

First HW is posted on Tritoned, due next Thursday

X, Y discrete

$P_{X|Y}(\cdot | y)$ conditional p.m.f. of X

given $Y = y$,

$$P_{X|Y}(x_i | y) = \frac{P_{X,Y}(x_i, y)}{P_Y(y)}$$
$$= P(X = x_i | Y = y)$$

provided $P(Y = y) > 0$.

Example: a dice game

1, 2, ..., 6

sum 2, 3, 4, ..., 12

1, 2, ..., 6

In a game, two dice are rolled and the sum of the two is observed.

$$4 = 1 + 3 = 2 + 2 = 3 + 1$$

$$\frac{3}{6 \times 6}$$

$$7 = 1 + 6 = 2 + 5 = 3 + 4$$

$$\frac{6}{36}$$

If the sum is 4, the player loses. If the sum is 7 the player wins.

Otherwise the game continues: the dice are rolled repeatedly until either a sum of 4 or 7 is observed.

Let X be the Bernoulli random variable that $X=1$ if in the end the player wins and $X=0$ if the player loses.

$X=1$ if 7 is observed in the end

$X=0$ if 4 is

Let N be the number of rolls until the end of the game.

$N = \#$ rolls until we see 7 or 4.

What is the conditional distribution of X given $N=k$?

$$N \sim \text{Geometric}(p), \quad p = P(\text{Sum} = 4) + P(\text{Sum} = 7) \\ = \frac{3}{36} + \frac{6}{36} = \frac{3+6}{36} = \frac{1}{4}.$$

$$P_{X|N}(\cdot | k)$$

$$P_{X|N}(0 | k) = \frac{P(X=0, N=k)}{P(N=k)}$$

$$= \frac{P(\text{the first } k-1 \text{ rolls} \notin \{4, 7\} \text{ and } k\text{-th roll is } 4)}{P(\text{the first } k-1 \text{ rolls} \notin \{4, 7\} \text{ and } k\text{-th roll} \in \{4, 7\})}$$

$$= \frac{(1-p)^{k-1} \cdot \left(\frac{3}{36}\right)}{(1-p)^{k-1} \cdot \left(\frac{3}{36} + \frac{6}{36}\right)} = \frac{1}{3}$$

$$P_{X|N}(1 | k) = \frac{2}{3} \quad \text{by similar calculation.}$$

Recall X, Y discrete R.V.s,

X and Y are independent iff

$$P_{X,Y}(x,y) = P_X(x) P_Y(y), \quad \text{for any } x,y$$

Write it into conditioning form

if $P_Y(y) > 0$,

$$P_{X|Y}(x|y) = P_X(x)$$

That is X and Y are independent if and only if

for any y $P(Y=y) > 0$, we have

$$P_{X|Y}(\cdot|y) = P_X.$$

In the example above,
 X and N are independent

Conditional expectation

$X: \Omega \rightarrow \{x_1, x_2, \dots\}$ \mathbb{P}_X p.m.f.

$$\mathbb{E}(X) = \sum_i x_i \mathbb{P}(X = x_i) = \sum_i x_i \mathbb{P}_X(x_i).$$

- X, Y discrete random variables.
- The **conditional expectation of X given $\{Y = y\}$** is defined as

$$\mathbb{E}(X | Y = y) = \sum_{x_i} x_i \mathbb{P}_{X|Y}(x_i | y)$$

provided that $\mathbb{P}(Y = y) > 0$.

Condition on $Y = y$, we have conditional p.m.f.
 $\mathbb{P}_{X|Y}(\cdot | y)$

Recall: $\mathbb{E}[g(X)] = \sum_i g(x_i) P_X(x_i).$

- In the same way as for expectation $E(X)$, we can compose the random variable X with a function $g : \mathbb{R} \rightarrow \mathbb{R}$, and the conditional expectation of $g(X)$ given $Y = y$ is

$$\mathbb{E}(g(X) | Y = y) = \sum_{x_i} g(x_i) \mathbb{P}_{X|Y}(x_i | y).$$

take $P_{X|Y}(\cdot | y)$

then we can compute $\mathbb{E}[g(X) | Y = y]$

$$= \sum_i g(x_i) P_{X|Y}(x_i | y).$$

Example

Let N be a random variable taking value in $\{0, 1, 2, \dots\}$.

Let ξ_1, ξ_2, \dots be a sequence of i.i.d. random variables with mean \underline{m} , independent of N .

Let $X = \xi_1 + \dots + \xi_N$. (a random sum)

The conditional expectation of X given $N=n$ is

$$E[X | N=n] = n \cdot E[\xi_1] = n \cdot m.$$

The conditional distribution of X given $N=n$ is the same as $\xi_1 + \xi_2 + \dots + \xi_n$.

$$\mathbb{E}[X | N=n] = \mathbb{E}[\xi_1 + \dots + \xi_n] \stackrel{\text{linearity}}{=} \mathbb{E}[\xi_1] + \dots + \mathbb{E}[\xi_n] \stackrel{\text{i.i.d.}}{=} n \cdot m.$$

Properties of conditional expectation

- (similar to the law of total probability, a special case of the so called “tower property” of conditional expectation)

$$\mathbb{E}(g(X)) = \sum_{y_i} \mathbb{E}(g(X) | Y = y_i) \mathbb{P}(Y = y_i) \quad \textcircled{1}$$

This identity is usually written in a more compact form as

$$\mathbb{E}(g(X)) = \mathbb{E}(\mathbb{E}(g(X) | Y)).$$

Why $\textcircled{1}$ is true:

$$\mathbb{E}[g(X)] = \sum_{x_i} g(x_i) \mathbb{P}(X = x_i)$$

$$\begin{aligned}
&= \sum_{x_i} g(x_i) \left(\sum_{y_j} P(X=x_i | Y=y_j) P(Y=y_j) \right) \\
&= \sum_{y_j} \left(\sum_{x_i} g(x_i) P(X=x_i | Y=y_j) \right) P(Y=y_j) \\
&= \sum_{y_j} E[g(X) | Y=y_j] P(Y=y_j).
\end{aligned}$$

We can understand

$E[g(X) | Y]$ as a Random Variable :

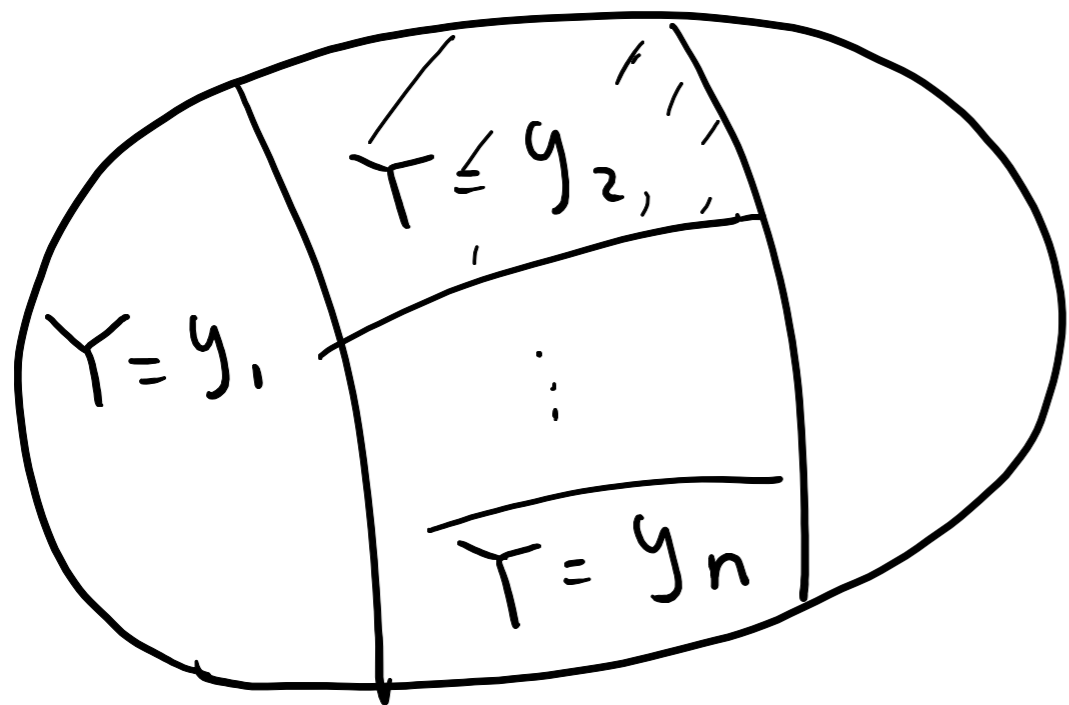
Ω

sample space

$$X: \Omega \rightarrow \mathbb{R}$$

$$Y: \Omega \rightarrow \mathbb{R}$$

Y takes value in $\{y_1, y_2, \dots\}$



the events $\{Y = y_i\}$ form
a partition of Ω

and we know what

$$\mathbb{E}[g(X) | Y = y_i] \text{ means.}$$

The R.V. $\mathbb{E}[g(X) | Y]: \Omega \rightarrow \mathbb{R}$ is

defined as $(\mathbb{E}[g(X) | Y])(\omega) = \mathbb{E}[g(X) | Y = Y(\omega)]$

That is, the R.V. $\mathbb{E}[g(x)|Y]$ respects the

partition

$$\Omega = \bigcup_j \{Y = y_j\},$$

and on the piece $\{Y = y_j\}$, it takes

value $\mathbb{E}[g(x)|Y = y_j]$.

Exercise: check that for the R.V. $\mathbb{E}[g(x)|Y]$

defined above,

$$\mathbb{E}[\mathbb{E}[g(x)|Y]] = \mathbb{E}[g(x)].$$

Solution to Exercise above (think about it yourself first, it's just about seeing definitions right)

Formally, let's define a function

$f: \{y_1, y_2, \dots\} \rightarrow \mathbb{R}$ by setting

$$f(y_i) = \mathbb{E}[g(X) | Y = y_i] \quad \text{if } P(Y = y_i) > 0.$$

Then $\mathbb{E}[g(X) | Y] = f(Y)$ by definition.

$$\text{Now } \mathbb{E}[f(Y)] = \sum_j f(y_j) P(Y = y_j)$$

$$= \sum_j \mathbb{E}[g(X) | Y = y_j] P(Y = y_j)$$

$$= \mathbb{E}[g(X)] \quad \text{by formula (i).}$$