \( B \). \qed

**Theorem 28** (Converse to Theorem 24).

\[
rJL_{CS} \vdash t_{k-l,m} : H \implies H = B \to (C_1 \lor D_1) \land \cdots \land (C_{2^m} \lor D_{2^m}) \]

and there is a size \( \leq 2^l \) set \( X \) of \( k \)-conjuncts of \( B \) with either \( C_i \in X \) or \( D_i \in X \) for each \( i = 1, \ldots, 2^m \).

Proof. By definition, \( t_{k-l,m} = syl(t_{k-l}, s_{l,m}) \). By Lemma 17, \( H = B \to F \) with (a) \( rJL_{CS} \vdash t_{k-l} : (B \to Q) \), (b) \( rJL_{CS} \vdash s_{l,m} : (Q \to F) \) for some formula \( Q \). From (a), by Lemma 25, \( Q \) must be a conjunction \( Q_1 \land \cdots \land Q_{2^m} \) such that all its \( l \)-conjuncts \( Q_i \) are also \( k \)-conjuncts of \( B \). So the set \( X = \{ Q_i \mid i = 1, \ldots, 2^l \} \) has size \( \leq 2^l \) (because of possible repetitions) and consists of \( k \)-conjuncts of \( B \). It now follows from (b), by Lemma 27, that \( F = (C_1 \lor D_1) \land \cdots \land (C_{2^m} \lor D_{2^m}) \) with either \( C_i \) or \( D_i \) being an \( l \)-conjunct of \( Q \) for each \( i = 1, \ldots, 2^m \), i.e., with either \( C_i \in X \) or \( D_i \in X \) for each \( i = 1, \ldots, 2^m \). \qed

**Theorem 29.** For any binary exponential graph \( G = (V, E) \) with \( |V| = 2^k \) and \( |E| = 2^m \) and any integer \( 0 \leq l \leq k \),

\[
rJL_{CS} \vdash t_{k-l,m} : (F_V \to F_G) \iff G \text{ has a vertex cover of size } \leq 2^l.
\]

Proof. The \( \iff \)-direction was proved in Theorem 24. We now prove the \( \implies \)-direction. \( F_V \to F_G \) already has the form prescribed by Theorem 28. The only \( k \)-conjuncts of \( F_V \) are the sentence letters \( p_1, \ldots, p_{2^m} \). Therefore, there must exist a set \( X \) of \( \leq 2^l \) of these sentence letters such that for each \( m \)-conjunct \( F_e \) of \( F_G \) at least one of the 1-disjuncts of \( F_e \), i.e., either \( p_{\tau_1(e)} \) or \( p_{\tau_2(e)} \), is in \( X \). This literally means that \( G \) has a set of \( \leq 2^l \) vertices that covers all the edges of \( G \). \qed

6. Lower Bounds for Reflected Fragments

**Theorem 30.** For any fitting reflected fragment \( rJL_{CS} \), derivability in \( rJL_{CS} \) is NP-hard.

Proof. It is easy to see that both \( F_V \) and \( F_G \) have size polynomial in the size of \( G \). As for the term \( t_{k-l,m} \), it was shown in Theorem 24 that \( |t_{k-l,m}| = O(k2^l) + O(2^m) \), which is polynomial in the size of \( G \) provided \( l \leq k \) (BVC for \( l > k \) is trivial). Thus, Theorem 29 shows that \( rJL_{CS} \) is NP-hard. \qed

It is time now to reap the fruits of the preceding theorem by showing that a wide range of constant specifications produce fitting reflected fragments.

In the following proof, we need to perform operations on schemes of formulas rather than on individual formulas. Thus, it is convenient to represent axiom schemes using the Substitution Rule:

\[
\frac{X}{X\sigma}.
\]

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where $\sigma$ is any substitution of formulas for sentence letters (see, for instance, the formulation of classical propositional logic in [14, Sect. 1.3]). In justification logics, we additionally have to allow substitutions $\sigma$ to replace justification variables with justification terms.

The Substitution Rule allows to make axiomatizations finite because each axiom scheme can be replaced by a single axiom $A$ such that each of infinitely many instances of the axiom scheme is a substitution instance of $A$. Note that in general we cannot use this representation to define $JL_{CS}$ because $CS$ need not be schematic. It is easy to see that

**Lemma 31 (Substitution Property, [3, 4, 5]).** The Substitution Rule is admissible for a justification logic $JL_{CS}$, and hence for $rJL_{CS}$, iff $CS$ is schematic.

Strictly speaking, we presented axiom schemes (e.g., for LP) using variables over formulas and variables over terms, e.g., $t : F \rightarrow F$ is understood in the sense that it is an axiom for any term $t$ and any formula $F$. Each axiom scheme written in this way can be easily converted to an axiom in the corresponding system with the Substitution Rule by replacing distinct variables over formulas by distinct sentence letters and distinct variables over terms by distinct justification variables, e.g., the scheme $t : F \rightarrow F$ becomes a formula $x : p \rightarrow p$. The latter will be called a most general instance (mgi) of the former (note that an mgi is not unique: the choice of sentence letters and justification variables plays no role).

By analogy with axiom schemes, a scheme of formulas with an mgi $F$ is the set

$$\{F\sigma \mid \sigma \text{ is a substitution} \} .$$

**Lemma 32.** Let $JL \in \{J, JD, JT, J4, JD4, LP, T_nLP, S4_nLP, S5_nLP\}$. Any schematically injective and axiomatically appropriate constant specification $CS$ for $JL$ yields a fitting reflected fragment $rJL_{CS}$.

**Proof.** All formulas that fit the five patterns from (1) can be broken into seven schemes of propositional tautologies with mgi’s

\[
\begin{align*}
  p & \rightarrow (q \rightarrow p) , \\
  (p \rightarrow (q \rightarrow r)) & \rightarrow ((p \rightarrow q) \rightarrow (p \rightarrow r)) , \\
  p_1 \land p_2 & \rightarrow p_1 , \\
  p_1 \land p_2 & \rightarrow p_2 , \\
  p & \rightarrow (q \rightarrow p \land q) , \\
  p_1 & \rightarrow p_1 \lor p_2 , \\
  p_2 & \rightarrow p_1 \lor p_2 ,
\end{align*}
\]

where $p$, $q$, $r$, $p_1$, and $p_2$ are distinct sentence letters (strictly speaking, we should have used a distinct set of sentence letters for each mgi). Let $A$ stand for any of these seven mgi’s. For each $JL$, its axiomatization contains $A1$, i.e., a full axiomatization of classical propositional logic. Therefore, the propositional tautology $A$ is a theorem of $JL_{CS}$. Since $CS$ is axiomatically appropriate, by Lemma 4, there exists a term $s,$
which contains neither + nor any justification variables, such that \( \mathcal{J}_{CS} \vdash s : A \), and hence \( \mathcal{J}_{CS} \vdash s : A \). By the Substitution Property (Lemma 31), \( \mathcal{J}_{CS} \vdash s : (A \sigma) \) for any substitution \( \sigma \). In other words, the term \( s \) satisfies (1) in the \( \leftarrow \rightarrow \)-direction for the respective axiom scheme.

For the \( \Rightarrow \)-direction, it is sufficient to note that for any +-free ground term \( t \) the set
\[
CS(t) = \{ F \mid \mathcal{J}_{CS} \vdash t : F \}
\]
is either empty or a scheme whose mgi we will denote by \( A_t \). This statement can be proved by induction on the size of \( t \). For constants, it is guaranteed by the schematic injectivity of \( CS \). Justification variables do not occur in ground terms. If \( CS(t') \) is empty, so is \( CS(!t') \). Otherwise,

- for logics with \( *_{CS} \) as their \( * \)-calculus,

\[
CS(!t') = \{ t' : F \mid F \in CS(t') \} =_{IH}
\]

\[
\{ t' : (A_t \sigma) \mid \sigma \text{ is a substitution} \} = \{ (t' : A_t) \sigma \mid \sigma \text{ is a substitution} \}. \tag{20}
\]

The last equality follows from the fact that \( t' \) does not contain variables. Thus, in this case \( A_{t'} = t' : A_t \).

- In the logics with \( *_{CS} \) as their \( * \)-calculus, for \( t' = \overbrace{\ldots \ldots c}^{n} \), \( n \geq 0 \),

\[
CS(!t) = \{ \overbrace{\ldots \ldots c}^{n} : \ldots : c : c : A : c : A \in CS \} =
\]

\[
\{ \overbrace{\ldots \ldots c}^{n} : \ldots : c : c : (A_t \sigma) \mid \sigma \text{ is a substitution} \} =
\]

\[
\{ \overbrace{\ldots \ldots c}^{n} : \ldots : c : c : (A_t) \sigma \mid \sigma \text{ is a substitution} \},
\]

so that \( A_{t'} = \overbrace{\ldots \ldots c}^{n} : \ldots : c : c : A_{c} \), where the existence of \( A_{c} \) is guaranteed by the schematic injectivity of \( CS \). For all other terms, \( CS(!t') = \emptyset \) independent of \( CS(t') \).

Finally,
\[
CS(t_1 \cdot t_2) = \{ G \mid (\exists F)(F \rightarrow G \in CS(t_1) \text{ and } F \in CS(t_2)) \} =_{IH}
\]

\[
\{ G \mid (\exists F)(\exists \sigma_1)(\exists \sigma_2)(F \rightarrow G = A_{t_1} \sigma_1 \text{ and } F = A_{t_2} \sigma_2) \}. \tag{21}
\]

It follows from Theorem 9 that \( A_{t} \) cannot be a single sentence letter. Clearly, if the main connective of \( A_{t} \) is not an implication, then \( CS(t_1 \cdot t_2) = \emptyset \). It remains to consider the case \( A_{t} = B \rightarrow C \). If \( B \) cannot be unified with \( A_{t_2} \), then \( CS(t_1 \cdot t_2) = \emptyset \). Otherwise, there must exist a most common unifier (mgu) \( \tau = \text{mgu}(B, A_{t_2}) \). Any formula \( F \) in (21) must be a substitution instance of both \( B \) and \( A_{t_2} \). Hence there must exist a substitution \( \sigma \) such that \( F = B \tau \sigma = A_{t_2} \tau \sigma \). Accordingly, any formula \( G \in CS(t_1 \cdot t_2) \) must
have the form $C \tau \sigma$. It follows that $CS(t_1 \cdot t_2) = \{C \tau \sigma \mid \sigma \text{ is a substitution}\}$. Thus, in this case, $A_{t_1t_2} = C \tau = C \operatorname{mgu}(B, A_{t_1})$. Clearly, the operation $\cdot$, which enables us to combine several different schemes, would have broken this pattern, but it does not occur in $t$.

Thus, our term $s$ must justify some scheme, of which the formula $A$ is an instance, i.e., $A = A_{r} \tau \sigma$ for some substitution $\sigma$. It can be checked that, if $B \tau \sigma = A$ and $B$ is a tautology, then $B = A$. Hence, $A_{r} = A$ by Theorem 9.

Therefore, the ground term $s$ justifies exactly the scheme with $\operatorname{mgi} A$. This discussion shows that there exist terms $c_1$, $c_2$, and $c_3$ that justify exactly the schemes with $\operatorname{mgi}$’s (13), (14), and (17) respectively, as well as terms $c_{A1}$, $c_{A2}$, $c_{v1}$, and $c_{v2}$ for the schemes with $\operatorname{mgi}$’s (15), (16), (18), and (19) respectively. It remains to note that the term $c_{v1} + c_{v2}$ satisfies all the requirements of $c_{v1}, v2$ and the term $c_{A1} + c_{A2}$ fits the role of $c_{A1}, A2$.

**Theorem 33.** Let $CS$ be a schematically injective and axiomatically appropriate constant specification for $JL \in \{J, JD, JT, J4, JD4, LP, T_sLP, S4_sLP, S5_sLP\}$. Then derivability in $rJL_{CS}$ is NP-complete.

**Proof.** It was proved in [18, 21] that $rJL_{CS}$ is in NP. By Lemma 32, $rJL_{CS}$ is fitting. Thus, by Theorem 29, $rJL_{CS}$ is NP-hard. □

7. **Reflected Justification Logics with Hypotheses**

The goal of this section is to extend the $*$-calculi to situations where $rJL$ is augmented with additional axioms. This will be important for the proof of Theorem 44 in the next section that shows the $\Pi_2^P$-hardness of the Derivability Problems for pure justification logics.

Some proofs in this section will be semantic. Accordingly, we introduce the simplest semantics for pure justification logics, that of symbolic models, also called Mkrtchyan models or simply $M$-models. This semantics was first introduced for LP by Alexey Mkrtchyan in [25] and extended to other pure justification logics in [19].

**Definition 34.** Let $CS$ be a constant specification for a pure justification logic $JL \in \{J, JD, JT, J4, JD4, LP\}$. An $M$-model for $JL_{CS}$ is a pair $\mathcal{M} = (V, \mathcal{A})$, where $V$ is a propositional valuation and $\mathcal{A}$ is an admissible evidence function for $JL_{CS}$. Informally, an admissible evidence function specifies for each term $t$ and formula $F$ whether $t$ is considered admissible evidence for $F$. If $\mathcal{A}(t, F) = \text{True}$, we say that $\mathcal{A}$ satisfies $t : F$.

Being satisfied by $\mathcal{A}$ is one of the criteria necessary for $t : F$ to hold in an $M$-model.

Formally, a function $\mathcal{A} : Tm \times Fm \rightarrow \{\text{True, False}\}$ is called an admissible evidence function for a justification logic $JL_{CS}$ iff it is closed under deduction in the $*$-calculus for the reflected fragment $rJL_{CS}$ (see Table 2). That is to say, if an admissible evidence function $\mathcal{A}$ satisfies a set $X$ of justification assertions and $X \vdash s : G$ in the respective $*$-calculus, then $\mathcal{A}$ must also satisfy $s : G$. In addition, if $JL \in \{JD, JD4\}$, an admissible evidence function for $JL_{CS}$ must satisfy the following condition: $\mathcal{A}(t, \bot) = \text{False}$ for
all terms $t$. We will use $\mathcal{A}(t, F)$ as an abbreviation for $\mathcal{A}(t, F) = \text{True}$ and also $\neg\mathcal{A}(t, F)$ as an abbreviation for $\mathcal{A}(t, F) = \text{False}$.\footnote{N. Krupski and Mkrtychev used the notation $F \in \mathcal{A}(t)$ instead of $\mathcal{A}(t, F)$ and $F \notin \mathcal{A}(t)$ instead of $\neg\mathcal{A}(t, F)$.}

Finally, the truth relation $\mathfrak{M} \models H$ is defined as follows:

- $\mathfrak{M} \models P$ iff $V(P) = \text{True}$;
- Boolean connectives behave classically;

$$\mathfrak{M} \models t : F \text{ iff } \begin{cases} \mathfrak{M} \models F \text{ and } \mathcal{A}(t, F) & \text{if } JL \in \{JT, LP\}, \\ \mathcal{A}(t, F) & \text{if } JL \in \{J, JD, J4, JD4\}. \end{cases}$$

Let $CS$ be a constant specification for a pure justification logic $JL$ and $\Gamma$ be any set of formulas. We write $JL_{CS}(\Gamma)$ to denote the closure of $JL_{CS} \cup \Gamma$ under modus ponens. It is easy to verify that the deduction theorem holds for $JL_{CS}$, and hence we have that $JL_{CS}(\Gamma) \vdash A$ if and only if there exists a finite set $\Gamma_0 \subseteq \Gamma$ such that $JL_{CS} \vdash \bigwedge \Gamma_0 \rightarrow A$.

**Definition 35.** Suppose that every formula in $\Gamma$ has the form $t : A$, i.e., $\Gamma$ consists only of justification assertions. We define the following calculi:

$$*_{CS+1} \Gamma = *_{CS} + \Gamma \quad \text{and} \quad *^1_{CS+1} \Gamma = *^1_{CS} + \Gamma. \quad (22)$$

That is to say, in each case the set of axioms is extended by all justification assertions from $\Gamma$ while the rules remain the same and can be freely applied to the new axioms. When the type of a $*$-calculus and a particular $CS$ are clear from the context or when they can be arbitrary, we will use the term $*_{1}$-calculus.

It is natural to ask whether a given $*_{1}$-calculus can prove every formula in the reflected fragment of $JL_{CS}(\Gamma)$ for the respective $JL_{CS}$. Unfortunately, there are cases where this does not hold. As an example from Kuznets [21], consider the situation for $LP_{CS}$ where $\Gamma = \{c : p, c : \neg p\}$. Then, via the Factivity Axiom, $LP_{CS}(\Gamma)$ is inconsistent, whereas there are certainly justification assertions that cannot be proved in the $*^1_{CS+1} \Gamma$-calculus. Thus, we need additional restrictions on $\Gamma$. For this, we introduce the following

**Definition 36.** A set of justification assertions $\Gamma$ is called factive provided that, whenever $t : A \in \Gamma$, either (a) $A$ is of the form $s : B$ and $A \in \Gamma$ or (b) $A$ is a purely propositional\footnote{A purely propositional formula is one that does not contain any justification terms.} formula. The set of purely propositional formulas $A$ such that $t : A \in \Gamma$ for some term $t$ is called the propositional content of $\Gamma$, and is denoted $\text{Prop}(\Gamma)$. We call a factive set $\Gamma$ consistent provided $\text{Prop}(\Gamma)$ is (propositionally) consistent.

The next theorem generalizes N. Krupski’s Theorem 5.1 from [18].

**Theorem 37.** Let $\Gamma$ be a consistent factive set of justification assertions and $CS$ be a constant specification for a pure justification logic $JL \in \{J, JD, J4, JD4, LP\}$. Then, for any formula of the form $t : F$, we have

$$JL_{CS}(\Gamma) \vdash t : F \iff \vdash_{*_{1}} t : F$$

for the respective $*_{1}$-calculus.
Proof. The proof is similar to the proof of Theorem 5.1 from [18], which in turn uses constructions of Mkrtchyan [25]. The $\Longleftarrow$-direction follows from the fact that any $*_r$-derivation can be easily converted into a derivation in $\mathcal{L}_{CS}[\Gamma]$. Indeed, all axioms of the $*_r$-calculus are either instances of axiom internalization in $\mathcal{L}_{CS}$ or members of $\Gamma$ and hence axioms of $\mathcal{L}_{CS}[\Gamma]$. Each rule in $*_r$-calculus translates into the corresponding axiom of $\mathcal{L}$ followed by one or two applications of modus ponens.

We prove the $\Longrightarrow$-direction by showing its contrapositive. Suppose $*_r \nvdash t : F$. Let the function $\mathcal{A}_t : Tm \times Fm \to \{True, False\}$ be defined by

$$\mathcal{A}_t(s,G) \iff *_r \vdash s : G.$$  

For $\mathcal{L} \in \{\mathcal{J}, \mathcal{J}_D, \mathcal{J}_T\}$, whereby $*_r = *_{CS,T}$, it is clear that $\mathcal{A}_t$ is an admissible evidence function for $\mathcal{J}_{CS}$; similarly, for $\mathcal{L} \in \{\mathcal{J}_4, \mathcal{J}_D, \mathcal{L}_P\}$, when $*_r = *_{CS,T}$, we have that $\mathcal{A}_t$ is an admissible evidence function for $\mathcal{L}_{CS}$. Note that any constant specification for $\mathcal{J}$ or $\mathcal{J}_D$ can also serve as a constant specification for $\mathcal{J}_T$ because all axioms of $\mathcal{J}$ and $\mathcal{J}_D$ are also axioms of $\mathcal{J}_T$. Similarly, if a constant specification can be used for $\mathcal{J}_4$ or $\mathcal{J}_D$, it can also be used for $\mathcal{L}_P$. In either case, by definition $\mathcal{A}_t$ satisfies all justification assertions from $\Gamma$ but does not satisfy $t : F$ by our assumption.

Since $\Gamma$ is consistent, there exists a propositional valuation $V$ that satisfies Prop($\Gamma$). Consider the $\mathcal{L}$-model $\mathcal{M} = \langle V, \mathcal{A}_t \rangle$ for $\mathcal{L}_{CS}$ or for $\mathcal{L}_{CS}$ respectively. Note that $\mathcal{M} \models t : F$ since $\neg \mathcal{A}_t(t,F)$. In addition, for either $\mathcal{J}_{CS}$ or $\mathcal{L}_{CS}$ we can prove that $\mathcal{M} \models \Gamma$. Indeed, it is easy to show by induction on $k$ that $\mathcal{M} \models s_k : \ldots : s_1 : G$ for each $s_k : \ldots : s_1 : G \in \Gamma$, where $G$ is a purely propositional formula. The base case, $k = 1$, follows from $G \in \text{Prop}(\Gamma)$.

The existence of a $\mathcal{J}_{CS}$-model (an $\mathcal{L}_{CS}$-model) where all formulas from $\Gamma$ hold while $t : F$ is false shows that $\mathcal{J}_{CS}[\Gamma] \not\vdash t : F$ (respectively $\mathcal{L}_{CS}[\Gamma] \not\vdash t : F$). But every $\mathcal{J}_{CS}$- or $\mathcal{L}_{CS}$-derivation is also a $\mathcal{J}_{CS}$-derivation (for the same $\mathcal{C}_S$); similarly, any $\mathcal{J}_{CS}$- or $\mathcal{L}_{CS}$-derivation is also an $\mathcal{L}_{CS}$-derivation. Hence $\mathcal{L}_{CS}[\Gamma] \not\vdash t : F$. This completes the proof of Theorem 37.

By analogy with $r\mathcal{J}_{CS}$ we will denote the reflected fragment of $\mathcal{L}_{CS}[\Gamma]$

$$r\mathcal{L}_{CS}[\Gamma] = \{ t : F \mid \mathcal{L}_{CS}[\Gamma] \vdash t : F \}.$$  

As we proved, $r\mathcal{L}_{CS}[\Gamma]$ is axiomatized by its respective $*_r$-calculus. Note that the only difference between a $*_r$-calculus and its corresponding $*_r$-calculus is the addition of axioms $\Gamma$. Therefore, a reflected fragment $r\mathcal{L}_{CS}[\Gamma]$ is axiomatized by the same $*_r$-calculus as $r\mathcal{L}_{CS}$ as far as rules are concerned. Consequently, there are still only two sets of rules chosen based on whether full positive introspection holds in $\mathcal{L}$. The differences between these $*_r$-calcoli, as in the case of $r\mathcal{L}_{CS}$, is in their axioms.

As a consequence of the above construction, other results that N. Krupski [18] established for $\mathcal{L}_{CS}$ also hold for $\mathcal{L}_{CS}[\Gamma]$. First, by the minimality of the admissible evidence function $\mathcal{A}_t$, the disjunction property for formulas of the form $s : F \lor t : G$ holds for $\mathcal{L}_{CS}[\Gamma]$ (cf. Corollary 2 of [18]). Similarly, if $\mathcal{C}_S$ is schematic (and polynomially decidable) and $\Gamma$ is finite, then the Derivability Problem for a $*_r$-calculus is in NP for either of the calculi, i.e., $r\mathcal{L}_{CS}[\Gamma]$ is in NP. This is proved by a construction similar to the one used in the proof of Theorem 5.2 in [18], the main difference being that
derivations in $\text{rJL}_{\text{CS}}\{\Gamma\}$ correspond to $\text{rJL}_{\text{CS}}$-derivations from hypotheses $\Gamma$, whereas N. Krupski considered only derivations without hypotheses.

For us, the importance of Theorem 37 lies in the fact that the results of Sects. 3–5 translate to $\text{rJL}_{\text{CS}}\{\Gamma\}$ for a proper subclass of consistent factive sets $\Gamma$.

**Lemma 38.** Let $\text{CS}$ be a constant specification for a pure justification logic $\text{JL} \in \{\text{J}, \text{JD}, \text{JT}, \text{J4}, \text{JD4}, \text{LP}\}$ such that the reflected fragment $\text{rJL}_{\text{CS}}$ is fitting. Let $\Gamma$ be a consistent factive set of justification assertions such that the only terms that occur in $\Gamma$ are justification variables. Then Lemmas 17–20, 22, 23, 26, and 27 all still hold if $\text{rJL}_{\text{CS}}$ is uniformly replaced by $\text{rJL}_{\text{CS}}\{\Gamma\}$ in the statements of the lemmas.

**Proof.** Since any derivation in $\text{rJL}_{\text{CS}}$ is also a derivation in $\text{rJL}_{\text{CS}}\{\Gamma\}$, the proofs of the $\Leftarrow$-directions in all these lemmas do not require any changes. The $\Rightarrow$-directions also hold because the only terms that gain additional provably justified formulas in $\text{rJL}_{\text{CS}}\{\Gamma\}$ are those that contain justification variables from $\Gamma$, but no variables have been used for construction of the terms in the proofs of all these lemmas. \qed

### 8. A Lower Bound for Full Justification Logics

Sections 4 and 5 established a reduction from the Vertex Cover Problem to the Derivability Problem in a given reflected fragment thereby proving NP-hardness of the latter. In the present section, we extend the proof method and obtain stronger lower bounds for full (non-reflected) pure justification logics $\text{JL}_{\text{CS}}$.\textsuperscript{14} We first prove that a quantified version of the Vertex Cover Problem is $\Pi_2^p$-hard by reducing co-QSAT$_2$ to it. Then we reduce this Quantified Vertex Cover Problem to the Derivability Problem in a given justification logic.

**Definition 39.** By co-QSAT$_2$ we mean the following problem. Let $\varphi$ be any 3CNF formula, i.e., a propositional formula in conjunctive normal form with exactly three literals in each clause. Given such a $\varphi$ with its sentence letters partitioned into two sets $\vec{p} = \{p_1, \ldots, p_{|\vec{p}|}\}$ and $\vec{q} = \{q_1, \ldots, q_{|\vec{q}|}\}$, determine whether

$$\psi = (\forall p_1) \cdots (\forall p_{|\vec{p}|})(\exists q_1) \cdots (\exists q_{|\vec{q}|})\varphi$$

is true.

The following theorem is standard. Several of its slightly different variants can be found, for instance, in [26, 27, 28].

**Theorem 40.** co-QSAT$_2$ is $\Pi_2^p$-complete.

\textsuperscript{14}Applying this method to hybrid logics does not make sense since they are mostly at least PSPACE-hard by virtue of being conservative over the corresponding modal logic. As for $\text{SS}_1\text{LP}$, the only hybrid logic that may not be PSPACE-hard, its conservativity over LP would easily yield the lower bound that can be obtained by our method.
Let $\psi = (\forall \bar{p}) (\exists \bar{q}) (C_1 \land \ldots \land C_r)$ be a formula of type (23), where each $C_i$ is a 3-clause: $C_i = L_{i,1} \lor L_{i,2} \lor L_{i,3}$, $i = 1, \ldots, r$. Each literal $L_{i,z}$ must be $p_j$, $\neg p_j$, $q_j$, or $\neg q_j$ for some $j$.

Given $\psi$ we construct a graph $G_\psi = (V_\psi, E_\psi)$ with vertices labeled by literals (the construction is identical with the reduction of $3\text{SAT}$ to $\text{VC}$ as given in [17]). The graph is defined as follows:

- For each clause $C_i$, $i = 1, \ldots, r$, in $\psi$ we have a triangle of pairwise joined vertices $c_{i,1}$, $c_{i,2}$, and $c_{i,3}$ in $G_\psi$. Each vertex $c_{i,z}$ is labeled by the corresponding literal $L_{i,z}$. These are called clause vertices and clause edges.

- For each sentence letter $q_j$, there are two vertices $v_{j,0}$ and $v_{j,1}$ joined by an edge. The vertex $v_{j,0}$ is labeled with $q_j$ and $v_{j,1}$ is labeled with $\neg q_j$. These are called literal vertices and literal edges.

- For each sentence letter $p_j$, there are two vertices $u_{j,0}$ and $u_{j,1}$ joined by an edge. The vertex $u_{j,0}$ is labeled with $p_j$ and $u_{j,1}$ is labeled with $\neg p_j$. These are also called literal vertices and literal edges.

- A clause vertex and a literal vertex are joined by a connecting edge iff they are labeled by the same literal.

There are $3r + 2N$ vertices in $G_\psi$, where $N = |\bar{\bar{p}}| + |\bar{\bar{q}}|$; namely, $3r$ clause vertices and $2N$ literal vertices. Similarly, there are $6r + N$ edges in $G_\psi$; namely, $3r$ clause edges, $N$ literal edges, and $3r$ connecting edges.

As is argued in [17], $G_\psi$ has a vertex cover of size $\leq 2r + N$ iff $\varphi$ is satisfiable. First, any vertex cover of $G_\psi$ must have at least $2r + N$ vertices since a vertex cover must contain at least one vertex for each literal edge and at least two vertices from each clause triangle. Second, since any vertex cover $C$ of size $2r + N$ must contain exactly one literal vertex per literal edge in the graph, it is possible to define a propositional valuation $\tau_C$ by letting $\tau_C(L) = \text{True}$ for exactly those literals that label literal vertices from the vertex cover. It is not hard to see that this valuation $\tau_C$ satisfies $\varphi$. Conversely, if $\tau$ is any valuation that satisfies $\varphi$, then there exists a vertex cover $C$ of size $2r + N$ such that $\tau = \tau_C$.

**Definition 41.** Let $\pi$ denote a (partial) valuation with domain $\bar{\bar{p}}$. A vertex cover $C$ of $G_\psi$ is called its $\pi$-cover if $C$ contains all literal vertices labeled by literals from the set $\{p_j \mid \pi(p_j) = \text{True}\} \cup \{\neg p_j \mid \pi(p_j) = \text{False}\}$.

The above discussion yields the following proposition.

**Proposition 42.** A sentence $\psi$ as in (23) is true iff for every valuation $\pi$ with domain $\bar{\bar{p}}$, the graph $G_\psi$ has a $\pi$-cover of size $2r + N$.

In order to work with balanced conjunctions, we modify $G_\psi$ to transform the questions about the existence of $\pi$-covers into Binary Vertex Cover Problems. For this, we construct a graph $G'_\psi$ that has the following properties: (a) $G'_\psi$ has $2^k + 2|\bar{\bar{p}}|$ vertices, (b) $G'_\psi$ has $2^m$ edges, (c) the sought-for $\pi$-covers have size $2^k$, and (d) the size of $G'_\psi$
is linear in the size of \( \psi \). In effect, \( G'_{\psi} \) is a binary exponential graph, except that the vertices \( u_{j,0} \) and \( u_{j,1} \), labeled \( p_j \) and \( \neg p_j \) respectively, are not counted. The construction of \( G'_{\psi} \) from \( G_{\psi} \) mimics that from the proof of Theorem 13: to ensure (c), add extra pairs of vertices joined by edges; to ensure (b), add a “star”-shape as in Stage 2 of the proof of Theorem 13; then, to ensure (a), add extra isolated vertices. By construction, Proposition 42 now implies the following property of \( G'_{\psi} \):

**Proposition 43.** A sentence \( \psi \) as in (23) is true iff for every valuation \( \pi \) with domain \( \bar{p} \), the graph \( G'_{\psi} \) has a \( \pi \)-cover of size \( 2^l \).

We are now ready to prove the \( \Pi^P_2 \)-hardness of the Derivability Problem for \( JL_{CS} \).

**Theorem 44.** Let \( CS \) be a constant specification for a pure justification logic \( JL \in \{ JL, JD, JT, J4, JD4, LP \} \) such that the reflected fragment \( rJL_{CS} \) is fitting. Then the Derivability Problem for \( JL_{CS} \) is \( \Pi^P_2 \)-hard.

**Proof.** We prove the theorem by reduction from \( co\text{-}QSAT_2 \). Given a formula \( \psi \) as in (23), we construct the graph \( G'_{\psi} \) as described above and apply to this graph the encoding from Definition 14. We define a set \( \Gamma_{\psi} \) of formulas by

\[
\Gamma_{\psi} = \{ x: p_j \lor x: \neg p_j \mid j = 1, \ldots, |\bar{p}| \},
\]

where \( p_j \) is a sentence letter that corresponds to the literal vertex \( u_{j,0} \) and \( \neg p_j \) is a sentence letter that corresponds to the literal vertex \( u_{j,1} \). Intuitively, the sentence letter \( p_j \) in the encoding corresponds to the literal \( p_j \) in the formula \( \psi \) while the sentence letter \( \neg p_j \) corresponds to the literal \( \neg p_j \), which explains the chosen notation. We hope that the resulting small collision of notation — \( p_j \) is the sentence letter that encodes the literal vertex that corresponds to the literal \( p_j \) — will facilitate understanding rather than hinder it.

Let \( \gamma_{\psi} \) be the conjunction of the formulas in \( \Gamma_{\psi} \). (Unlike the other conjunctions we work with, \( \gamma_{\psi} \) need not be balanced.) Let \( V^0_{\psi} \) be the set of all vertices of \( G'_{\psi} \), and let \( V^\prime_{\psi} = V^0_{\psi} \setminus \{ u_{j,0}, u_{j,1} \mid j = 1, \ldots, |\bar{p}| \} \). Note that \( |V^\prime_{\psi}| = 2^k \) is a power of two. We define \( K_{\psi} \) to be

\[
K_{\psi} = \gamma_{\psi} \rightarrow t^*_{k \rightarrow l \rightarrow m}:(F_{V^\prime_{\psi}} \rightarrow F_{G'_{\psi}}),
\]

where a term \( t^*_{k \rightarrow l \rightarrow m} \) plays a role similar to \( t_{k \rightarrow l \rightarrow m} \) and is defined below. To prove Theorem 44 it will suffice to show that \( JL_{CS} \vdash K_{\psi} \) iff \( \psi \) is true.

By the deduction theorem, \( JL_{CS} \vdash K_{\psi} \) iff

\[
JL_{CS}(\Gamma_{\psi}) \vdash t^*_{k \rightarrow l \rightarrow m}:(F_{V^\prime_{\psi}} \rightarrow F_{G'_{\psi}}). \tag{24}
\]

For any valuation \( \pi \) with domain \( \bar{p} \), define

\[
V_{\pi} = \{ p_j \mid \pi(p_j) = \text{True} \} \cup \{ \neg p_j \mid \pi(p_j) = \text{False} \}
\]

and let \( \Gamma_{\psi,\pi} \) be the set of formulas \( \{ x: L \mid L \in V_{\pi} \} \). Note that for any valuation \( \pi \) with domain \( \bar{p} \) the set \( \Gamma_{\psi,\pi} \) is a finite consistent factive set of justification assertions and the only term that occurs in it is the justification variable \( x \). Hence, by Lemma 38, for any
valuation \( \pi \) with domain \( \bar{\varphi} \), Lemmas 17–20, 22, 23, 26, and 27 hold for \( \mathcal{C}_S[\Gamma_{\varphi,\pi}] \).

Consider the assertions

\[
\mathcal{C}_S[\Gamma_{\varphi,\pi}] \vdash t_{k-l-m}': (F_{V_{\bar{\varphi}}} \rightarrow F_{G_{\bar{\varphi}}}) .
\]

(25)

Clearly, (24) holds iff (25) holds for all \( \pi \). Thus, by Theorem 37 and Proposition 43, in order to prove Theorem 44, it will suffice to prove the following

**Lemma 45.** For all valuations \( \pi \) with domain \( \bar{\varphi} \),

\[
\mathcal{C}_S[\Gamma_{\varphi,\pi}] \vdash t_{k-l-m}': (F_{V_{\bar{\varphi}}} \rightarrow F_{C})
\]

\[
\iff G_{\bar{\varphi}}' \text{ has a } \pi\text{-cover of size } 2^l,
\]

where by the derivability in \( \mathcal{C}_S[\Gamma_{\varphi,\pi}] \) we understand the derivability in the corresponding \( \mathcal{C}_{\bar{\varphi}}\) calculus.

**Proof.** The proof of this lemma is very much like the proof of Theorem 29, but we still need to define the term \( t_{k-l} \). First, let \( t_{k-l} \) be the term \( \text{conj}(t_k + c_1 \cdot x, l) \). By almost exactly the same reasoning as in Lemma 21, for any set \( C \) of size \( 2^l \) with \( C \subseteq V_{\bar{\varphi}} \cup V_\pi \),

\[
\mathcal{C}_S[\Gamma_{\varphi,\pi}] \vdash t_{k-l}': (F_{V_{\bar{\varphi}}} \rightarrow F_{C}) .
\]

(26)

Indeed, by Lemma 18, \( \mathcal{C}_S[\Gamma_{\varphi,\pi}] \vdash t_k: (F_{V_{\bar{\varphi}}} \rightarrow L) \) for any sentence letter \( L \) that corresponds to a vertex from \( V_{\bar{\varphi}} \). It is easy to see that \( \mathcal{C}_S[\Gamma_{\varphi,\pi}] \vdash c_1: (F_{V_{\bar{\varphi}}} \rightarrow L) \) for any \( L \in V_\pi \) because \( \mathcal{C}_S[\Gamma_{\varphi,\pi}] \vdash c_1: (L \rightarrow (F_{V_{\bar{\varphi}}} \rightarrow L)) \). Thus, (26) follows by Lemma 19.

The converse is proved in a way similar to Lemma 25. In particular, by Lemma 19, \( \mathcal{C}_S[\Gamma_{\varphi,\pi}] \vdash t_{k-l}': H \) holds precisely for formulas \( H \) of the form \( B \rightarrow D \), where \( D \) is a balanced conjunction of depth \( \geq l \) such that for every \( l\)-conjunct \( C_i \) of \( D \) we have \( \mathcal{C}_S[\Gamma_{\varphi,\pi}] \vdash (t_k + c_1 \cdot x): (B \rightarrow C_i) \). By Lemma 18, the term \( t_k \) only justifies implications from a formula to its \( k\)-conjunct. Clearly, \( c_1 \cdot x \) only justifies implications \( Y \rightarrow L \) with \( L \in V_\pi \). Therefore,

all \( l\)-conjuncts of \( D \) that are not in \( V_\pi \) must be \( k\)-conjuncts of \( B \).

(27)

Note that \( |t_{k-l}'| = O(k2^l) \) as was \( |t_{k-l}| \).

Now define \( t_{k-l-m} \) to be the term \( \text{syl}(t_{k-l}, s_{l-m}) \). By exactly the same argument as in Theorem 24, using the same Lemmas 17 and 23, with (26) replacing the claim of Lemma 21, we have

\[
G_{\bar{\varphi}}' \text{ has a } \pi\text{-cover of size } \leq 2^l \leq |V_{\bar{\varphi}}| \implies \mathcal{C}_S[\Gamma_{\varphi,\pi}] \vdash t_{k-l-m}': (F_{V_{\bar{\varphi}}} \rightarrow F_{G_{\bar{\varphi}}'}) .
\]

Conversely, Theorem 28 holds for \( \mathcal{C}_S[\Gamma_{\varphi,\pi}] \) in place of \( \mathcal{C}_S \), except that now the set \( X \) can contain sentence letters \( L \in V_\pi \) in addition to \( k\)-conjuncts of \( B \). Indeed, Lemmas 17 and 27 hold for \( \mathcal{C}_S[\Gamma_{\varphi,\pi}] \). The claim of Lemma 25 is here replaced by (27), which allows elements of \( V_\pi \) in \( X \) along with \( k\)-conjuncts of \( B \).

Lemma 45 now follows by exactly the same argument as in the proof of Theorem 29.

This completes the proof of Theorem 44. 

\( \square \)
Theorem 46. Let $\mathcal{CS}$ be a schematically injective and axiomatically appropriate constant specification for a pure justification logic $\mathcal{JL} \in \{\text{J, JD, JT, J4, JD4, LP}\}$. Then the Derivability Problem for $\mathcal{JL}_{\mathcal{CS}}$ is $\Pi^p_2$-hard.

Proof. By Lemma 32, $\mathcal{JL}_{\mathcal{CS}}$ is fitting. Thus, by Theorem 44, $\mathcal{JL}_{\mathcal{CS}}$ is $\Pi^p_2$-hard. □

Theorem 47. Let $\mathcal{CS}$ be a schematically injective and axiomatically appropriate constant specification for a pure justification logic $\mathcal{JL} \in \{\text{J, JD, JT, J4, JD4, LP}\}$. Then the Derivability Problem for $\mathcal{JL}_{\mathcal{CS}}$ is $\Pi^p_2$-complete.

Proof. It was proved in [19, 21, 1] that $\mathcal{JL}_{\mathcal{CS}}$ is in $\Pi^p_2$. On the other hand, the $\Pi^p_2$-hardness follows from Theorem 46. □

The lower bound from Theorem 46 was first proved for $\mathcal{L}_{\mathcal{CS}}$ by Milnikel in [24]. A slightly stronger result can be found there for $\mathcal{J4}_{\mathcal{CS}}$: it is $\Pi^p_2$-hard for any schematic and axiomatically appropriate $\mathcal{CS}$. The results for the other four logics are new. By analogy with Milnikel’s result for $\mathcal{J4}_{\mathcal{CS}}$, we conjecture that the requirement of schematic injectivity in Theorem 46 for $\mathcal{J}_{\mathcal{CS}}$ can be relaxed to that of schematicness.

9. The Role of $\mathcal{CS}$

Our method for proving lower bounds for both justification logics and their reflected fragments as well as Milnikel’s original proof of the lower bound for $\mathcal{L}_{\mathcal{CS}}$ from [24] require $\mathcal{CS}$ to be axiomatically appropriate and schematically injective. A natural question arises: whether these two conditions on $\mathcal{CS}$ are essential for proving the lower bounds? In particular, is $\mathcal{L}$ itself $\Pi^p_2$-hard? Although we cannot answer the latter question, in this section we will try to explore the dependency of the lower bound on a constant specification.

It is clear that neither schematic injectivity nor axiomatic appropriateness are necessary for the lower bounds to hold. In particular,

Lemma 48. Let $\mathcal{JL} \in \{\text{J, JD, JT, J4, JD4, LP, T,L, S4, S5, LP}\}$. There exists a constant specification $\mathcal{CS}$ for $\mathcal{JL}$ that is neither schematically injective nor axiomatically appropriate such that $\mathcal{JL}_{\mathcal{CS}}$ is NP-hard. If $\mathcal{JL} \in \{\text{J, JD, JT, J4, JD4, LP}\}$, then, in addition, $\mathcal{JL}_{\mathcal{CS}}$ is $\Pi^p_2$-hard.

Proof. Let terms $c_1, c_2, c_{A1,A2}, c_A$, and $c_{\vee 1, \vee 2}$ from (1) be constants. Let all tautologies from the right sides of the five equivalencies in (1) be axioms from A1. Finally, let a constant specification $\mathcal{CS}$ be such that all five equivalencies from (1) hold while no other constant justifies any axioms at all. Then the reflected fragment $\mathcal{JL}_{\mathcal{CS}}$ is clearly fitting. Thus, by Theorem 30, $\mathcal{JL}_{\mathcal{CS}}$ is NP-hard. In addition, if $\mathcal{JL}$ is a pure justification logic, by Theorem 44, $\mathcal{JL}_{\mathcal{CS}}$ is $\Pi^p_2$-hard. At the same time, this $\mathcal{CS}$ is surely not axiomatically appropriate. It is not schematically injective either since constants $c_{A1,A2}$ and $c_{\vee 1, \vee 2}$ justify two axiom schemes each.

The constructed constant specification is schematic, but even the schematicness condition is easy to violate provided the constants $c_1, c_2, c_{A1,A2}, c_A$, and $c_{\vee 1, \vee 2}$ remain schematic. It should be noted that schematicness is often needed to prove the matching upper bound. □
The constant specification from the proof of the previous lemma also demonstrates another curious fact: the + operation does not play a big role in the lower bound on the complexity of the logic.

**Lemma 49.** Let \( JL \in \{ J, JD, JT, J4, JD4, LP, T_n, S4_n, S5_n, LP \} \). There exists a constant specification \( CS \) such that the + free reflected fragment of \( JL_{CS} \) is NP-hard.

**Proof.** Although + was used to construct terms \( c_{1,2} \) and \( c_{1,2} \) for schematically injective constant specifications, it is not required for the constant specification \( CS \) from the proof of Lemma 48. Nowhere else in our reduction was + used. Therefore, even if axiom A3 and rule *A3 are omitted from the axiomatizations of \( JL \) and of its reflected fragment respectively and the operation + is dropped from the language completely (see [15] for precise definitions) the resulting + free reflected fragment is still fitting and, hence, NP-hard. \( \square \)

However, the ability of one term to justify several axiom schemes does seem to be necessary for the proven lower bounds. This ability can be ensured already on the level of constants, without the use of +. However, if the lack of + is coupled with the schematic injectivity of a constant specification, then all terms effectively become schematically injective and the reflected fragment is polynomially decidable, which can be shown by analyzing N. Krupski’s algorithm from [18].

The preceding discussion shows that the lower bounds are, in some sense, local. Namely, they can be ensured by finitely many constants using only a small portion of propositional reasoning. In fact, the proof of the existence of undecidable \( LP_{CS} \) from [20] has a similar flavor: only a few constants are sufficient to make the logic undecidable. For instance, it is possible that \( JL_{CS} \) can be shown to be \( \Pi_2^p \)-hard using one part of the constant specification \( CS \) and to be undecidable using another part. Therefore, the requirements of schemativeness and/or schematic injectivity can be relaxed to apply only to a small subset of justification constants.

Since axiomatic appropriateness is also a local property, it becomes clear that it is independent of whether the reflected fragment is fitting. In particular, Lemma 48 can be easily reformulated for an axiomatically appropriate but not schematically injective constant specification. The only change in the proof would be an addition of a sixth constant that proves all the axioms.

However little of internalization is used in the proof of our lower bounds, it cannot be dispensed of completely:

**Lemma 50.** Let \( JL \in \{ J, JD, JT, J4, JD4, LP, T_n, S4_n, S5_n, LP \} \). There exists a schematically injective but not axiomatically appropriate constant specification \( CS \) for \( JL \) such that \( rJL_{CS} \) is in P. If \( JL \in \{ J, JD, JT, J4, LP \} \), then, in addition, \( JL_{CS} \) is in co-NP.

**Proof.** It has been known that \( LP_0 \) with the empty constant specification \( CS = \emptyset \) is in co-NP. Its reflected fragment is trivially in P since it is empty. Extending these results to other justification logics is straightforward. \( \square \)

The preceding lemma can also be proved using a non-empty schematically injective constant specification, but the proof is much more involved.
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