

~~$$\text{exp}_p(v) = \gamma_v(\sqrt{a^2 + b^2})$$~~

~~$$\gamma_v = \begin{pmatrix} a \cos t \\ b \sin t \end{pmatrix}$$~~

Def: An abstract surface is a set  $S$  with a collection of coordinate charts such that:

(a coordinate chart is a 1-to-1 map from a domain in  $\mathbb{R}^2$  to  $S$ )

1)  $S =$  union of the images of the coordinate charts.

2)  $\forall$  choice of two charts

$$\varphi_1: D_1 \hookrightarrow S \quad \varphi_2: D_2 \hookrightarrow S$$

~~W.A. #111~~  $\varphi_1^{-1}(\text{image}(D_1) \cap \text{image}(D_2))$  is open in  $\mathbb{R}^2$ .

and  $\boxed{\varphi_2^{-1} \varphi_1}$  is smooth from  $D_1$  to  $D_2$   
 in fact from  $\varphi_1^{-1}(\text{image}(D_1) \cap \text{image}(D_2))$   
 to  $\varphi_2^{-1}(\text{image}(D_1) \cap \text{image}(D_2))$

3) (Hausdorff axiom).  $\forall p \neq q \in S$   
 $\exists$  coordinate charts  $\varphi_1, \varphi_2$  s.t.

$p \in \text{Im } \varphi_1, p \notin \text{Im } \varphi_2.$

$q \notin \text{Im } \varphi_1, q \in \text{Im } \varphi_2$

$$\text{Im } \varphi_1 \cap \text{Im } \varphi_2 = \emptyset$$

Remark: Can define a topology on  $S$ :

open sets = unions of images of open sets from domains of charts.

---

We want a way of measuring distance on  $S$ . We compute lengths of curves by integrating the lengths of their velocity vectors.

---

Given a chart  $\varphi: D \rightarrow S$ , the tangent plane to  $S$  at  $p$  is  $T_{\varphi^{-1}(p)} D = T_p S$  or velocity vectors of curves in  $S$ .

---

We need to compute lengths of tangent vectors to  $S$ .

---

When  $S \subset \mathbb{R}^3$ ,  $|v| = \sqrt{v \cdot v}$ .

We define metrics on abstract surfaces via inner products.

Def: An inner product on  $\mathbb{R}^2$  is a map  $\mathbb{R}^2 \times \mathbb{R}^2 \rightarrow \mathbb{R}$   
 $(v, w) \mapsto \langle v, w \rangle$

s.t.

- 1)  $\langle , \rangle$  is bilinear (linear in  $v$  and in  $w$ )
- 2)  $\langle , \rangle$  is symmetric, i.e.,:  
 $\langle v, w \rangle = \langle w, v \rangle \quad \forall v, w \in \mathbb{R}^2$
- 3)  $\forall v \neq 0 \quad \langle v, v \rangle \geq 0$   
and  $\langle v, v \rangle = 0 \iff v = 0$ .

Remark: If symmetry fails, define

$$\langle v, w \rangle_2 = \langle v, w \rangle + \langle w, v \rangle.$$

Def: Given an inner product, we can define a length or norm on  $\mathbb{R}^2$  via  $\|v\| := \sqrt{\langle v, v \rangle}$ .

Def: given  $v, w \in \mathbb{R}^2 \setminus \{0\}$ .

can define the angle between  $v$  &  $w$

$$\text{as } \arccos \left( \frac{\langle v, w \rangle}{\|v\| \|w\|} \right)$$

This is well-defined because we have

Lemma: (Schwarz' inequality):

$$|\langle v, w \rangle| \leq \|v\| \|w\|$$

Proof:  $0 \leq \langle v + tw, v + tw \rangle$

$$= \langle v, v \rangle + \langle v, tw \rangle + \langle tw, v \rangle + \langle tw, tw \rangle$$

$$= \underbrace{\langle v, v \rangle}_{\in \mathbb{R}} + 2t \underbrace{\langle v, w \rangle}_{\in \mathbb{R}} + t^2 \underbrace{\langle w, w \rangle}_{\in \mathbb{R}}$$

degree 2 polynomial is always  $\geq 0$

$\Leftrightarrow$  at most one real root.

$\Leftrightarrow$  discriminant  $\leq 0$ .

$$\Leftrightarrow \langle v, w \rangle^2 - \langle w, w \rangle \langle v, v \rangle \leq 0$$

$$\Leftrightarrow |\langle v, w \rangle| \leq \|v\| \|w\| \quad \square$$

Fact: The datum of an inner product  
 $\Leftrightarrow$  the datum of a symmetric  
invertible  $2 \times 2$  matrix with positive  
eigenvalues.

---

Given  $\langle \cdot, \cdot \rangle$  on  $\mathbb{R}^2$   $e_1 = (1, 0)$ ,  $e_2 = (0, 1)$   
define the matrix  $A = (a_{ij})$ .

$$a_{ij} = \langle e_i, e_j \rangle \quad e_1 = (1, 0), \quad e_2 = (0, 1)$$

Given  $v = (x_1, y_1)$   $w = (x_2, y_2)$

$$\begin{aligned} \langle v, w \rangle &= \langle x_1 e_1 + y_1 e_2, x_2 e_1 + y_2 e_2 \rangle \\ &= x_1 x_2 a_{11} + x_1 y_2 a_{12} + x_2 y_1 a_{21} \\ &\quad + x_2 y_2 a_{22} \end{aligned}$$

$$= (x_1 \ y_1) \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} x_2 \\ y_2 \end{pmatrix}$$

$$= {}^t v A w$$

---

We use a family of inner products to  
define a metric on an abstract surface.

Definition: Given an abstract surface  $S$ , a vector field  $V$  on  $S$  is the datum for each  $p \in S$  of a vector  $V(p) \in T_p S$ .

We say  $V$  is smooth if  $V$  varies smoothly with  $p$ . This means  $\forall$

coordinate chart  $\varphi: D \rightarrow S$

~~$V(p) = V(\varphi(p))$  is a smooth function  $\rightarrow (f(\varphi(p)), g(\varphi(p)))$~~

$p \in \text{Im } \varphi$ .

$T_{\varphi^{-1}(p)} D \ni W(\varphi^{-1}(p)) = V(p) \in T_p S$

$\stackrel{\varphi^{-1}(p)}{\parallel}$   
 $\mathbb{R}^2$

$\varphi^{-1}(p) = (x, y)$ .

$W(x, y) = (f(x, y), g(x, y))$

$f, g \in C^\infty$ .

Def: Given an abstract surface  $S$ , a metric on  $S$  is the data, for all  $p \in S$  of an inner product  $\langle \cdot, \cdot \rangle_p$ .

$$\text{on } T_p S \cong \mathbb{R}^2$$

which varies smoothly with  $p$ .

This means  $\forall$  vector fields  $v, w$  on  $S$

$\langle v(p), w(p) \rangle_p$  is a  $C^\infty$  function

$\langle \cdot, \cdot \rangle_p = g(p)$  is called the metric tensor.

Def: A geometric surface is an abstract surface with a metric.

Construction method 1: conformal change.

One way of defining a new metric on a domain  $D \subset \mathbb{R}^2$  is by rescaling the length of vectors.

Euclidean

Given a  $C^\infty$  function  $h$  on  $D$

s.t.  $h(p) > 0 \quad \forall p \in D$ , define

$$\langle v, w \rangle_{h,p} = \frac{v \cdot w}{h^2(p)} \quad v, w \in T_p D$$

This is called a conformal metric,  
 $h$  is the scaling factor or ruler  
 function.

Example ① The Poincaré plane  $P$ :

$$h(x, y) = y$$

$P =$  the upper half plane  $y > 0$

with metric

$$\langle v, w \rangle_{(x, y)} = \frac{v \cdot w}{y^2}$$

$$\varphi: D = P \longrightarrow P$$

Identity.

$$\varphi_x = (1, 0)$$

$$\varphi_y = (0, 1)$$

$$E = \varphi_x \cdot \varphi_x = \langle \varphi_x, \varphi_x \rangle_{(x, y)} = \frac{1}{y^2}$$

$$F = \varphi_x \cdot \varphi_y = \langle \varphi_x, \varphi_y \rangle_{(x, y)} = 0$$

$$G = \frac{1}{y^2} \quad \rightarrow \quad A = \begin{pmatrix} \frac{1}{y^2} & 0 \\ 0 & \frac{1}{y^2} \end{pmatrix}$$

Example ② The Poincaré disk model  
 of the hyperbolic plane.



$H =$  open disk of radius 2.

$$\langle v, w \rangle_p = \frac{v \cdot w}{\left(1 - \frac{x^2 + y^2}{4}\right)^2}$$

$p = (x, y)$

$$h(x, y) = 1 - \frac{x^2 + y^2}{4} > 0$$

Construction method 2: pull-back.

Suppose  $N$  is a geometric surface and  $F: M \rightarrow N$  is smooth and regular ( $M$  an abstract surface).

(regular means  $F_*: T_p M \rightarrow T_{F(p)} N$  is a linear isom.  $\forall p$ )

If  $\langle \cdot, \cdot \rangle_N$  is the metric on  $N$ ,

define  $\langle \cdot, \cdot \rangle_M$  via

$$\langle v, w \rangle_M := \langle F_* v, F_* w \rangle_N.$$

Example: The stereographic sphere:

$S^2$  unit sphere in  $\mathbb{R}^3$   $N = (0, 0, 1)$

$$S_N^2 := S^2 \setminus \{N\}$$

St:  $S^2_N \longrightarrow \mathbb{R}^2 = x, y \text{ plane.}$

$\uparrow \longmapsto$  point of intersection of  
of the  $x, y$  plane with  
the line through  $p$  &  $N$ .