

MATH180C: Introduction to Stochastic Processes II

[Lecture A00: math-old.ucsd.edu/~ynemish/teaching/180cA](http://math-old.ucsd.edu/~ynemish/teaching/180cA)

[Lecture B00: math-old.ucsd.edu/~ynemish/teaching/180cB](http://math-old.ucsd.edu/~ynemish/teaching/180cB)

Today: MC review. Conditioning on
continuous random variables

Next: PK 7.1, Durrett 3.1

Week 4:

- homework 3 (due Saturday, April 23)
- Midterm 1: **Friday, April 22**

Example: Birth and death processes

If we consider the birth and death process, the equation $\pi Q = 0$

takes the following form

$$-\pi_0 \lambda_0 + \pi_1 \mu_1 = 0$$

$$\pi_0 \lambda_0 - \pi_1 (\lambda_1 + \mu_1) + \pi_2 \mu_2 = 0$$

\vdots

$$\pi_{i-1} \lambda_{i-1} - \pi_i (\lambda_i + \mu_i) + \pi_{i+1} \mu_{i+1} = 0$$

where $\theta_i = \frac{\lambda_{i-1}}{\mu_i} \cdot \frac{\lambda_{i-2}}{\mu_{i-1}} \cdots \frac{\lambda_0}{\mu_1}$, $\theta_0 = 1$.

Then, $\sum_{i=0}^{\infty} \pi_i = 1$ implies that $\pi_0 \sum_{i=0}^{\infty} \theta_i = 1$

If $\sum_{i=0}^{\infty} \theta_i < \infty$, then (X_t) is positive recurrent and $\pi_j = \frac{\theta_j}{\sum_{i=0}^{\infty} \theta_i}$

If $\sum_{i=0}^{\infty} \theta_i = \infty$, then $\pi_j = 0 \forall j$.

$$Q = \begin{pmatrix} -\lambda_0 & \lambda_0 & & \\ \mu_1 & -(\lambda_1 + \mu_1) & \lambda_1 & \\ & \mu_2 & -(\lambda_2 + \mu_2) & \lambda_2 \\ & & & \ddots \end{pmatrix} = q_{01}$$

$$\pi_1 = \frac{\lambda_0}{\mu_1} \pi_0$$

$$\Rightarrow \pi_2 = \frac{\lambda_1}{\mu_2} \pi_1 = \frac{\lambda_1 \lambda_0}{\mu_2 \mu_1} \pi_0$$

$$\pi_{i+1} = \frac{\lambda_i}{\mu_{i+1}} \pi_i = \cdots = \underbrace{\frac{\lambda_i \cdots \lambda_0}{\mu_{i+1} \cdots \mu_1}}_{\theta_{i+1}} \pi_0$$

Example. Linear growth with immigration

Birth and death process, $\lambda_j = \lambda_j + a$, $\mu_j = \mu_j$ (*)

Using Kolmogorov's equations we showed (lecture 5)

that $E(X_t) \rightarrow \frac{a}{\mu - \lambda}$, $t \rightarrow \infty$, if $\mu > \lambda$.

What is the limiting distribution of X_t ?

From the previous slide, $\pi_j = \frac{\theta_j}{\sum_{i=0}^{\infty} \theta_i}$, $\theta_j = \frac{\lambda_{j-1} \cdots \lambda_0}{\mu_j \cdots \mu_1}$

If we replace λ_j, μ_j by (*), we get

$$\pi_j = \left(\frac{\lambda}{\mu}\right)^j \left(1 - \frac{\lambda}{\mu}\right)^a \frac{\frac{a}{\lambda} \left(\frac{a}{\lambda} + 1\right) \cdots \left(\frac{a}{\lambda} + j - 1\right)}{j!}, \quad j > 1$$

$$\pi_0 = \left(1 - \frac{\lambda}{\mu}\right)^{\frac{a}{\lambda}}$$

What you should know for midterm 1 (minimum):

- definition of continuous time MC, Markov property, transition probabilities, generator
- representations of MC: infinitesimal (generator), jump-and-hold, transition probabilities, rate diagram and relations between them (in particular Q and $P(t)$)
- computing absorption probabilities and mean time to absorption
- computing stationary distributions for finite and infinite state MCs and interpretation of $(\pi_i)_{i=0}^{\infty}$
- basic properties of birth and death processes

Conditioning on continuous r.v.

Def. Let X and Y be jointly distributed continuous random variables with joint probability density function $f_{X,Y}(x,y)$. We call the function

$$f_{X|Y}(x|y) := \frac{f_{X,Y}(x,y)}{f_Y(y)} \quad \text{for } f_Y(y) > 0$$

the **conditional probability density function** of X given $Y=y$.

The function $F_{X|Y}(x|y) = \int_{-\infty}^x f_{X|Y}(s|y) ds$

is called **conditional CDF** of X given $Y=y$

Conditional expectation

Def. Let X and Y be jointly distributed continuous random variables, let $f_{X|Y}(x|y)$ be a conditional distribution of X given $Y=y$ and let $g: \mathbb{R} \rightarrow \mathbb{R}$ be a function for which $E(|g(X)|) < \infty$.

Then we call

$$E(g(X) | Y=y) := \int_{-\infty}^{+\infty} g(x) f_{X|Y}(x|y) dx \quad \text{if } f_Y(y) > 0$$

the **conditional expectation** of $g(X)$ given $Y=y$.

In particular, if $g(x) = \mathbb{1}_A(x)$ indicator of set A , then

$$E(\mathbb{1}_A(X) | Y=y) = P(X \in A | Y=y) = \int_A f_{X|Y}(x|y) dx$$

Remark

If Y is a continuous random variable, then

$$P(Y=y) = 0 \text{ for all } y \in \mathbb{R}$$

Therefore, we cannot define $P(X \in A | Y=y)$ as

$$P(X \in A | Y=y) = \frac{P(X \in A, Y=y)}{P(Y=y)}$$

On the other hand consider example:

$$X, Y \text{ i.i.d. } X, Y \sim \text{Unif}[0,1], \quad Z = X - Y$$

$$\text{If } Y = \frac{1}{2}, \quad Z = X - \frac{1}{2} \sim \text{Unif}\left[-\frac{1}{2}, \frac{1}{2}\right]$$

makes perfect sense

Intuitive explanation / derivation

$$P(X \in [x, x+\Delta x], Y \in [y, y+\Delta y]) \\ = f_{X,Y}(x,y) \Delta x \Delta y + o(\Delta x \cdot \Delta y)$$

Using the multiplication rule ($f_Y(y) > 0$ on $[y, y+\Delta y]$)

$$P(X \in [x, x+\Delta x], Y \in [y, y+\Delta y]) \\ = P(X \in [x, x+\Delta x] | Y \in [y, y+\Delta y]) P(Y \in [y, y+\Delta y])$$

$$\frac{P(X \in [x, x+\Delta x] | Y \in [y, y+\Delta y])}{\Delta x} = \frac{P(X \in [x, x+\Delta x], Y \in [y, y+\Delta y])}{\underbrace{P(Y \in [y, y+\Delta y])}_{\Delta y} \Delta x}$$

$\downarrow \Delta x \rightarrow 0$

$$"f_X(x | Y \in [y, y+\Delta y])"$$

$\downarrow \Delta y \rightarrow 0$

$$"f_X(x | Y=y)" = f_{X|Y}(x|y)$$

Δy

$\downarrow \begin{matrix} \Delta x \rightarrow 0 \\ \Delta y \rightarrow 0 \end{matrix}$

$$\frac{f_{X,Y}(x,y)}{f_Y(y)}$$