

Today: § 4.2-4.3: Bases of  $\text{Col}(A)$ ,  $\text{Nul}(A)$

& § 4.5-4.6: Dimension & Rank

Next: § 4.4 & 4.7: Change of Basis

Homework:

MyMathLab Homework #4: Due Tuesday ~~TONIGHT~~ by 11:59pm

MyMathLab Homework #5: Due Feb 20 by 11:59pm

A **basis** of a subspace  $H$  is a collection of vectors

$$\{v_1, v_2, \dots, v_n\} \subset H$$

that (1) spans  $H$ , and

(2) is linearly independent.

Subspaces are frequently presented as the span of some collection of vectors; but those vectors may not be independent. How do we find a basis?

$$H = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \right\}$$

Corollary: If  $H = \text{span}\{\underline{v}_1, \dots, \underline{v}_n\}$ , then some collection of these vectors is a basis for  $H$ .

$$\text{E.g. } H = \text{span}\left\{\begin{bmatrix} -3 \\ 1 \\ 2 \end{bmatrix}, \begin{bmatrix} 6 \\ -2 \\ -4 \end{bmatrix}, \begin{bmatrix} -1 \\ 2 \\ 5 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 8 \end{bmatrix}, \begin{bmatrix} -7 \\ -1 \\ -4 \end{bmatrix}\right\}$$

$$A = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & -2 & 0 & -1 & 3 \\ 0 & 0 & 1 & 2 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$


**Theorem:** The pivotal columns of  $A$  form a basis for  $\text{Col}(A)$ . (The coefficients expressing the non-pivotal columns in terms of this basis can be read off of  $\text{rref}(A)$ .)

Eg. 
$$\begin{bmatrix} 1 & 3 & 2 \\ 0 & -1 & -1 \\ 2 & 1 & -1 \end{bmatrix}$$

**Caution:** The pivotal columns of  $A$ , **not**  $\text{rref}(A)$ , form a basis for  $\text{Col}(A)$ . Typically  $\text{Col}(A) \neq \text{Col}(\text{rref}(A))$ .

How about  $\text{Nul}(A)$ ? How do I find a basis?

$$A = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & -2 & 0 & -1 & 3 \\ 0 & 0 & 1 & 2 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Theorem: This  procedure for identifying  $\text{Nul}(A)$  always produces a basis for it.

A given subspace always has zillions of bases. But there is one thing in common among all bases.

Theorem: Any two bases of a vector space have the same number of vectors.

Pf.

Definition: If  $V$  is a vector space, its **dimension** is the number of vectors in any basis.

E.g.  $V = \text{span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}, \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ -1 \\ -1 \end{bmatrix} \right\}$

We saw that the matrix  $A = \begin{bmatrix} 1 & 3 & 2 \\ 0 & -1 & -1 \\ 2 & 1 & -1 \end{bmatrix}$  has 2 pivot columns.  $V = \text{Col}(A)$ , so

$$\dim(V) =$$

E.g.  $\mathbb{P}_3 = \{\text{polynomials of degree} \leq 3\}$

E.g.  $\mathbb{P} = \{\text{polynomials}\}$

Theorem: If  $\{\underline{v}_1, \dots, \underline{v}_n\}$  is linearly independent, it can be extended to form a basis:

$$\{\underline{v}_1, \dots, \underline{v}_n, \underline{u}_1, \dots, \underline{u}_p\}.$$

If  $\{\underline{w}_1, \dots, \underline{w}_n\}$  is a spanning set, it can be reduced to form a basis.

Corollary: If  $H$  is a subspace of  $V$ , then

$$\dim(H) \leq \dim(V).$$



Definition: Given a matrix  $A$ ,

$$\text{rank}(A) := \dim(\text{Col}(A))$$

$$\text{nullity}(A) := \dim(\text{Nul}(A)).$$

$$A = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & -2 & 0 & -1 & 3 \\ 0 & 0 & 1 & 2 & -2 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Rank Theorem: If  $A$  is an  $m \times n$  matrix,

$$\text{rank}(A) + \text{nullity}(A) = n$$

(= #Columns of  $A$ )