

Today: § 4.4: Coordinates

& § 3.1-3.2: Determinants

Next: § 3.2-3.3: Determinants & Volume

Reminders:

MyMathLab Homework #5: Due Tuesday by 11:59pm

MATLAB Assignment #4: Due February 23 by 11:59pm

Midterm #2: Feb 28, 8-10pm

Reminder: If  $V$  is a vector space and  $\mathcal{B} = \{\underline{b}_1, \underline{b}_2, \dots, \underline{b}_n\}$  is a basis for  $V$ , the **coordinate vector**  $[\underline{v}]_{\mathcal{B}}$  of any vector  $\underline{v} \in V$  is the column of coefficients in the unique expansion of  $\underline{v}$  in the basis  $\mathcal{B}$ :

$$\underline{v} = x_1 \underline{b}_1 + x_2 \underline{b}_2 + \dots + x_n \underline{b}_n \rightsquigarrow [\underline{v}]_{\mathcal{B}} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

Theorem: If  $\mathcal{B} = \{\underline{b}_1, \underline{b}_2, \dots, \underline{b}_n\}$  is a basis for  $V$ , then the function  $T: V \rightarrow \mathbb{R}^n: T(\underline{v}) = [\underline{v}]_{\mathcal{B}}$  is a one-to-one linear transformation from  $V$  onto  $\mathbb{R}^n$ .

Such a linear transformation is called an

E.g.  $A = \begin{bmatrix} 1 & 3 & 5 \\ 0 & 1 & 1 \\ 1 & 0 & 2 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \left\{ \right\} = \mathcal{B}$  basis for  $\text{Col}(A)$ .

The point of isomorphisms is: they preserve all linear properties.

Theorem: Let  $\{\underline{b}_1, \underline{b}_2, \dots, \underline{b}_n\} = \mathcal{B}$  be a basis for  $V$ .

Then \*  $\{\underline{v}_1, \dots, \underline{v}_k\} \in V$  are linearly independent in  $V$   
iff  $[\underline{v}_1]_{\mathcal{B}}, \dots, [\underline{v}_k]_{\mathcal{B}}$  are linearly independent in  $\mathbb{R}^n$ .

\* " " ——— span ———  $V$   
" " ——— span ———  $\mathbb{R}^n$ .

Eg. Show that  $\{1, x-1, (x-1)^2\}$  is a basis for  $\mathbb{P}_2$ .

## § 3.1 Determinants

If  $A$  is a  $2 \times 2$  matrix  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ , when doing row reduction, we find that the columns are both pivotal unless  $\underbrace{ad - bc = 0}$ .

This is the **determinant** of  $A$ , denoted  $\det A = |A|$ .

Theorem:  $A$  is invertible iff  
in which case  $A^{-1} =$

For any  $n \times n$  matrix  $A$ , there is a quantity  $\det A$  which

\* is a polynomial function of the entries of  $A$

\* determines whether  $A$  is invertible.

The  $2 \times 2$  case has a simple formula; for larger matrices, it is more complicated.

The generalization of the  $2 \times 2$  case is the cofactor expansion.

Eg.  $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix} \begin{bmatrix} + & - & + \\ - & + & - \\ + & - & + \end{bmatrix}$

# Cofactor Expansion

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{bmatrix}$$

$$\begin{aligned} \det A &= a_{j1}C_{j1} + a_{j2}C_{j2} + \dots + a_{jn}C_{jn} \\ &= a_{1j}C_{1j} + a_{2j}C_{2j} + \dots + a_{nj}C_{nj} \end{aligned}$$

for any row  
or column  $j$ .

Eg.  $\begin{bmatrix} 1 & 5 & 0 \\ 2 & 4 & -1 \\ 0 & -2 & 0 \end{bmatrix}$

E.g.

$$A = \begin{bmatrix} 3 & 7 & 8 & 9 & -6 \\ 0 & 2 & -5 & 7 & 3 \\ 0 & 0 & 1 & 5 & 0 \\ 0 & 0 & 2 & 4 & -1 \\ 0 & 0 & 0 & -2 & 0 \end{bmatrix}$$

Theorem: If  $A$  is triangular  $\det A$  is the product of the diagonal entries.



## § 3.2: Determinants & Row Operations

$$* A \xrightarrow{R_i \rightarrow R_i/p} \tilde{A} :$$

$$* A \xrightarrow{R_i \leftrightarrow R_j} \tilde{\tilde{A}} :$$

$$* A \xrightarrow{R_i \rightarrow aR_i + R_i} \tilde{\tilde{\tilde{A}}} :$$

Theorem: If  $A$  is  $n \times n$  and has full rank  
(ie.  $\text{rank } A = n$  ie.  $A$  is invertible)  
then  $\det A = \pm$  product of the pivots  
in row reduction.

If  $\text{rank } A < n$ ,  $\det A = 0 \dots$

Eg.

$$\begin{bmatrix} 0 & 1 & 4 \\ 1 & 2 & -1 \\ 5 & 8 & 0 \end{bmatrix}$$